

# Measuring social consensus

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## Abstract

Many organizations describe their processes as consensus-driven, but there is no consensus on the definition of consensus. Qualitative definitions of consensus prioritize social phenomena like “unity” that are not necessarily measurable. Quantitative definitions of consensus derive from numbers of votes and can be realized in software. When unity and cooperation become unobtainable for any reason, measuring consensus as a quantity (an amount of agreement) is a reasonable adaptation to alleviate gridlock and possibly avoid escalation of conflicts. This article investigates the metrology of social consensus.

## 1 Introduction

The first principle of republicanism is that the *lex majoris partis* is the fundamental law of every society of individuals of equal rights: to consider the will of the society enounced by the majority of a single vote as sacred as if unanimous, is the first of all lessons in importance, yet the last which is thoroughly learnt. This law once disregarded, no other remains but that of force, which ends necessarily in military despotism. [1]

Consensus is a Latin word. Its primary definition in the *Thesaurus linguae Latinae* is “*concordia, conventientia, assensus*” [2, defn. I]—concord, agreement, assent. In etymology of the English word, the *Oxford English Dictionary* describes the Latin word as “agreement, accord, unanimity, concord, harmony, sympathy” [3].

In modern practice it has come to mean different things. Some forms of consensus can be assessed only qualitatively, such as the overall sentiment that a group leader must articulate in order to maintain the group’s cohesion. Other forms of consensus can be measured by voting, albeit with limitations that are a characteristic of all voting methods.

When questions become politicized and cooperation breaks down, qualitative assessments of consensus can face direct challenge from those who feel they are on the losing end of a decision. What does one do in these situations? War, whether political, procedural, legal, or total, is always a threat. But one action that may avert war is to *measure* the consensus so that those on the losing end are faced with empirical evidence that they have little support.

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The path to reliable measurements begins with qualitative concepts like *hot* and *cold*. Through a process of refinement and compromise, eventually qualitative concepts are replaced by a quantity (thermodynamic temperature in this example). A measurement method is then devised that, through a similar process of refinement and compromise, is made repeatable, reproducible, and objective. Fitness for purpose is not guaranteed; e.g., setting a particular air temperature does not necessarily achieve the goal of making a person feel neither hot nor cold. But if the resulting quantity and measurement method serve the purposes of the original qualitative concepts, they can then replace them and, thus, remove subjectivity from an assessment.

Qualitative and quantitative forms of consensus fit into this story. Consensus as a quantity would be an amount of agreement, for which voting is a measurement method. The goal is then to refine consensus to something that can be evaluated in a repeatable and reproducible process that can be automated, factoring out the qualitative, social, and emotional aspects that are subjective—but also to remain aware of the compromises made and fitness for the original purposes.

This article investigates the nature and limitations of the measurement model of consensus. The remainder proceeds as follows. [Section 2](#) looks at qualitative definitions of consensus and characterization methods. [Section 3](#) proceeds to quantitative definitions and methods. [Section 4](#) describes different measurement scenarios and process concerns. [Section 5](#) addresses uncertainty for those measurements. [Section 6](#) briefly describes other uses of consensus. Finally, [Section 7](#) gives conclusions.

## 2 Qualitative consensus

### 2.1 Definitions

Qualitative definitions of consensus are those that cannot be realized by an algorithm. They prioritize social phenomena like “unity” or the mood of the crowd that are not necessarily measurable by counting votes and might even be undermined by the process of voting.

The phrase “unity, not unanimity” appears in many contexts where group cohesion is essential to effective leadership. Nevertheless, it remains the case that one active dissenter is all it takes to *block* agreement—the same as if an explicit unanimous vote were required.

Randy Schutt writes: “Consensus is a process for deciding what is best for a **group**. The final decision is often not the first preference of any individual in the group, and many may not even like the final result. But it is a decision to which they all **consent** because they know it is the best one for the group.” This form of consensus “is a process for people who want to work together honestly in good faith to find good solutions for the group. It cannot be used by people who do not, can not, or will not cooperate” [4].

The Common Wheel Collective explains:

Consensus is not just the end result of the group’s decision-making process, or the part where a vote is taken and the vote is unanimous, barring any blocks or stand-asides. The consensus process has to be built into the entire structure of the group or organization and form the basis for all of its activities and basic operation. This is true for all egalitarian collectives, even those who accept some form of majority vote in their decision-making and may therefore not strictly be defined as operating by consensus. [5]

The Internet Engineering Task Force (IETF) guidelines and procedures state, “IETF consensus does not require that all participants agree although this is, of course, preferred. In general, the dominant view of the working group shall prevail. (However, it must be noted that ‘dominance’ is not to be determined on the basis of volume or persistence, but rather a more general sense of agreement)” [6, §3.3].

