



Investigating transport of particulate matter from cooking emissions in a multi-story house using low-cost sensor measurements and different modeling approaches

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ABSTRACT

This work investigates the transport of fine particulate matter (PM_{2.5}) in a multi-story test house using cooking emissions as a point source. The test house was instrumented with 13 PM_{2.5} monitors, and the particle sources included pan cooking and air frying, as well as ambient PM_{2.5} penetration during periods of no indoor activity. In the absence of indoor sources, we observed about 10 % of ambient PM_{2.5} concentrations penetrating indoors with a time lag of ≈ 1 h. Similar peak PM_{2.5} concentrations were observed for pan frying and air frying of the same food ingredients. A cross-correlation analysis showed that it took 2–4 min for kitchen peak concentrations to reach other sensors on the first floor and about 8 min to reach the second floor. PM_{2.5} concentrations were heterogeneous on the first floor, with non-kitchen areas peaking at $45\% \pm 9\%$ of kitchen levels. Second-floor concentrations were more homogeneous, peaking at $18\% \pm 2\%$ of kitchen levels. Using a typical occupancy scenario, the highest estimated personal PM_{2.5} exposure (44 %) was experienced in the kitchen/dining area, which accounted for 9 % of the time spent at home. We used three modeling approaches to analyze particle transport throughout the house, with increasing input requirements: a multi-box model, an empirical model, and the NIST CONTAM model. All models predicted time integrated PM_{2.5} concentrations on the 1st and 2nd floors, with R^2 between 0.57 and 0.82 and RMSE from $6 \mu\text{g m}^{-3}$ to $11 \mu\text{g m}^{-3}$.

1. Introduction

Airborne pollutants enter the indoor environment from two major sources: (1) outdoor air entry and (2) emissions from indoor processes and activities. In efforts to become more energy efficient, building envelopes are designed and constructed to be more airtight. This reduced infiltration results in a decrease in air change rates (ACR). While this can limit exposure to outdoor contaminants, without adequate mechanical ventilation, reduced infiltration can also exacerbate exposure from indoor sources since the emissions may have a longer indoor residence time [1,2]. Such indoor sources include cooking, emissions from

building materials, heating and cooling systems, household cleaning products, and a variety of building occupant behaviors [3,4]. Other energy saving strategies or climate adaption techniques in houses can have negative impacts on indoor air quality. For example, increased thermal insulation or increased cooling equipment may increase the likelihood of condensation and indoor humidity levels, which can lead to potential biological growth [5].

While there is a wide variety of potential contaminants in indoor air [6], particulate matter (PM) is one of great concern due to potential for high exposure and well-documented negative health effects [4,7,8]. Two of the main contributors to indoor PM of indoor origin worldwide are

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cooking and heating using biofuels [9–11]. While combustion for heating purposes is more prevalent in some developing regions, indoor PM generation from cooking is prevalent everywhere due to high heat emissions of solid and liquid particles originating from the food itself [12,13]. In a study investigating cooking in 15 different Australian houses, He et al. observed peak PM_{2.5} concentrations in the order of 750 $\mu\text{g m}^{-3}$ during frying activities [14]. A study by Vu et al. in 131 London homes showed that 31 % of indoor PM_{2.5} originated indoors, especially from cooking activities [10].

Personal exposure to PM_{2.5} at home is a function of the time spent in different indoor microenvironments by each occupant. Concentrations of cooking emissions, for example, are likely to peak in the kitchen and then decrease as particles are transported throughout the indoor environment [15,16]. Concentrations decrease primarily due to dilution with the indoor air, dilution with outdoor air, and depositional losses to indoor surfaces [17,18]. Ultimately, in a home with closed external doors and windows, a small fraction of particles is expected to go outdoors via exfiltration, while the majority of particles deposit indoors [17,19].

Low-cost, or consumer-oriented PM sensors are becoming increasingly frequent in applications of indoor air quality and exposure assessment. They allow for citizen science and also research applications where many measurements are required, such as investigations of spatiotemporal trends of pollutants both indoors and outdoors. However, low-cost sensor use comes with a tradeoff in data quality. Studies have shown that the Plantower PMS sensor, a common particle counter used in many low-cost PM_{2.5} monitors, can present significant differences in concentration when compared to laboratory-grade instrumentation, partially due to their principle of operation using a miniaturized optical detection system based on light scattering [20–22]. Concentration measurements through particle light scattering are dependent on particle density, hygroscopicity, refraction index, and composition [23]. Variations in environmental conditions, especially relative humidity, have been shown to skew the concentration readings from these instruments [24–27]. However, if used in an informed manner, the benefits of low-cost sensors have the potential to outweigh their limitations, particularly to inform consumers of high-concentration events and prompt action to mitigate those concentrations.

A variety of modeling approaches can be used to describe particle transport and to predict their concentrations in indoor environments. Once particle deposition and air flows are determined via measurements or theoretical approaches, a combination of box models can be developed to describe particle transport through different zones in an indoor environment at varying levels of computing requirement. On one end of this spectrum, a box can encompass an entire room or zone for a more simplified approach [28] and on the other end, a finite volume method (FVM) can be used to discretize a space into many small control volumes for significantly higher accuracy and computational needs [29]. For example, Boedicker et al. compared two mechanistic models to describe particle surface deposition and calculated particle concentration gradients by dividing a test house into three major zones [17]. CONTAM, a multizone airflow and contaminant transport software model developed by NIST, can be used to determine airflow rates, contaminant concentrations, and personal exposure in multiple zones [30]. Empirical models have also been developed to fit experimental data and generate regression coefficients for relatively simple, location-specific equations that estimate indoor particle concentrations [31]. As an example of a computationally-heavy approach, Yu et al. applied the FVM and a set of theoretical equations to model indoor particle flows three-dimensionally through thousands of cells [32].

This work presents results from concurrent measurements using over a dozen PurpleAir monitors that use Plantower sensors deployed inside a three-level test house to investigate the transport of PM_{2.5} emissions from cooking activities, along with transport modeling for the measurement periods. Specific objectives were to (1) Investigate PM_{2.5} concentration gradients and transport time; (2) Compare three different

modeling approaches to predict PM_{2.5} concentrations throughout a house; and (3) Calculate the potential PM_{2.5} exposure for an everyday activity pattern. These results can be leveraged to inform indoor PM_{2.5} exposure from point sources in residential indoor environments.

2. Materials and methods

2.1. The CASA field campaign

Measurements for this work were performed during the Chemical Assessments of Surfaces and Air (CASA) field campaign, which took place from February 25th to April 2nd, 2022, at the Net-Zero Energy Residential Test Facility (NZERTF) at the US National Institute of Standards and Technology (NIST) in Gaithersburg, Maryland.

The 1100 m³ NZERTF test house was designed to be ≈ 60 % more energy efficient than houses built to meet the requirements of the 2012 International Energy Conservation Code and, as such, yields a low infiltration rate ($\approx 0.05 \text{ h}^{-1}$). It is a 393 m² (4227 ft²) 3-story, 4-bedroom and 3-bathroom house that has an open-floor concept kitchen/dining area on the first floor. The first floor has an area of 141 m² (1518 ft²) while the second floor has a 111 m² (1191 ft²) area. There are 3 bedrooms and 2 bathrooms on the second floor. The house also has an unfinished basement and an attic within the thermal envelope. The heating, ventilating, and air conditioning (HVAC) consists of two independently operated heating and cooling air conditioning systems: a large duct (low velocity) and a small diameter (high velocity) system. There is also a dedicated outdoor mechanical ventilation system that can be operated as an Energy Recovery Ventilation (ERV) system or a Heat Recovery Ventilation (HRV) system with a total mechanical ventilation rate of $\approx 0.19 \text{ h}^{-1}$. The HRV/ERV combined with infiltration result in a total ACR of $\approx 0.24 \text{ h}^{-1}$ (supplemental Table S1). The HVAC system was outfitted with a MERV 8 filter. The basement has no air conditioning return air, only air conditioning supply, and there are passive vents connecting the basement to the first floor and the attic to the second floor of the house. The air conditioning fan was constantly on through the experiments. The mechanical ventilation system supply vents are located in the kitchen, southwest bedroom, southeast bedroom, and main bedroom while return vents are located on the bathroom ceilings. Architectural drawings for the NZERTF are available online [33].