The directives of the International Organization for Standardization (ISO) and International Electrotechnical Commission (IEC) define consensus as “General agreement, characterized by the absence of sustained opposition to substantial issues by any important part of the concerned interests and by a process that involves seeking to take into account the views of all parties concerned and to reconcile any conflicting arguments. NOTE Consensus need not imply unanimity” [7, §2.5.6].

Andersson et al. did a case study of ISO information security standard development from the perspective of the Swedish Institute for Standards technical committee TC318 and found that, while consensus discourse (“focusing on participation and consensus-making, such as ‘discuss’ and ‘harmonize’”) could be distinguished from warfare discourse (“military metaphors such as ‘put pressure on,’ ‘guard,’ and ‘monitor’”), most participants were silent and passive either way (cf. “passive non-resistance” in [Section 3.1.2](#)) [8]:

Choosing concepts such as resistance in a definition of consensus clearly shows how the warfare discourse interacts with, and influences, the consensus discourse. This interaction between the two discourses also makes the definition vague and ambiguous, leaving much room for interpretation; for example: What is an absence of strong resistance? How strong is strong? What are the important subject matters? ... This example shows that even though the consensus discourse was heavily emphasized and communicated to the TC318 members, in practice, this was not the way de jure information security standards were developed. Instead, these best practices were developed by a relatively small group of active members who took it upon themselves to interpret when resistance to a proposal was too strong or was made by an important stakeholder.

Although the “unity, not unanimity” process of consensus is sometimes attributed to the meeting practices of Quakers, a current Quaker book of discipline states “We are not seeking a consensus; we are seeking the will of God” [9, §2.89].

## 2.2 Contrast with gatekeeping

With consensus, a whole group speaks with one voice. With gatekeeping, dissenting voices are suppressed so that only one voice can be heard.

If the decision of a deliberative body is subject to arbitrary nullification, the arbiter can keep rejecting decisions until the deliberative body delivers what they want. The deliberative body then serves no purpose but to launder the will of the arbiter as their own putative consensus.

There can be no meaningful consensus when there is such an imbalance of power that consent can be manufactured or compelled, where one party needs the consent of the other, but the reverse isn’t true.

These situations call into question the definition of consent itself, which has been litigated to different conclusions in different jurisdictions. For example, in the United States, it is standard procedure for government systems to present a dialog to government employees stating, “You understand and consent to the following: ...” from which the only way to proceed is to click a button labelled “Accept.” But in the European Union, consent under such conditions is invalid [10]:

The employer-employee situation is generally considered as an imbalanced relationship in which the employer wields more power than the employee. Since consent has to be freely given, and in light of the imbalanced relationship, your employer in most cases can't rely on your consent to use your data.

### 2.3 Qualitative methods of characterizing consensus

Where a qualitative definition of consensus is used, someone is the final arbiter of consensus. It is a case of expert judgment substituting for measurement.

IETF: "Consensus can be determined by a show of hands, humming, or any other means on which the WG agrees (by rough consensus, of course). Note that 51% of the working group does not qualify as 'rough consensus' and 99% is better than rough. It is up to the Chair to determine if rough consensus has been reached" [6, §3.3]. RFC 7282, which is informational and does not overrule the preceding text from RFC 2418, argues that the determinant of rough consensus is the soundness of the technical case, not the number of votes for or against [11]. "One hundred people for and five people against might not be rough consensus" and "Five people for and one hundred people against might still be rough consensus" are section titles.

ISO/IEC: "If the leadership determines that there is a sustained opposition, it is required to try and resolve it in good faith. However, a sustained opposition is not akin to a right to veto. The obligation to address the sustained oppositions does not imply an obligation to resolve them successfully. ... The responsibility for assessing whether or not a consensus has been reached rests entirely with the leadership" [7, §2.5.6].

Hand signals used in street protests lack standardization but may be more expressive of individual sentiment than formal voting; e.g., an ordinal scale consisting of *agree*, *don't agree*, *oppose*, and *block* instead of simply yes or no [12].

### 2.4 Vulnerabilities

Tactics used to wreck a consensus process include fraud, obstruction, obfuscation, disinformation, flooding (exhausting the group with endless, repetitive arguments), intimidation, and politicizing the question in terms of a manufactured or exaggerated enemy. See also the "Ploys to subvert consensus" chapter of [5].

In groups using a qualitative definition of consensus, when a single member chooses to obstruct the work of the group, the onus falls on the leadership to resolve the problem.

IETF: "While open discussion and contribution is essential to working group success, the Chair is responsible for ensuring forward progress. When acceptable to the WG, the Chair may call for restricted participation (but not restricted attendance!) at IETF working group sessions for the purpose of achieving progress. The Working Group Chair then has the authority to refuse to grant the floor to any individual who is unprepared or otherwise covering inappropriate material, or who, in the opinion of the Chair is disrupting the WG process. The Chair should consult with the Area Director(s) if the individual persists in disruptive behavior" [6, §3.2]. Procedures for mailing list suspension were added in [13].

## 3 Quantifying consensus

### 3.1 Definitions

#### 3.1.1 General

Quantitative definitions of consensus are those that are realizable in an algorithmic sense. They depend only on counts, amounts, and proportions, not on expert judgment or the mood of a crowd.

Voting can be thought of not merely as a process for decision-making but as the measurement method for a quantity called consensus. From this viewpoint, the vote is a dimensionless unit of measurement. Once votes for each choice have been counted, the result of the measurement can be expressed in various ways:

- As the number of votes for each choice (a count);
- As the proportion of the total number of votes that each choice received *or* the proportion of voters who voted for each choice (ratios);
- As an ordinal ranking of choices by the number of votes received;
- As a reduction to a dichotomic scale (e.g., a [sufficient] consensus does or does not exist). Any ratio measurement can be reduced to a dichotomic scale by applying a threshold.

None of these results is inextricably bound to the making of a particular decision. The results of measurements, including measurements of consensus, are used to drive decisions, but the decision rules are separate from the measurement. Measurements provide data that can be used to inform decisions or upon which a data-driven policy can be implemented. A decision might be required regardless of whether a consensus exists or is measurable.

That being said, the difference between the following two descriptions usually reduces to semantics:

1. Consensus is measured as a count, amount, or proportion. Because this quantity exceeds a threshold, the decision is made that a motion passes. In pseudocode:

```
Number Consensus1 = Measurement1() # Measurement
if Consensus1 > Threshold           # Condition
    motion passed                    # Decision
```

2. Consensus is measured on a dichotomic scale (there is or is not a consensus). Because there is a consensus, the decision is made that a motion passes. In pseudocode:

```
Boolean Consensus2 = Measurement2() # Measurement
if Consensus2       # Condition
    motion passed   # Decision
```

If the dichotomic Consensus2 in description 2 is reduced from the count, amount, or proportion that was used in description 1—that is to say, if Measurement2 has the following pseudocode definition—then the behavior is unchanged, and the only difference is that the thresholding operation was moved from the decision rule into the measurement:

```
Boolean function Measurement2 = (Measurement1() > Threshold)
```

But description 2 does not exclude the possibility that a dichotomic result could be arrived at through a significantly different process.

If the population is evenly divided between two candidates in an election for public office or if no choice is supported by a majority, there is no consensus by any definition. Voting reveals the absence of consensus

in these cases. But the decision rules given by election law in practice will pick a winner arbitrarily—sometimes literally by coin toss—rather than leave an office vacant.

### 3.1.2 Unanimity

Unanimity is obviously measurable as it entails the consent of every member of the population. There is no wiggle room on the unanimous part; there is only variation in what constitutes consent.

The Oxford English Dictionary defines consensus (the most relevant sense) as “Agreement in opinion, feeling, or purpose among a group of people, esp. in the context of decision-making. Also: the collective unanimous opinion of a number of people” [3, defn. 1.a].

When consensus is defined as unanimity, a defender of the status quo has the power of a dictator. Opposition can be sustained indefinitely by any member who simply refuses to stop objecting. Reconciliation can be prevented indefinitely by any member who simply refuses to accept any offered compromise. A single member who is willing to sustain objection can say “my way or the highway.” The result is an imbalance of power in favor of vested interests (preservation of the status quo).

The Group of 20 (G20) uses consensus = unanimity: “All votes regarding the report will proceed as a consensus form which means, one ‘Against’ vote can make [does make] the report fail” [14].

The European Parliament uses consensus = unanimity, but there is a movement to lower the threshold for many actions [15].

The World Intellectual Property Organization (WIPO) has been requiring unanimity for accreditation of observers, but this is not traceable to its documented rules of procedure [16, 17].

In some collaborative and decision-making bodies, consensus means *unanimous consent*, which is a term of art for a particular procedural shortcut in which any who are opposed to the question are given the opportunity to let it pass without objection. Under Robert’s Rules [18], a motion can pass by unanimous consent with only passive silence from the majority of members; in other words, silence implies consent.

The circumstantial difference between explicitly voting for something and merely remaining silent when unanimous consent is called for is one basis for claims that consensus is different than unanimous support. It boils down to where on the scale between enthusiastic, active support and detached, passive non-resistance the threshold of individual consent resides. It also gives rise to the Abilene paradox, wherein the ostensible consensus is not actually supported by any member of the group [19].