The CASA study was an intensive indoor air and surface chemistry experimental investigation with participation of over a dozen research groups from United States and Canada. Additional details about CASA are described elsewhere [34]. While CASA lasted for 49 days and encompassed several types of perturbations to the house, the work presented here includes only two types of datasets: cooking experiments and ambient PM penetration into the house. Briefly, eight cooking experiments (CE1 - CE8) were performed over the course of three experimental days (March 13–15), involving the same ingredients and preparation. Six of these were done using a frying pan while the other two (CE4 and CE7) used an air fryer. The cooking process consisted of heating up the pan/air fryer with canola oil, then adding sliced green bell peppers, followed with tater tots, and bacon. Food items were cooked sequentially with each having a cooking time of ≈ 10 min. The peak oil temperature for the six pan events were 238 °C to 277 °C (460 °F to 531 °F). While not remaining at this high of temperature for the full duration of the cooking period, this maximum temperature range reached the smoke point for canola oil (220 °C to 230 °C, 428 °F to 446 °F).

The first two cooking experiments (CE1 and CE2) were performed under high indoor relative humidity (RH, 60–80 % on the first floor, slightly lower upstairs), which was generated using a whole-house humidifier. The remaining experiments experienced lower RH (30–50 %), with no humidity control. The temperature inside the house remained consistent during these days with a gradient between the four floors (supplemental Table S2). The HRV exhaust, outdoor, and return flows had an average airflow rate of $231 \pm 21 \text{ m}^3 \text{ h}^{-1}$ ($136 \pm 13 \text{ scfm}$) during

the experimental cooking days. No range hood was used, and all internal doors were kept open throughout the study. The HVAC supply flowrate was higher than the other three flows with a value of $1950 \text{ m}^3 \text{ h}^{-1}$ (1150 scfm), but it was reduced to around $1360 \text{ m}^3 \text{ h}^{-1}$ (800 scfm) from 1:00 pm to 11:50 pm on March 14th and 11:50 am to 11:59 pm on March 15th. This constant HVAC flow recirculated air throughout the house at a rate defined henceforth as the recirculation rate (RR, of 1.04 h^{-1}). The outdoor ACR was $0.24 \pm 0.01 \text{ h}^{-1}$ during the experimental days included in this work, as determined by the decay of daily sulfur hexafluoride injections. Additional house conditions for this experimental period are found in Figure S1 and Figure S2. There were other cooking-related experiments performed during CASA (e.g., boiling a vinegar glaze and cooking popcorn in a microwave oven), but those are not included in this work because particle production was low for vinegar cooking, and the microwave cooking was performed closely with other activities.

2.2. Instrumentation and their locations

This work used $\text{PM}_{2.5}$ measurements made with 13 units of the PurpleAir PM monitor (PA-II, PurpleAir, Inc.). These instruments were distributed as follows: five on the first floor, five on the second floor, and one each in the basement, attic, and outdoors (Fig. 1 and Table S3). The kitchen sensor was located $\approx 1 \text{ m}$ above the kitchen counter where cooking was performed. Each PurpleAir contains two Plantower particle sensors (PMS-5003, Plantower). Data from each sensor's Channel A were collected using the Purple Air proprietary mass concentration calculation for indoor particles ("CF1") at 2-min time resolution. The sensors were new at the time of this study, and this was their first deployment.

2.3. Laboratory collocation and data corrections

For quality assurance, the 13 PurpleAir sensors used in this study were collocated with an aerodynamic particle sizer (APS) and a scanning mobility particle sizer (SMPS) using a butanol-based condensation particle counter in a 38 m^3 (1342 ft^3) well-mixed test room in which cooking activities were performed. The same food cooked at CASA was

prepared for these experiments, although amounts were reduced due to the smaller size of the test room. In short, experiments encompassed four emission events where olive oil was heated on a pan by an electric hot plate and then small amounts of bell peppers, tater tots, and bacon were cooked. The chamber temperature was $\approx 27^\circ \text{C}$ and the relative humidity was $\approx 30\%$, which is within the range observed during the low-RH cooking experiments at CASA. To convert number-based measurements by the SMPS and APS into mass-based concentrations, we assumed spherical particles and a density of 1 g cm^{-3} . Results from the SMPS and APS were then combined to calculate $\text{PM}_{2.5}$ concentrations.

Average $\text{PM}_{2.5}$ concentrations on six-minute intervals were compared between the two sets of instruments and a linear regression was performed to determine a correction factor for the PurpleAir sensors. The linear regression showed that the PurpleAir tends to overestimate $\text{PM}_{2.5}$ concentrations, as previously reported for indoor and outdoor sources [22,35–37]. PurpleAir concentrations were about two times higher than those measured by the comparison instruments. Then, this correction factor was applied to the CASA cooking events, where $\text{PM}_{2.5, \text{ corrected}} = 0.49 \times \text{PM}_{2.5, \text{ PurpleAir}}$ (a $\approx 5 \mu\text{g m}^{-3}$ intercept of the regression curve was ignored). Peak corrected injection concentrations ranged from 30 to $250 \mu\text{g m}^{-3}$. The time series for the collocation experiment, and comparison within PurpleAir instruments and between them and the reference instrumentation is presented in supplemental Figures S3 through Figure S8 and accompanying text. Although the use of laboratory calibrations to correct field data is generally discouraged [38], we strived to approximate the aerosol emission characteristics (size, composition, lack of aging) as well as the environmental conditions (temperature, RH, and lack of direct solar radiation) of the low-RH cooking experiments performed during CASA. We did not use field data for corrections due to missing field data from the APS instrument.

2.4. Time series analysis of particle transport

To investigate the temporal behavior of indoor transport of cooking emissions, we measured the time lag between the peak $\text{PM}_{2.5}$ concentration observed by the kitchen sensor and by the remaining 11 sensors distributed throughout the house. The time lag between each sensor and the kitchen sensor was determined through a cross-correlation analysis,

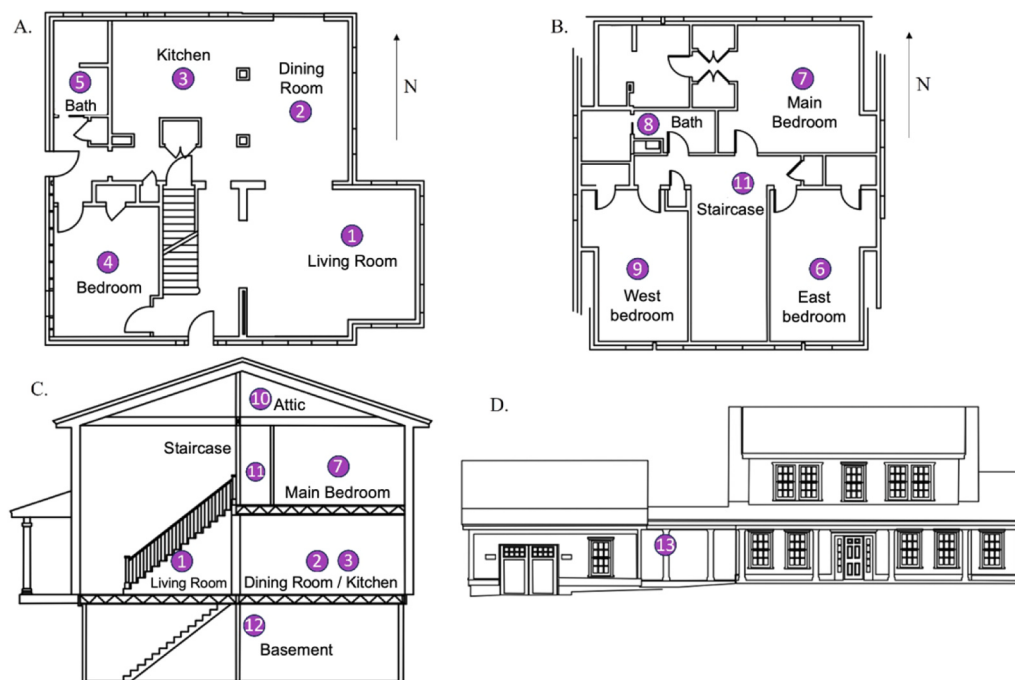


Fig. 1. Different views of the NZERTF test house including instrument locations (purple circles): first floor (A), second floor (B), side (C), and front (D).

and only time lags with a correlation coefficient greater than 0.8 were used. The height of the peak PM_{2.5} concentrations were also compared directly. The fractions of source peak values were calculated by dividing the sensor concentration at its respective lag time by the peak concentration observed by the kitchen sensor.

2.5. Modeling PM_{2.5} concentrations throughout the house

We used the opportunity of real-time measurements in a dozen locations in the house to compare three different modeling approaches, with varying levels of difficulty and input requirements, to predict PM_{2.5} concentrations throughout the house. These three approaches consist of (1) a multi-box model in which the house is represented as four interconnected continuously stirred tank reactors (CSTR), (2) an empirical model adapted from the literature based on indoor distances, and (3) a multizone model developed in CONTAM [30]. Table 1 describes the main inputs and outputs of each model.