### 3.1.3 Unanimity minus a constant

The variation in which there is a fixed threshold for the number of dissenting votes that is deemed compatible with consensus is documented in Wikipedia [20]. Although it is a logical mitigation to the worst pathologies of requiring unanimity, we have not found a definitive example of its use in practice. Without citation, Wikipedia alleges its use in larger Masonic lodges: “Whilst in many such cases even a single black ball will be fatal to the candidate’s election, rules in larger clubs ensure that a single member cannot exercise a veto to the detriment of the future of the club. For example, two black balls are required to exclude...” [21].

### 3.1.4 Supermajority proportion

Consensus might be defined as the agreement of a supermajority such as  $\frac{3}{5}$ ,  $\frac{2}{3}$ , or  $\frac{3}{4}$  of the population. Although decisions are made and public offices filled based on  $\frac{1}{2}$  of the population or less, such proportions are not regarded as indicating consensus.

IETF uses a definition of “rough consensus” that is mostly qualitative, but there is a note that “51% of the working group does not qualify as ‘rough consensus’ and 99% is better than rough” [6, §3.3].

An amendment to the U.S. constitution must be ratified by  $\frac{3}{4}$  of the states.

## 3.2 Quantitative methods of characterizing consensus

In the following subsections we focus on common voting methods that can be adapted to the measurement point of view.

### 3.2.1 Simple example

This section describes a measurement of consensus on a yes-or-no question using a minimum number of votes as the quorum and a supermajority of votes as the threshold for a decision. Since quorum is determined from the number of votes, abstentions (present but not voting) have no impact in this example.

Assume that the following values are given:

- $V_Y$  Number of votes *in favor of* the proposition (“yes votes”)
- $V_N$  Number of votes *against* the proposition (“no votes”)
- $T$  Consensus threshold,  $\frac{1}{2} < T \leq 1$
- $Q$  Number of votes required for quorum,  $Q \geq 1$

The measure of consensus is the proportion of votes in favor,  $p = V_Y / (V_Y + V_N)$ . This measure is reduced to a dichotomic scale (consensus does or does not exist) by the following decision rules, which furthermore associate the consensus (if it exists) with a particular outcome:

Condition	Decision
$V_Y + V_N \geq Q$ and $p \geq T$	A consensus exists <i>in favor of</i> the proposition.
$V_Y + V_N \geq Q$ and $(1 - T) < p < T$	Negative result. There is evidence of the absence of consensus.
$V_Y + V_N \geq Q$ and $p \leq (1 - T)$	A consensus exists <i>in opposition to</i> the proposition.
$V_Y + V_N < Q$	Null result. There is an absence of evidence.

### 3.2.2 Elaborated model for yes-or-no questions

To handle other methods of voting on yes-or-no questions, we introduce another parameter,  $P$ , the effective population size. It can be set at one of four levels:  $P(1)$ , the nominal size of the voting body;  $P(2)$ , the current size of the voting body with vacant positions excluded;  $P(3)$ , the number of members present at the time of voting; or  $P(4)$ , the number of members that did not abstain.

A quorum can be defined as either (1) a minimum number of members that must be present at the time of voting or (2) a minimum number of members that must not abstain. However, in any event, at least one member must vote for there to be a quorum: complete absence of evidence supports only a null result.

If the voting body does not have defined membership, P(1) and P(2) are not applicable. If abstentions are not counted, P(3) and quorum type (1) are not applicable.

Quorum type (1) can be specified as a constant or it can be derived as a proportion of P(1) or P(2). In contrast, quorum type (2) can be specified as a constant or it can be derived as a proportion of P(1), P(2), or P(3). [Table 1](#) shows why certain combinations of P's and Q's are not valid. Note that the effective population size used for quorum purposes need not be the same as is used for determining consensus.

To cover all cases, we reformulate the model in terms of three logical propositions:

- $q$  Quorum is met
- $t_a$  Threshold of consensus is met for acceptance
- $t_r$  Threshold of consensus is met for rejection

Retaining these definitions from [Section 3.2.1](#):

- $V_Y$  Number of votes *in favor of* the proposition (“yes votes”)
- $V_N$  Number of votes *against* the proposition (“no votes”)

The generalized threshold expressed in terms of  $P$  (however  $P$  is defined for consensus purposes) can be a simple majority, a supermajority, near-unanimity (unanimity minus a constant, see [Section 3.1.3](#)), or unanimity. If supermajority is used, we need:

- $T$  Threshold for a supermajority as a proportion of  $P$ ,  $\frac{1}{2} < T \leq 1$

But if near-unanimity is used, we instead need:

- $C$  Tolerated shortfall in votes from unanimity,  $0 \leq C < \frac{1}{2}P$

The value of  $T$  or  $C$  would typically be fixed by voting rules while the value of  $P$  may vary. The situation where  $P$  becomes so small that the constraint  $C < \frac{1}{2}P$  is violated must be avoided through appropriate choices of  $P$  and  $Q$  or by reducing  $C$  in this special case.

Unanimity is the limiting case for both supermajority with  $T = 1$  and near-unanimity with  $C = 0$ :

Threshold	$t_a$ criterion	$t_r$ criterion
Majority	$V_Y > \frac{1}{2}P$	$V_N > \frac{1}{2}P$
Supermajority	$V_Y \geq TP$	$V_N \geq TP$
Near-unanimity	$V_Y \geq P - C$	$V_N \geq P - C$
Unanimity	$V_Y = P$	$V_N = P$

The decision rules then become (with  $\wedge$ ,  $\vee$ , and  $\neg$  indicating logical conjunction, disjunction, and negation, respectively):

Condition	Decision
$q \wedge t_a$	A consensus exists <i>in favor of</i> the proposition.
$q \wedge \neg(t_a \vee t_r)$	Negative result. There is evidence of the absence of consensus.
$q \wedge t_r$	A consensus exists <i>in opposition to</i> the proposition.
$\neg q$	Null result. There is an absence of evidence.

If P(1), P(2), or P(3) is used as the effective population size for determining consensus, abstaining has the same impact as voting no. But if P(4) is used, only no-votes count against consensus.



Table 1: Interactions between definitions of effective population size and quorum.

Specification of quorum	Quorum type (1), a minimum number of members that must be present at the time of voting	Quorum type (2), a minimum number of members that must not abstain
Constant	Valid	Valid
Proportion of P(1), the nominal size of the voting body	Valid	Valid
Proportion of P(2), the current size of the voting body with vacant positions excluded	Valid	Valid
Proportion of P(3), the number of members present at the time of voting	Invalid: proportion of members present that must be present	Valid
Proportion of P(4), the number of members that did not abstain	Invalid: proportion of members that did not abstain that must be present	Invalid: proportion of members that did not abstain that must not abstain

### 3.2.3 Extended to 1-of-M contests

A yes-or-no question is a contest between two exclusive choices. We now consider the case where there are two or more choices, but only one can be chosen. In some voting terminology these are called 1-of-M contests [22].

However many choices the contest has, it is possible for the choice that receives the most votes to satisfy one of the thresholds listed in Section 3.2.2. We need only adjust the model to allow for an arbitrary number of choices. On the other hand, it is impossible to conclude from votes in favor of various choices that they were voting *against* the others, so the criteria of rejection for yes-or-no questions do not generalize to 1-of-M contests.

The logical propositions:

- $q$  Quorum is met
- $t_i$  Threshold of consensus is met for choice  $i$

The measurables:

- $V_i$  Number of votes for choice  $i$

The thresholds:

Threshold	$t_i$ criterion
Majority	$V_i > \frac{1}{2}P$
Supermajority	$V_i \geq TP$
Near-unanimity	$V_i \geq P - C$
Unanimity	$V_i = P$

The decision rules:

Condition	Decision
$q \wedge t_i$	A consensus exists <i>in favor of</i> choice $i$ .
$q \wedge \neg(\bigvee t_x)$	Negative result. There is evidence of the absence of consensus.
$\neg q$	Null result. There is an absence of evidence.

When  $M = 2$ , the logic is similar to that of a yes-or-no question, but the format is different. The choices usually are candidates for office.

### 3.2.4 N-of-M contests

We now consider the case where there are two or more choices and two or more can be chosen. In some voting terminology these are called N-of-M contests [22]. The ballot instructions would typically say “Vote for at most  $N$ ” substituting the specific number for  $N$ .

In public elections that require only a plurality, it is trivial to change the decision rules to fill  $N$  offices. One merely moves the line downward to elect the top  $N$  candidates:

Candidate	Votes
Montego Placeholder	90 785
Random Incumbent	69 212
Emilia Somebody	49 086
Ace Fakename	46 995
Known Character	28 479
Perennial Favorite	5 662

Applying the criteria given in [Section 3.2.3](#), all, one, or none of the elected candidates might satisfy a consensus threshold by themselves. But looking at the slate that was elected as a group, it is not necessarily the case that any cast ballot included votes for that exact slate, that a supermajority would prefer it to any other combination, or that the slate elected is a rational choice for a cohesive team. So, it is easy to identify “consensus candidates” from the individual tallies, but to identify a “consensus slate” if one exists requires tabulation by slate (the power set of the set of candidates) rather than by individual candidate.

### 3.2.5 Ranked order voting

Some public elections have voters rank choices in order of preference. In these cases, the vote as a unit does not arise until the tallying stage, at which point the process begins by counting the number of ballots that ranked each choice first. As the process continues, if a choice is eliminated, the votes for that choice are effectively transferred to the next choice in order of preference for each ballot.