The number of inputs, or the difficulty to obtain them, increases with each model. While the box model is arguably the most generalizable, the main output is simpler: an average concentration for each zone of the house. The empirical model requires parallel measurements in several indoor locations in order to determine its coefficients, so it cannot be transferred to other homes without using multiple sensors, and it outputs location-specific concentrations. CONTAM requires several home-specific inputs, including leakage areas, temperatures, and room volumes, as well as PM_{2.5} mass generation rates, but it is capable of estimating the PM_{2.5} concentrations in each room of the house.

2.5.1. Approach #1: multi-box model

This approach is based on a fundamental Continuously-Stirred-Tank-Reactor (CSTR) mass-balance equation (Eq. 1), applied to four control volumes, or zones: (1) the kitchen/dining area, where emissions were measured and assumed to quickly spread through the entire volume and then disperse to the rest of the first floor; (2) the remaining air volume of the first floor (excluding the kitchen/dining area), for which an average concentration is estimated and assumed to then transport to the second floor and the basement; and (3) the air volume of the second floor, and (4) the air volume of the basement.

$$\frac{dM}{dt} = QC_{in} - QC + S - L \quad (1)$$

where dM/dt is the PM_{2.5} mass accumulation in the control volume (also described as VdC/dt), Q is the airflow rate through the modeled space, C_{in} is the PM_{2.5} concentration entering the space, C is the PM_{2.5} concentration in the modeled space, S is the PM_{2.5} source within the modeled space, and L is the PM_{2.5} loss within the modeled space.

The schematic in Fig. 2 shows the modeled spaces with airflow paths considered for each space. Airflow between spaces was primarily driven by the continuously operating HVAC fan. The total airflow rate in and

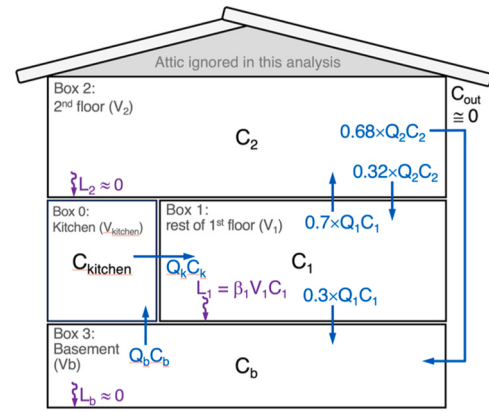


Fig. 2. Multi-box model developed to describe the PM_{2.5} mass flows through four compartments in the test house: the kitchen/dining area (V_{kitchen}), the first floor excluding the kitchen/dining area (V_1), the second floor (V_2), and the basement (V_b). Flowrates into and out of each space are assumed to be promoted by the ventilation rate α ($RR + ACR$).

out of each zone (Q_k , Q_1 , Q_2 , and Q_b) were assumed to equal $\alpha \times V$, where $\alpha = ACR + RR$ (1.40 h^{-1}), and V is the air volume of each space (excluding cabinetry). In this model, not all airflow carries particles, so airflows that carry a concentration of zero particles (e.g., coming from outside) were excluded from the model. To balance internal airflows, it was assumed that the airflow from the first floor is split between the second floor (70 %) and the basement (30 %), which was supported by air condition system supply flow balometer measurements performed by NIST (data not shown here). We also assumed that the outflow from the second floor is split between the first floor (32 %) and the basement (68 %), to enable some recirculation of air into the first floor.

The discrete solution for Eq. 1 for the PM_{2.5} mass accumulation ΔC during a period Δt is shown in Eq. 2 for the first floor, with similar solutions for the second floor and the basement (Supplemental Eq. S1 and Eq. S2 and accompanying text). The inputs for the second floor and the basement are the modeled concentrations on the first floor outputted by Eq. 2. As such, the only experimental concentrations used in the model are those measured in the kitchen.

$$C_{1,t} = C_{1,t-1} + (Q_k C_{k,t-1} + 0.32 Q_2 C_{2,t-1} - Q_1 C_{1,t-1} - \beta V_1 C_{1,t-1}) \frac{\Delta t}{V_1} \quad (2)$$

Where $C_{1,t}$ and $C_{1,t-1}$ are the average PM_{2.5} concentrations of the first floor (excluding the kitchen/dining area) at times t and $t - 2 \text{ min}$; C_k is the concentration measured in the kitchen; C_2 is the concentration modeled for the second floor (Eq. S1); Q_k is the air flow through the kitchen ($\alpha \times V_k$) and V_k is the air volume of the kitchen/dining area

Table 1
Inputs and primary output of each modeling approach used in this study.

Input category	Approach #1: Multi-box model	Approach #2: Empirical model	Approach #3: CONTAM
Source PM _{2.5} concentration	Kitchen PM _{2.5} concentration (PA3).	Kitchen PM _{2.5} concentration (PA3).	PM _{2.5} mass generation rates.
Particle losses	Depositional losses to surfaces (β).	-	NZERTF average depositional lose rates.
Physical distances or volumes	Zone volumes.	Distances between particle source and modeled locations.	Room volumes.
Airflow	Internal air recirculation rate due to HVAC airflows (RR) and house ACR.	-	RR, ACR, HRV flow rate, leakage area between rooms and outdoors.
Temporal behavior of particle transport	-	Average particle transport time from the kitchen to each modeled location (t_{lag}).	-
Other	-	Model coefficients (a , b , c , d , determined using experimental training data).	Temperature of each room and outdoors.
Model output	Average PM _{2.5} concentration for zones on the first floor, second floor, and basement.	PM _{2.5} concentration in 4 specific locations on the 1st floor and 5 locations on the 2nd floor.	PM _{2.5} concentration for each room.

(excluding cabinetry); Q_1 and Q_2 are the total flow rates through of the first and second floors, respectively ($Q_1 = \alpha \times V_1$ and $Q_2 = \alpha \times V_2$), where V_1 and V_2 are the volumes of the first floor (excluding the kitchen/dining area) and the second floor, respectively. β is the particle depositional losses to surfaces for the first floor, measured experimentally during particle decay periods minus ACR and RR (0.21 h^{-1} , Table S4); and Δt is the time step for the model, set to be equal to the PurpleAir time resolution of 2 min.

Due to recirculation of air from the second floor to the first floor and basement, this model was run in an iterative fashion. The model equations are run sequentially to determine concentrations on the first floor, then second floor, then basement. During the first iteration, all particle inputs are zero except for the kitchen. Then, second-floor results of the previous iteration are used as an additional input for subsequent iterations on the first floor and basement, as shown by Eq. 2 and the arrows in Fig. 2. We found that after 3 iterations, the results changed by less than $0.2 \mu\text{g m}^{-3}$, so this model was run for a total of 4 iterations for each zone. Additional descriptions and model assumptions are described in the supplemental file.

2.5.2. Approach #2: empirical model

Shen et. al. proposed a model for the temporal and spatial variation of $\text{PM}_{2.5}$ in a single-floor apartment in Beijing, China [31]. In their apartment setting, there were two windows that promoted significant $\text{PM}_{2.5}$ infiltration from outdoors, and 1 $\text{PM}_{2.5}$ source from the kitchen. They developed the relationship described by Eq. 3:

$$\log(C_{i,t}) = a * \log\left(\frac{C_{o,t-\text{lag}-o1}}{L_{o1}}\right) + b * \log\left(\frac{C_{o,t-\text{lag}-o2}}{L_{o2}}\right) + c * \log\left(\frac{C_{k,t-\text{lag}-k}}{L_k}\right) + d \quad (3)$$

Where $C_{i,t-\text{lag}-i}$ is the concentration ($\mu\text{g m}^{-3}$) at the outdoor and indoor source sensor at given lag times; L_i is the pathway distance (m) from a given indoor site to the outdoor (L_{o1} and L_{o2}) and source sensor (L_k) (Table S5); a , b , c , and d are the regression coefficients. Shen et. al. found the respective regression coefficients for a , b , c , and d to be 0.181 ± 0.005 , 0.190 ± 0.004 , 0.437 ± 0.004 , and 0.794 ± 0.002 .

The NZERTF test house used for CASA has a tight building envelope and low ACR. So, unlike Shen et al., we opted to include just one infiltration term that represents the distance from each sensor to its closest HRV duct, which is expected to be the main point of injection of ambient PM into the house. Lag times of ambient PM penetration to each room was determined from three instances of high ambient (outdoor) concentration events (Figure S9). Indoor/outdoor regressions for this period and average time lag times used for the ambient term are available in Table S6.