If ranked order voting is used, the criteria given in [Section 3.2.3](#) can be applied to the counts derived from the most preferred choice of every ballot in the first round of tabulation. But if a winner is not selected in the first round, it is fair to say that there is no consensus. The ultimate selection will be an explainable compromise but not a consensus choice.

### 3.3 Limits of validity

#### 3.3.1 Representation of voter intent

An accurately recorded vote tells you that someone voted that way. It does not tell you why they did. There are many additional levels of validity that one can ask for; e.g.:

- The vote must be *intentional*, i.e., not an accidental miscasting caused by misunderstanding the ballot or pressing the wrong button.
- The vote must be *informed*, i.e., not swayed by disinformation or ignorance.
- The vote must be *voluntary*, i.e., not swayed by coercion, pressure, or meddling of any kind.
- The vote must be *responsible*, i.e., not an arbitrary or capricious choice.
- The vote must be *intelligent*, i.e., not based on faulty reasoning.
- The vote must be *sincere*, i.e., not a “strategic vote.”

No democratic voting process can ensure a valid result when over half of voters are casting votes that are compromised in one of the aforementioned senses.

These additional conditions fundamentally change the problem from a classical, physical measurement to one that is better approached with the methods of social science. There is a great deal of experience that can be applied if the time and resources are available. In practice, the applicable laws, rules, and procedures determine how (or whether) these additional conditions are addressed, and the variability is enormous.

#### 3.3.2 Impossibility theorems

A series of formal results [23, 24, 25, 26, 27] has shown that no voting method within broad classes of voting methods can satisfy every criterion that one would want. This means that every member of some set of pathologies cannot simultaneously be prevented.

Undesirable properties that voting methods can have include:

- The result can be determined by a single voter (a dictator) regardless of how others vote
- The result can be option  $Y$  even though every voter prefers  $X$  to  $Y$
- A decision between  $X$  and  $Y$  can be influenced by factors other than the voters’ rankings of  $X$  and  $Y$  relative to each other
- The most effective way of voting to obtain a desired result is to vote insincerely for something else (“strategic voting”)

Every voting method exhibits some pathology when the best result is not obvious. Fortunately, the goal of measuring consensus is not to decide a winner in every circumstance but to determine whether circumstances indicate a clear winner.

#### 3.3.3 Danger of surrogate measurement

The existence of both quantitative and qualitative definitions of consensus suggests that the quantities could be regarded as *surrogate measures* for the unmeasurable qualities. The meaning and ramifications of surrogate measures are explained by the following two quotations, which were found via [28]:

Many of the attributes we wish to study do not have generally agreed methods of measurement. To overcome the lack of a measure for an attribute, some factor which can be measured is used instead. This alternate measure is presumed to be related to the actual attribute with which the study is concerned. These alternate measures are called surrogate measures. [29]

It is usual that once a scale of measurement is established for a quality, the concept of the quality is altered to coincide with the scale of measurement. The danger is that the adoption in science of a well defined and restricted meaning for a quality... may deprive us of useful insight which the common natural language use of the word gives us. [30]

When surrogacy goes awry, we are left with an instance of the streetlight effect, also known as the lamppost problem: we are measuring a given quantity not because it is what we were looking for but because it is what we know how to quantify (it is where the light is).

## 4 Measurement

### 4.1 Scenarios

Consensus is needed in different situations and is transformed by the information available, the constraints on measurement, and the possible outcomes of those situations. The most relevant scenarios are described in the following subsections.

#### 4.1.1 Public elections

Public elections are a form of social choice with the following distinct characteristics:

- The voting population is large enough to make the measurement nontrivial
- There is no quorum
- Ballot secrecy complicates validation and verification
- Votes are held infrequently and at significant cost
- Contests are to choose one or more candidates from a slate of candidates, optionally followed by yes-or-no ballot questions
- The contests, questions, and election process are fixed in advance through a legal process
- Certain tactics for subverting a valid consensus, such as disinformation and politicizing a question (see [Section 2.4](#)), are tolerated

#### 4.1.2 Agreement of a committee or group

Agreement of a committee or group, including both organized meetings with defined membership and ad hoc gatherings without defined membership, is a form of social choice with the following distinct characteristics:

- The voting population is small enough to eliminate many sources of uncertainty
- A particular quorum is usually required
- Ballot secrecy is rarely required
- Votes can be held more frequently with less overhead
- Most contests are yes-or-no questions

- The questions are put forward by the same group and can be amended
- The population has more power to change the process
- Wrecking tactics may be subject to disciplinary action

#### 4.1.3 Polls on social media

Social media platforms including Mastodon, X, and Facebook<sup>1</sup> support polls with the following distinct characteristics:

- Except for polls in closed groups, the size of the voting population is unpredictable—polls can go viral
- There is no quorum
- Ballot secrecy is optional and varies by platform
- Polls can be created at will by anyone at virtually no cost
- Contest types are limited by the platform
- The barrier to voting multiple times using different accounts is low to nonexistent, so the process is not appropriate for high-stakes decisions

For example, in Mastodon version 4.2.10, polls have the following limitations:

- The supported contest types are 1-of-M and M-of-M (i.e., N-of-M where  $N = M$ ; all choices may be selected simultaneously)
- The number of choices is limited to 4 (configurable in the [glitch-soc fork](#))
- Closed groups are not yet supported except by controlling access to the whole Mastodon server
- No write-ins—additional options are customarily suggested in replies but are not measured as part of the poll
- No counting of abstentions

Closed groups, abstentions, and additional contest types have been requested (see issues [#19059](#), [#19952](#), [#20519](#), [#23295](#), and [#25339](#)), but their implementation will or would require changes to the many client apps as well as to the database schema and server.

## 4.2 Preconditions and process control

The context and procedures that apply to a measurement of consensus can affect the validity of the measurement both in terms of the values obtained and in terms of their fitness for purpose. As with any measurement, it is necessary for confounding factors to be under control.

### 4.2.1 Ensuring fair ballot access

Ballot access refers to the ability for all relevant options to be presented to voters. In public elections, there are criteria and procedures in election law that limit which candidates or issues are listed on the ballot. In committee or group votes, the applicable rules limit which questions can get on the agenda and be brought up for vote.

We can identify two different levels at which consensus can operate. The first is the level of an individual question that is put to a vote. The second is the level of the overall business or goals of the group or

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<sup>1</sup>Commercial entities or products are identified in order to describe a measurement concept adequately. Such identification does not imply recommendation or endorsement by the National Institute of Standards and Technology, nor does it imply that the entities or products are necessarily the best available for the purpose.

population that is voting. Accurate measurement of consensus at the first level is necessary but insufficient. If the options that are actually most preferred are not on the ballot, you can measure consensus on the question presented, but it is still the wrong question.

A consensus that  $X$  is better than  $Y$  does not imply that there is a consensus in favor of  $X$ .  $X$  might have lost to a third option  $Z$  or to “none of the above” if these options had been offered. Similarly, a lack of support for any choice offered in the slate of options for moving forward does not imply that there is a consensus in favor of maintaining the status quo.

Given control of the ballot and some not very restrictive conditions, the McKelvey–Schiefelbusch theorem shows that choices made by majority vote can be forced arbitrarily far away from the preferences of a population by playing subpopulations against one another in successive polls [31, 32].

Biased control of the agenda and the ballot is thus incompatible with valid measurement of consensus.

#### 4.2.2 Mitigating obstruction

If unanimous support is not a prerequisite for consensus, it is necessary to define procedurally how a single member who chooses to obstruct the work of a group can be overruled in a fair and orderly fashion. This is straightforward when consensus is measured through voting—just use a threshold that is less than unanimity. However, obstruction can occur through means other than the exercise of an individual vote, e.g., quorum-busting [33, 34], which may require more extensive procedural mitigations.

#### 4.2.3 Avoiding sequential voting pathologies

In organized meetings, when a choice must be made among exclusive options, house rules often force the contest to be broken into a sequence of yes-or-no votes on the individual options. This results in a number of serious pathologies, which are described briefly in the following paragraphs. When options are exclusive, it is better to design a single contest that allows a direct choice among them.

**Conflicting choices.** A consensus can exist in support of two or more exclusive options. If consensus was measured on a dichotomous scale, we can go no farther than demonstrating that this situation exists. If ordinal or ratio scales were used, we can compare the results to possibly determine which consensus is stronger.

**Suboptimal choice.** If the decision is made as soon as any of the options receives a passing result, the process is biased in favor of whichever options are offered earlier in the order of voting. This follows directly from the possibility of two or more of the options each having adequate support.

If the full list of options to be considered is not made available to the group before the start of sequential voting, we have an instance of the secretary problem [35]. At each step, the group is faced with the dilemma of settling for the choice before them or rejecting it in hopes that something better will be offered. If there is one option that would unambiguously be the group’s favorite (a strong Condorcet winner), the probability of it being chosen by this process is less than half.

**Default.** The result of sequential voting can be the group rejecting every option and defaulting on its obligation to choose among them. When all of the options are unpopular, despite there being no alternatives or better ideas on offer, sequential voting leads to paralysis.

### 4.3 Example implementation of decision rules

The decision rules for consensus with the contest types described in [Section 3.2](#) have been implemented in a Ruby module named `ConsensusMeasurement`. It includes only the logic for evaluating consensus given the parameters discussed in [Section 3.2](#), not the collection and tabulation of ballots and votes.