For the distance between each sensor and the indoor PM source in the kitchen, we used straight-line distances to the kitchen sensor (ignoring any physical barriers) for the first floor and explored three options for the second floor to investigate how this model can be adapted to a multi-floor residence: (1) the straight-line distance, accounting for the height differences between floors, (2) the vertical distance between the first and second floors, (3) a vertical path from the cooking surface to the second floor, then horizontally to each sensor, again by straight-line distances and not pathway distance (Figure S10, Table S5). The model adjusted for this work is as follows (Eq. 4).

$$\log(C_{i,t}) = a * \log\left(\frac{C_{o,t-\text{lag}-hrv}}{L_{hrv}}\right) + b * \log\left(\frac{C_{k,t-\text{lag}-k}}{L_k}\right) + c \quad (4)$$

Where $C_{i,t}$ is the $\text{PM}_{2.5}$ concentration at a given location and time; $C_{o,t-\text{lag}-hrv}$ is the concentration at the outdoor location at time t minus the lag time of indoor transport; L_{hrv} is the distance from the respective location to its nearest HRV supply duct and L_k is the distance to the kitchen sensor; $C_{k,t-\text{lag}-k}$ is the $\text{PM}_{2.5}$ concentration at the kitchen sensor at t minus the lag time; a , b , and c are the regression coefficients.

2.5.3. Approach #3: CONTAM model

CONTAM is used to construct a digital idealization of a building and virtually recreate the environment. The model uses measured temperatures, HVAC airflow, and HRV airflow to determine pressure differences, airflows and contaminant migration between adjacent zones [30]. The NZERTF CONTAM model comprises individual zones for each room and closet in the test house. Throughout the test period, measurements for the following model parameters were recorded: indoor and outdoor temperatures, wind speed and direction, total HRV airflow rates, total HVAC airflow rate, and CO_2 concentrations. All values, shown in Table S7, were recorded every minute and used as inputs in the model. Zone volumes are shown in Table S8.

The previously developed detailed CONTAM model for the NZERTF [39] was modified for this effort as summarized in the supplementary information (SI section 1.8). In brief, modifications for this work include breaking the single zone open floor plan living/dining volume into two zones, breaking the single zone two-story entry foyer into two zones, and adding leakage flows into and out of the basement from the HRV ventilation system and HVAC system as described in the Supplementary Information. In addition, five assumptions were made in the modeling effort. These assumptions include smoothing the measured data over gaps, CO_2 injection flows rates, a balanced HVAC system, closets with the same temperatures as adjoining rooms, and the fraction of the HVAC flow delivered to the basement.

Before modeling the cooking events the model was validated. The updated CONTAM model was run using inputs from days where CO_2 was injected as a non-reactive tracer during the post-CASA test period. CO_2 was injected on six occasions and at three locations (basement, first floor, second floor). Two of these injections were used to adjust duct leakage areas in the model reflecting the NZERTF environment during CASA, and the other four injections used for validation. While modeling the CO_2 injections, the need for three of the previously mentioned model adjustments became apparent. First, the separation of the living room into its own zone was required due to mixing issues. The living room was the only first floor location where the CO_2 concentration was measured. Separating the living room from the kitchen, where CO_2 was injected on the first floor, was necessary to produce a realistic CO_2 concentration peak shape for the CO_2 measurement in the living room. This is due to the uniform concentration assumption for each zone. Second, the separation of the foyer into two zones was needed to better capture the thermal stratification of the two-story space and the resulting airflows. The foyer was horizontally separated into two zones y floor. Third, the transport of the CO_2 to the basement was faster than the HVAC supply air in the model could provide. Hence, leakage in the amount of 10 % total HVAC airflow was diverted to the basement through both the supply and return.

After confirming the CO_2 concentrations produced by the updated NZERTF model reasonably fit measured CO_2 concentrations during the other four CO_2 injections, the updated NZERTF model was used to simulate indoor particulate matter, specifically $\text{PM}_{2.5}$, resulting from the cooking events using the appropriate measured parameters for each cooking day. There were four assumptions for this model:

The $\text{PM}_{2.5}$ measurement in the kitchen did not increase until the first food item was added to the hotplate. As a result, the simulated cooking event start time was set to the time at which measured $\text{PM}_{2.5}$ began to increase.

The dining room sensor was located within the same zone that the cooking took place but with more physical separation from the cooktop than the kitchen sensor. Hence, it was assumed that the dining room sensor was more representative of the entire kitchen volume $\text{PM}_{2.5}$ concentration and was used as the reference point for the mass of $\text{PM}_{2.5}$ emitted into the NZERTF during each cooking event.

Since the mass of $\text{PM}_{2.5}$ that was produced during each cooking event was unknown, a constant simulated $\text{PM}_{2.5}$ mass generation rate was generated from the kitchen zone data. The $\text{PM}_{2.5}$ mass generation rate was set to an amount such that the peak simulated concentration in the

dining room matched the peak measured concentration in the dining room (to within 1 %). The simulated PM_{2.5} mass generation rate for each cooking event is shown in Table 2. This generation rate was assumed to be constant from the time the cooking event started to the peak concentration time. For some cooking events (e.g., CE6) this constant source rate assumption was not ideal.

1. The median PM_{2.5} particle size by mass was assumed to be 0.7 μm , based upon data from similar cooking (stir fry) events during the HOMEChem study [13]. As such this value was used to determine the HVAC filter efficiency (0.2 filter efficiency as defined in CONTAM) and room deposition value 0.11 h^{-1} [40]. The deposition value was applied to every zone in the model as the PM_{2.5} depositional loss rate.
2. Modeled initial PM_{2.5} values were the measured values in each zone prior to the cooking event. Each cooking event was modeled independently of other events.

2.6. Indoor microenvironmental PM_{2.5} exposure

To explore the implications of cooking for house inhabitants we performed a PM_{2.5} exposure analysis using a typical schedule throughout a house which included two cooking events. This exposure scenario was adapted from Klepeis [41,42], and includes a total of 16.5 h in the house. Time spent indoors includes: 10 h in the bedroom, 3 h in the living room, 1.5 h in the kitchen/dining room, 1 h in the bathroom, and 1 h in the home office (first floor bedroom).

For this analysis, we combined datasets from cooking events, including post-cooking decay periods throughout the house, as well as datasets for outdoor PM_{2.5} penetration during background periods. This was necessary because the test house did not experience any PM_{2.5} penetration during the experimental cooking days (observed by a decay period to near-zero indoor PM_{2.5} concentrations and further discussed in the empirical modeling results, below).

Background concentrations were used from Sunday, March 6th. The house remained closed and unoccupied throughout that day, so the concentrations observed indoors were due to penetration from outdoor particles. On that day, the 24-h average ambient PM_{2.5} concentration was 14.9 $\mu\text{g m}^{-3}$, peaking at 33.7 $\mu\text{g m}^{-3}$. Indoor concentrations peaked at 18 $\mu\text{g m}^{-3}$ and averaged 8 $\mu\text{g m}^{-3}$ in the main spaces of the house (Figure S9b). Exposure periods following cooking events encompassed the summed ambient and cooking concentrations and accounted for the average decay periods observed for cooking events CE1–CE8.

3. Results and discussion

3.1. Indoor PM_{2.5} concentrations during cooking events

For the three cooking days, the first floor (excluding the kitchen sensor) had a 24-hr average PM_{2.5} concentration of $3.5 \pm 0.4 \mu\text{g m}^{-3}$, while the second floor had an average of $2.0 \pm 0.2 \mu\text{g m}^{-3}$. The 24-hr average values for the attic, basement, and outside sensors were 0.1, 2.3, and 0.9 $\mu\text{g m}^{-3}$, respectively (Fig. 3). Hourly average concentrations for each sensor in the first and second floors are shown in

Table 2

Simulated mass generation rates for PM_{2.5} in each cooking event.

Cooking event	PM _{2.5} mass generation rate ($\mu\text{g}/\text{min}$)
1	1 210
2	485
3	768
4	2 440
5	700
6	1 110
7	347
8	525

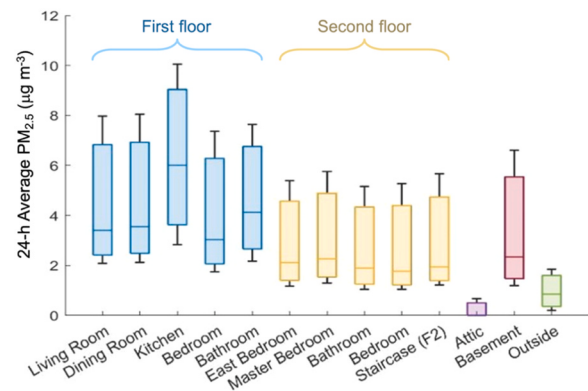


Fig. 3. The 24-hr average PM_{2.5} concentrations throughout the house during the cooking experiment days at CASA. Colors represent the different floors of the house. The measurements in the staircase between the 1st and 2nd floors was performed at the 2nd floor level. Boxes represent the interquartile range (25th, 50th, and 75th percentiles) and whiskers represent the range of data within $1.5 \times$ the interquartile range from the first and third quartiles, excluding outliers.

Figure S11. Fig. 4 presents time series of PM_{2.5} concentrations for each cooking event throughout the house.

Although the researchers strived to replicate cooking experiments exactly, there was variability in observed concentrations and temporal behavior from cooking the same meals, for both air fryer and pan cooking. This was also the case during the HOMEChem study [13]. Differences in emissions are expected as they depend on many factors including cooking oil type, food being cooked, temperature, additives, and the room air volume as well as local airflow conditions [43]. The peak PM_{2.5} concentrations for the cooking experiments ranged from 31 $\mu\text{g m}^{-3}$ (CE7, air fryer) to 240 $\mu\text{g m}^{-3}$ (CE6, pan frying), as recorded by the source (kitchen) sensor. The peak concentrations resulting from pan frying were lower than those reported in other studies [14,44]. The second highest concentration peak recorded by the kitchen sensor was for air frying during CE4 (226 $\mu\text{g m}^{-3}$). Some events produced only one prominent concentration peak (CE1, CE3, CE4, and arguably CE7), while others produced multiple discernible peaks (notably CE5 and CE8). The start of each concentration peak in the kitchen coincided with adding new ingredients or flipping or stirring them in the pan.

3.2. PM_{2.5} transport through the house: peak time lags

The overall time lags for each sensor as well as their peak magnitudes with respect to the measurements in the kitchen for all cooking events are presented in Fig. 5. At no point during the cooking experiments did the attic sensor detect a change in PM_{2.5} concentration, so it was omitted from further analysis. Because of multiple concentration peaks during the same cooking event, CE5 and CE8 were excluded from this analysis. More detailed cross-correlation results are presented in Figure S12 and Figure S13, and Table S9 through Table S11.

The first-floor sensors generally saw small time lags from the cooking emissions. The dining room saw a median time lag of two minutes, while the living room and first floor bathroom saw median time lags of four minutes. As a reminder, the time resolution of the PurpleAir instruments used in this study is two minutes. The short lag experienced in the bathroom is explained by the fact that the HRV exhaust is located in that space, resulting in a strong impact of the HRV airflows on the indoor contaminant transport for that zone. Of all the sensors on the first floor, the bedroom saw the longest time lag, with a median lag time of five minutes. This sensor was the farthest from the cooking area. This suggests that the airflow pattern to this location took a path correlating to the pathway distance. The particles were transported to the second floor more quickly than what would be expected by following an airflow

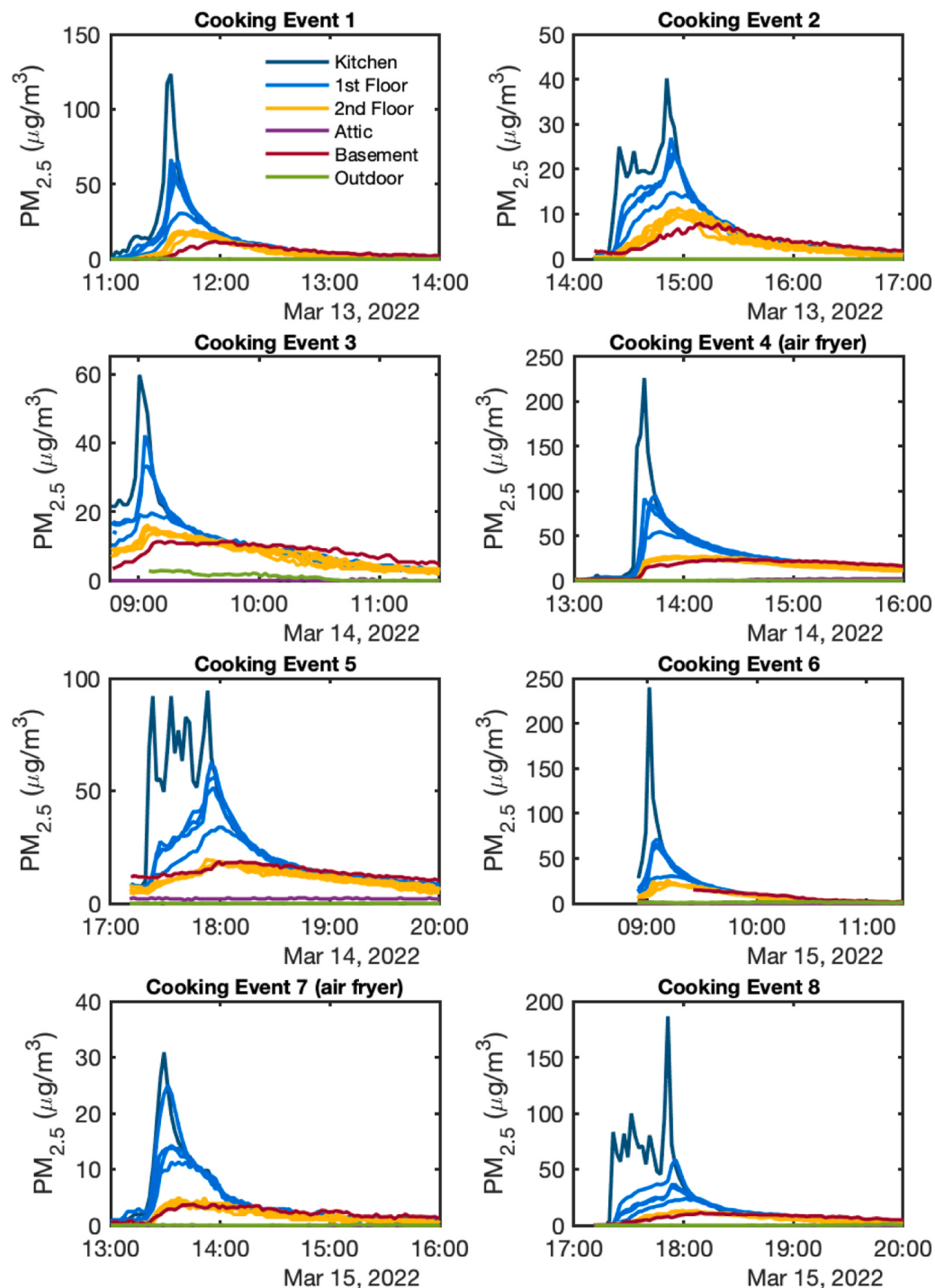


Fig. 4. $PM_{2.5}$ concentrations throughout the house during the 8 cooking events used in this work (March 13, 2022 through March 16, 2022), measured by PurpleAir sensors ($\mu g m^{-3}$). Concentrations presented here were corrected using post-calibration experiments ($PM_{2.5, corrected} = 0.49 \times PM_{2.5, PurpleAir}$). CE1 and CE2 were performed under high RH (60–80 %), while CE3 to CE8 were performed under low RH (30–50 %). Cooking events 4 and 7 were performed in an air fryer, all others on a pan on electric cooktop. Note that the y-axis scale is different for each panel and the legend in the first panel applies to all panels.

pathway through doors and stairs. The median time lag for the east bedroom, main bedroom, and the west bedroom were 5.5, 9, and 7 min respectively. The second-floor bathroom and stairwell saw the longest time lags among the second-floor sensors, with median time lags of 10 and 10.5 min; the stairwell transport likely followed a non-direct airflow pathway or was impacted by thermal stratification. The basement sensor experienced the longest time delay between all the in-house sensors with a median time lag of 22 min. The attic saw none to minimal increase in particulate matter concentration and seemed to be largely unaffected by

indoor sources. The attic is only connected to the rest of the house via short passive ducts and air leakage in the attic floor.

The PM concentration decreasing as particles travel through the house is consistent with what was expected considering the time lags between each sensor and the source. The first-floor sensors observed about half of $PM_{2.5}$ concentrations observed in the kitchen. Next, the second floor as well as the basement sensors observed about half of the $PM_{2.5}$ concentrations observed on the first floor. The living room, dining room, and first floor bathroom sensors all experienced the shortest time

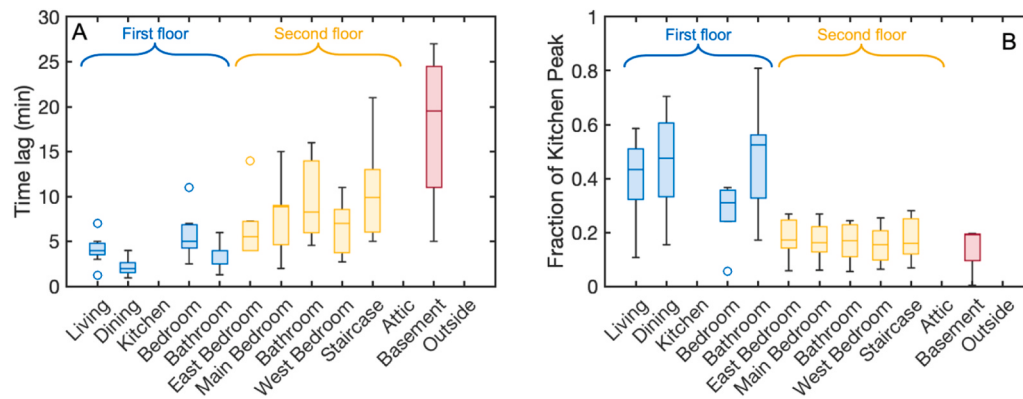


Fig. 5. (A) Cooking emission time lag between concentration peaks (min). (B) Fraction of peak concentration relative to source peak. Whiskers represent the range of data within $1.5 \times$ the interquartile range from the first and third quartiles, and outliers fall outside this range. Mean values and resulting sample sizes are presented in Table S9.

lags, and subsequently the smallest reduction in concentration from the source. Their median peak magnitude with respect to the source were 44 %, 49 %, and 53 %, respectively. The first-floor bedroom experienced the smallest concentration fraction (33 %) from all sensors on the first floor.

Floor-to-floor transport of cooking emissions appears to homogenize $PM_{2.5}$ concentrations and time lags across all second-floor sensors. The median second-floor peak magnitude with respect to the source ranged from 15 % to 19 %. This indicates that, despite the high indoor recirculation rate in this house that is promoted by the continuously running HVAC system, the majority of emitted particles from a given cooking event might initially disperse through the first floor, then are evenly transported to the second floor. The HVAC system was outfitted with a MERV 8 filter, which is known to have a > 20 % efficiency for particles $< 3 \mu m$ in size.

3.3. Modeling $PM_{2.5}$ transport

Table 3 compares the three modeling approaches used in this study in terms of the slope of the linear fit line, coefficient of determination (R^2), root mean square error (RMSE), and sample size (n). No model was superior in terms of all three metrics (linear slope, R^2 , and RMSE). While the empirical model generated the closest linear slope and lowest RMSE value, the box model (for 1st and 2nd floors) generated the highest R^2 value. The result for each model is discussed individually below.

3.3.1. Approach #1: multi-box model

The multi-box model was used to estimate particle concentration increases throughout the house from a kitchen source. The time series results for this modeling approach can be seen in Figure S14. The box model underpredicted concentration peaks (by 46 %, on average) but worked reasonably for predicting mean, time-integrated concentrations for each cooking period, as discussed below. Because multiple PurpleAir sensors were offline during CE3 and CE6, those were omitted from analysis. A comparison of experimental measurements and modeled results is shown in Fig. 6, with additional information on Figure S14 and

Table 3
Comparison between three models in terms of mathematical and statistical summaries.

Modeling approach	Linear slope	R^2	RMSE ($\mu g m^{-3}$)	n
Multi-box model (1st and 2nd floors)	0.79	0.82	9.4	12
Multi-box model (basement)	0.40	0.72	6.9	6
Empirical model	0.95	0.77	6.2	45
CONTAM	0.86	0.57	11.3	48

Table S12.

The box model did not capture the temporal behavior of the observed concentrations, resulting in the arcing patterns observed in the data in Fig. 6a, also seen in the time series shown in Figure S14. However, the box model performed well in predicting time-integrated $PM_{2.5}$ concentrations on the first and second floors (with an average difference of -1 % compared to experimental values, Table S12). Integrated $PM_{2.5}$ concentrations were underestimated by 46 % on the basement level. This is likely because this model assumes a uniform concentration in each zone and may not adequately capture air movement between zones. In reality, localized flows are likely to enhance PM transport throughout the house. Fabian and Levy [45] investigated the use of a single-box model and CONTAM to predict $PM_{2.5}$ concentrations in a multi-family building and found that the box model was not capable of capturing important dynamics in these cases. They also found that CONTAM performed better than the box model. Dhiman et al. [46] examined PM transport between two zones in a dining facility and found that differences in ACR during different meals accounted for the variability in indoor PM transport.

3.3.2. Approach #2: empirical model

We adapted an empirical model (Eq. 4) to recreate a time series of $PM_{2.5}$ concentrations in 10 locations throughout the test house where measurements were also made by PurpleAir sensors. The values for coefficients a, b, and c for the different approaches to measure distances on the second floor are listed in Table 4. The model performed slightly better to predict concentrations on the first floor ($R^2 = 0.90$) compared to the second floor ($R^2 = 0.82$ – 0.86).

Due to the observed homogenization between the sensors' lag time and concentration decay for the second floor, Method 2 performed best to account for floor-to-floor transport of $PM_{2.5}$. In Method 2, for the first floor, the distances used were direct lines, ignoring any physical barriers (ranging from 4.29 to 8.10 m). For the second floor using Method 2, the distances used were a direct vertical line to a point above the kitchen for all sensors (4.39 m).

The robustness of Method 2 was then evaluated by omitting one cooking event at a time as a training dataset and then testing it on the remaining cooking event dataset. Results from this analysis are shown in Table S13 and Figure S15. The training and testing analysis resulted in similar average a, b, and c coefficients (-0.007 , 0.914 , and 0.683 respectively).

Ambient PM penetration indoors had a negligible effect in indoor PM concentrations during cooking periods (as evidenced by a coefficient of -0.006). When evaluating the ambient PM model separately, in three instances of high ambient $PM_{2.5}$ concentrations (Figure S15) and no indoor PM sources, the average linear regression slope was 0.104 , with an average lag time of 61 min. This demonstrates that about 10 % of

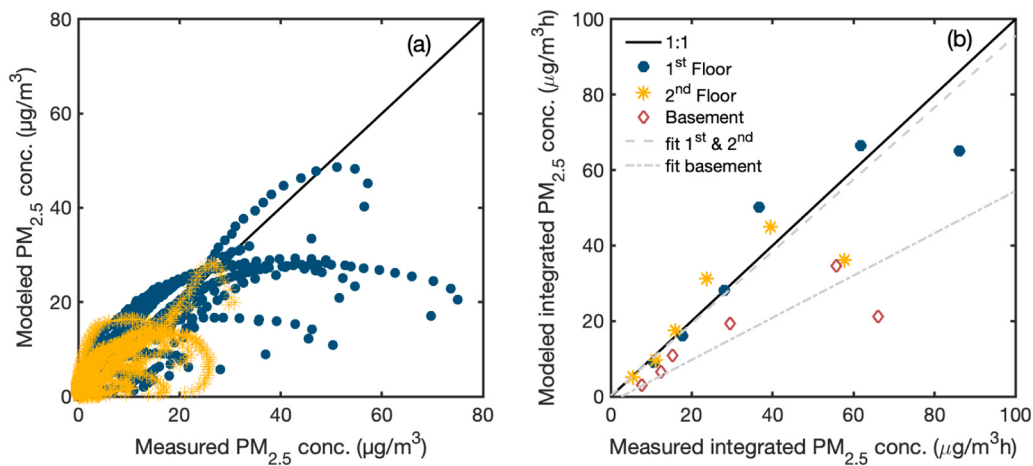


Fig. 6. (a) Measured and box model $PM_{2.5}$ concentrations for all cooking events (time resolution = 2 min). (b) time-integrated measured and box model $PM_{2.5}$ concentrations for the first floor, second floor, and basement of the test house ($n = 18$). The fit for the first and second floor combined data yielded a slope of 0.79, an $R^2 = 0.82$, and $RMSE = 9.4 \mu g m^{-3}$. The linear fit for the basement yielded a slope of 0.40, an $R^2 = 0.72$, and $RMSE = 6.9 \mu g m^{-3}$.

Table 4

Model coefficients for a, b, and c ($\pm$ standard deviations); coefficient of determination (R^2); root mean square error (RMSE), and number of data points (n). Measurements in which concentrations were $0 \mu g m^{-3}$ were filtered out. Cooking events 2, 6, and 8 were also excluded from this analysis due to their temporal behavior having multiple prominent peaks during cooking.

		a	b	c	R^2	RMSE($\mu g m^{-3}$)	n
1 st Floor	Method 1	-0.017 ± 0.008	0.928 ± 0.009	0.704 ± 0.008	0.90	0.2	1271
Both Floors	Method 1 (straight line)	-0.001 ± 0.005	0.871 ± 0.008	0.718 ± 0.006	0.82	0.2	2672
	Method 2a (vertical)	-0.006 ± 0.005	0.922 ± 0.007	0.681 ± 0.006	0.86	0.2	2672
	Method 2b (vertical, omitting infiltration)	omitted	0.853 ± 0.008	0.775 ± 0.004	0.82	0.2	2672
	Method 3 (vertical + horizontal)	0.008 ± 0.005	0.852 ± 0.008	0.782 ± 0.006	0.82	0.2	2672

ambient $PM_{2.5}$ concentrations were observed indoors about 1 h later. The ambient PM term was ignored in subsequent analyses. The resulting equation for the empirical model (Method 2b) during cooking periods, ignoring ambient PM penetration, is shown in Eq. 5.

$$\log(C_{i,t}) = 0.853 * \log\left(\frac{C_{k,t-lag-k}}{L_k}\right) + 0.775 \quad (5)$$

A comparison between modeled and experimental $PM_{2.5}$ concentrations and integrated concentrations, using the empirical model (Method 2b), are presented in Fig. 7, with additional model results shown in Figure S16. When integrating $PM_{2.5}$ concentrations over each

cooking period, the model performance was similar between the first and the second floors. Compared to the box model, the time integrated concentrations were more accurate (slope closer to 1), but less precise (lower R^2 and higher RMSE).

3.3.3. Approach #3: CONTAM model

The updated CONTAM model of the NZERTF was able to capture both the peak concentrations of $PM_{2.5}$ as well as the particle concentration decay using the peak concentration data in the dining room and building parameters (zone temperatures, wind, HVAC and HRV airflows) as inputs (Fig. 8). As with the previous two models, the measured

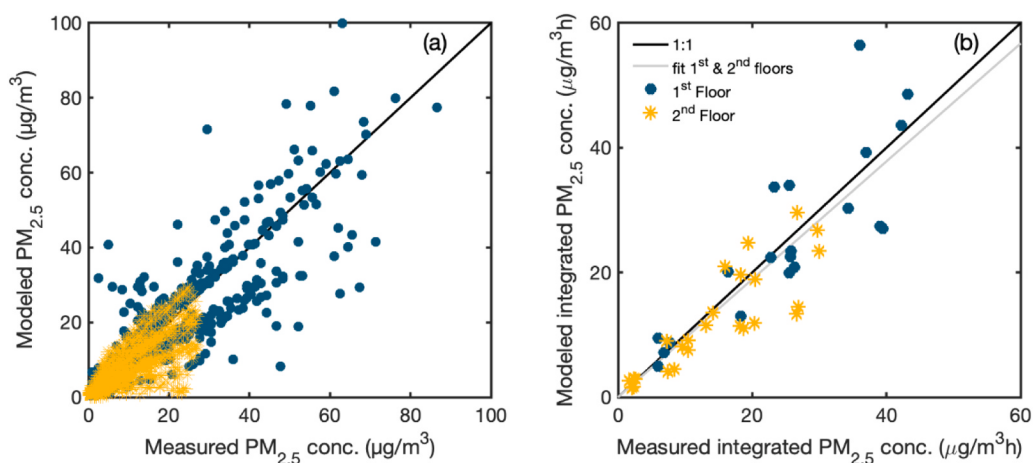


Fig. 7. Measured and modeled (a) $PM_{2.5}$ concentrations ($n = 2672$, time resolution = 2 min) and (b) time integrated $PM_{2.5}$ concentrations ($n = 45$) using the empirical model (Method 2b) for the first floor and second floor of the test house. The linear fit for the first and second floor combined data yielded a slope of 0.95, an $R^2 = 0.77$, and $RMSE = 6.2 \mu g m^{-3}$.

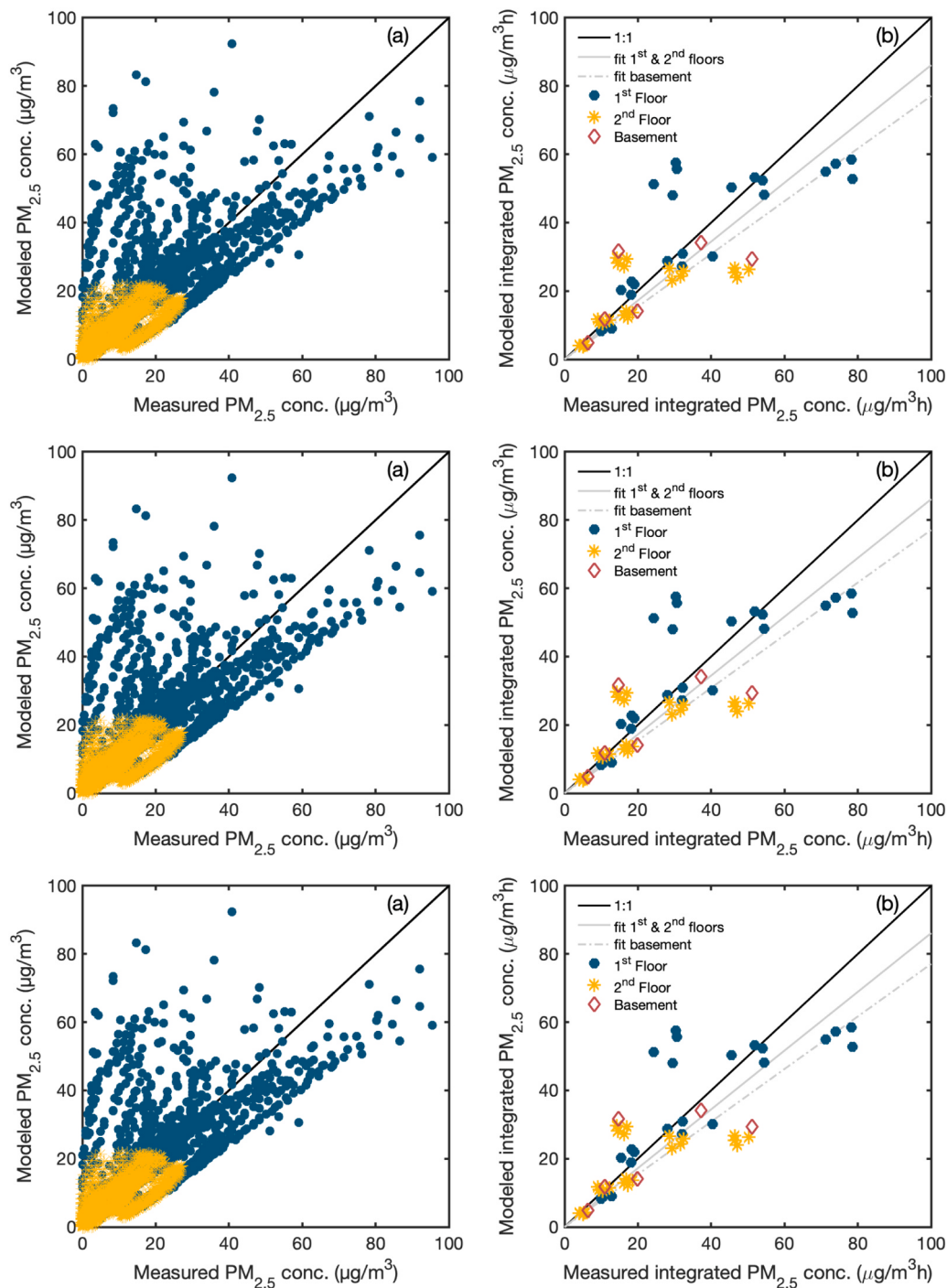


Fig. 8. Measured and CONTAM modeled $PM_{2.5}$ (a) particle concentrations ($n = 5280$, time resolution = 2 min) and (b) time integrated $PM_{2.5}$ concentrations ($n = 48$) from the first floor and second floor of the test house. The linear fit for the first and second floor combined data yielded a slope of 0.86, an $R^2 = 0.57$, and $RMSE = 11.3 \mu g m^{-3}$. Due to missing experimental data, CE3 and CE8 were removed from the time-integrated analysis.

particle concentration data was compared to the modeled particle concentration data for each cooking event. As seen in Fig. 8a), the first-floor particle concentrations (blue dots) were higher than the second-floor particle concentrations (yellow dots) and are shown against a 1:1 relationship line (perfect agreement). The data showing consistent trends away from the 1:1 line are from situations when a constant emission source did not represent the varying cooking emission data (e.g. CE1 in Figure S17).

The time-integrated PM concentrations in each zone were calculated for both the measured and modeled particle concentration data of the

first and second floors over the course of an hour after the start of the cooking event. A majority of the differences were likely the result of the assumption of constant particle generation rate while cooking. For the first and second floor, time integrated concentrations using the CONTAM model results were less accurate relative to the measurements than using the empirical model, but more accurate than the box model. Due to the constant emission source assumption the CONTAM model was less precise than either of the other two models.

3.4. Indoor microenvironmental PM_{2.5} exposures

Using a realistic activity pattern in which a person spends 16.5 h per day at home, the PM_{2.5} exposure and mean PM_{2.5} concentrations for five locations throughout the house are presented in Fig. 9. Detailed results for this analysis are presented in Table S14 and Table S15.

Indoor concentrations due to outdoor particle infiltration ranged between 2.1 $\mu\text{g m}^{-3}$ and 6.4 $\mu\text{g m}^{-3}$. Indoor concentrations due to indoor cooking ranged between 0 $\mu\text{g m}^{-3}$ and 28.9 $\mu\text{g m}^{-3}$. Mean PM_{2.5} concentrations ranged between 3 $\mu\text{g m}^{-3}$ and 32 $\mu\text{g m}^{-3}$ for quantified indoor microenvironments (locations of sensors), with the highest value in the kitchen (during mealtimes) and the lowest in the bedroom (during nighttime). This would lead to a 16.5-hr average concentration of 7 $\mu\text{g m}^{-3}$. Although not encompassing the entire day, this value is below other studies that have reported 24-hr average home PM_{2.5} concentrations (around 28 $\mu\text{g m}^{-3}$ to 47 $\mu\text{g m}^{-3}$ [47]).

Of the total PM_{2.5} exposure in the home, 54 % originated from indoor cooking and the remaining 46 % resulted from outdoor PM_{2.5} infiltration into the house. This result agrees with Lunderberg et al., who estimated PM_{2.5} infiltration factors in approximately 4000 US homes and determined that about half of indoor PM_{2.5} originates from indoor sources [48].

The PM_{2.5} exposures in the different microenvironments ranged between 3 $\mu\text{g m}^{-3}\text{h}$ and 48 $\mu\text{g m}^{-3}\text{h}$. The total summed exposure over the 16.5-hour duration at home would be 109 $\mu\text{g m}^{-3}\text{h}$. The highest exposure was observed during the cooking periods. Although the kitchen / dining area only accounted for 9 % of the time spent at home, it corresponded to 44 % of the PM_{2.5} exposure (48 $\mu\text{g m}^{-3}\text{h}$) due to relatively high PM_{2.5} concentrations ($\approx 32 \mu\text{g m}^{-3}$). The second highest exposure location was in the bedroom, responsible for 61 % of the time at home at a low PM_{2.5} concentration (3 $\mu\text{g m}^{-3}$). These results agree with other studies that suggest that the highest PM exposure in the home occur in the kitchen [15] and in the bedroom [49].

4. Limitations

This study had four major limitations:

Due to the design goal of the NZERTF, the test house operates at low ACR (0.24 h^{-1}). While this allowed for a long residence time of emitted species, it also limits the interaction between the indoor and outdoor air. This is not currently representative of the average US house's ACR, described as following a lognormal distribution with a geometric mean of 0.5 $\text{h}^{-1} \pm 2.0 \text{h}^{-1}$ [50]. Lower ACR values could become more prevalent as energy efficiency and building envelope tightening efforts become more prevalent.

Due to the experimental design of CASA, the HVAC system operated continuously, while most residential units run less than 20 % of the time [51]. This resulted in enhanced internal mixing in this work compared to

the average home.

The operation principle of the low-cost sensors and their inherent measurement uncertainty result in limitations on particle sizes that can be observed and their accuracy. During cooking activities in this study, particle number concentrations peaked in the ultrafine (< 100 nm) size range [34], which is outside the detection limit for Plantower sensors (d_{50} cutoff = 0.3 μm).

We did not investigate the effects of weather (particularly windspeed and indoor/outdoor temperature differences) in the transport of particles.

5. Conclusions

We investigated particle transport from cooking emissions throughout a 4-level house using low-cost sensors. We show that when the HVAC fan is on, emissions are transported relatively quickly throughout the main spaces of the house, within ~ 5 min to the first floor and within ~ 10 min to the second floor. Cooking emissions reached the basement after ~ 22 min and they did not reach the attic at measurable concentrations. During indoor transport, particle concentrations decrease due to dilution with indoor air, deposition to surfaces, and losses to the outdoor environment. Compared to peak PM_{2.5} concentrations observed in the kitchen, the remaining areas on the first floor observed roughly half of those magnitudes, which dropped by roughly half again when reaching the second floor.

We used three modeling approaches to describe particle transport throughout the house, with different input requirements: a multi-box model, an empirical model, and the CONTAM multizone model. While the box model predicted time integrated PM_{2.5} concentrations in the first and second floors of the house, several assumptions had to be made, especially related to internal airflows and box volumes. The empirical model performed similarly but required space-resolved, concurrent measurements throughout the house to develop it, which is not always feasible. The CONTAM model predicted the particle decays adequately using only the peak concentration in the dining room for each event and building parameters as an input, but required a detailed house model, tuning with CO₂ tracer testing, and the assumption of constant particle production during cooking.

All models predicted time integrated PM_{2.5} concentrations on the 1st and 2nd floors, with R^2 between 0.57 and 0.82 and RMSE from 6 to 11 $\mu\text{g m}^{-3}$. All models, especially the box model and CONTAM, under-predicted PM_{2.5} concentrations more severely during air fryer experiments compared to pan frying. This was likely because air fryer experiments led to a single, sharp peak of emissions and these models outputted a more gradual increase and decrease in concentrations due to assumptions of uniform concentration within each zone. The method used for quantifying the PM_{2.5} source (i.e., concentration in the kitchen vs average from the kitchen-dining area vs mass-emission rates) had strong influence on the results for all models.

While all models outputted time-resolved particle concentrations, spatial resolution varied. The empirical model and the CONTAM model were able to estimate particle concentrations at specific point locations within the house, while the box model was only able to predict average concentrations for certain zones in the house. Although the box model is more limited than the other two investigated modeling approaches, its inputs were easier to obtain and its output may be sufficient to provide information for making decisions based on overall PM_{2.5} concentrations indoors, e.g., where to place a portable air cleaner to reduce occupant exposure. No trends or differences were observed between the behavior of particles during high RH compared to low RH experiments.

Understanding and predicting PM_{2.5} concentrations throughout a house can help identify trends and inform prevention and mitigation strategies. While indoor sources of PM are not constrained to just cooking, the results of this work might be applicable to other indoor point sources such as candles, incense, and office products such as printers [52].

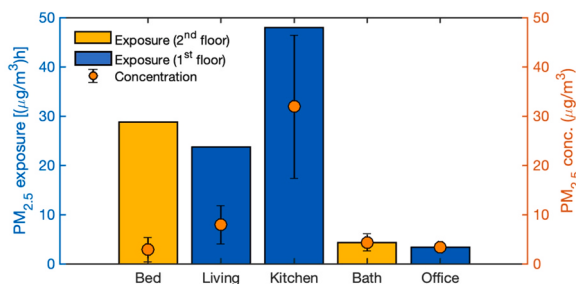


Fig. 9. PM_{2.5} exposure (bars, left axis) and mean PM_{2.5} concentration (dots, right axis) for a typical day. The first-floor bedroom is listed here as the home office. Locations on the first floor are shown in blue bars and those on the second floor are shown in yellow bars (bed = main bedroom, bath = second floor bathroom). Error bars represent the standard deviation in PM_{2.5} concentration values and scale linearly for exposure values (not shown).

CRediT authorship contribution statement

Stephen M. Zimmerman: Writing – original draft, Visualization, Formal analysis. **Andrew B. Martin:** Writing – original draft, Methodology, Investigation, Formal analysis, Data curation. **Liora E. Mael:** Investigation, Data curation. **Delphine K. Farmer:** Supervision, Resources, Project administration, Investigation, Conceptualization. **Dustin Poppendieck:** Writing – review & editing, Supervision, Resources, Investigation. **Marina E. Vance:** Writing – review & editing, Writing – original draft, Visualization, Supervision, Resources, Project administration, Methodology, Funding acquisition, Formal analysis, Data curation, Conceptualization.

Declaration of Competing Interest

The authors declare the following financial interests/personal relationships which may be considered as potential competing interests: Marina Eller Vance reports financial support was provided by Alfred P Sloan Foundation. If there are other authors, they declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper

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Disclaimer

Certain equipment, instruments, software, or materials are identified in this paper in order to specify the experimental procedure adequately. Such identification is not intended to imply recommendation or endorsement of any product or service by NIST, nor is it intended to imply that the materials or equipment identified are necessarily the best available for the purpose. The policy of NIST is to use the International System of Units in all publications. In this document, however, some units are presented in the system prevalent in the relevant discipline.

Supplementary materials

Additional figures, tables, and text describing the indoor environmental conditions during the study period, sensor locations, modeling conditions, equations, and assumptions, and supplementary result figures.

Appendix A. Supporting information

Supplementary data associated with this article can be found in the online version at [doi:10.1016/j.indenv.2025.100126](https://doi.org/10.1016/j.indenv.2025.100126).

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