The module and its associated test cases are available as a separate distribution [36]. The following excerpted comments and method signatures describe the implementation and the adaptations made.

The simple model of [Section 3.2.1](#) is implemented in a single method:

```
# Measurement of consensus on a yes-or-no question using a supermajority of
# votes as the threshold
# quorum          Integer ≥ 1
# votes_y and votes_n Integer ≥ 0
# threshold       Rational 1/2 < T ≤ 1
# Returns :negative_result, :null_result, :accepted, or :rejected.
def self.question_simple(quorum, votes_y, votes_n, threshold)
```

The methods for the elaborated model don't take the nominal or current size of the voting body as parameters. If the quorum is specified as a proportion of P(1) or P(2), the caller must reduce it to the number of members and specify `quorum_type :num_present` or `:num_voting` as applicable. For example, if quorum is defined as  $\frac{1}{3}$  of P, `Rational(P,3).ceil` should be passed as the value for quorum.

The remaining option is quorum type (2) defined as a proportion of P(3). This is supported by specifying `quorum_type :proportion_voting` and passing the proportion as a Rational value for quorum.

Thus, the parameters related to the determination of quorum are:

```
quorum_type      :num_present, :num_voting, or :proportion_voting
quorum           Integer ≥ 1 (:num_present and :num_voting)
                 Rational, 0 < proportion ≤ 1 (:proportion_voting)
present and voting Integer ≥ 0, present ≥ voting
```

All options for determining consensus are supported by the following parameters:

```
population       Integer P ≥ 0
threshold_type   :majority, :supermajority, :near_unanimity, or :unanimity
threshold        For :near_unanimity, Integer 0 ≤ C < P/2
                 For :supermajority, Rational  $\frac{1}{2}$  < T ≤ 1
                 Optional and ignored for :majority and :unanimity
```

```
# Determine whether quorum is met
# Parameters as described in the notes above
# Returns boolean
def self.quorate?(quorum_type, quorum, present, voting)

# Evaluate threshold of consensus for a particular choice
# votes Integer ≥ 0
# Other parameters as described in the notes above
# Returns boolean
def self.consensus?(votes, population, threshold_type, threshold=nil)
```

```

# Elaborated yes-or-no question
# votes_y and votes_n Integer ≥ 0
# Other parameters as described in the notes above
# Returns :negative_result, :null_result, :accepted, or :rejected
def self.question(quorum_type, quorum, present, votes_y, votes_n, population,
                 threshold_type, threshold=nil)

# N-of-M contest
# (For 1-of-M, see one_of_m below)
# votes Array of Integer ≥ 0 totalling at most N × voting
# Other parameters as described in the notes above
#
# Returns :negative_result, :null_result, or an array of indices of the
# choices in array votes that passed the threshold of consensus by
# themselves. No attempt is made to identify a consensus slate if one
# exists; only the individual choices are evaluated.
def self.n_of_m(quorum_type, quorum, present, voting, votes, population,
               threshold_type, threshold=nil)

# 1-of-M contest
# Mostly the same as n_of_m, but with the following simplifications for N=1:
# - Parameter voting is removed since it must equal votes.sum
# - Returns :negative_result, :null_result, or the index of the choice in
# array votes that passed the threshold of consensus
def self.one_of_m(quorum_type, quorum, present, votes, population,
                 threshold_type, threshold=nil)

```

In addition to basic type and range checks on inputs, various additional constraints are enforced where feasible given the data provided to the different methods:

quorate?

- Number voting must not exceed number present

consensus?

- Number of votes must not exceed size of population

question

- Number of votes must not exceed number present
- Number of votes must not exceed size of population

n\_of\_m

- Number voting must not exceed number present
- Number voting must not exceed size of population
- Number voting must not exceed number of votes
- Number of votes must not exceed M times number voting\*

one\_of\_m invokes n\_of\_m with number voting = number of votes.

\* Since N is not a parameter, the burden is partly on the caller to ensure that the number of votes represented in the array votes is no greater than N times the number voting. The function consensus? will throw an exception if any element of the array exceeds population. n\_of\_m checks the upper bound  $N = M$ .



The value of present (used for quorum) can exceed the value of population (used for consensus) when P(4) the number of members that did not abstain is used as the effective population size for determination of consensus.

## 5 Uncertainty

### 5.1 General

Uncertainty is part of all elections and consensus processes. As Bunnett wrote in the aftermath of the 2000 U.S. presidential election, “The uncertainty of measurement is much greater than one vote. ... Scientific realities are widely recognized in other aspects of our lives, so why not in something so fundamental to the United States as the election process?” [37]

One might set a goal of producing vote counts *with uncertainty intervals* for particular choices. Given various inputs both actual and assumed, one could calculate these. But the subsequent application of decision rules to create sharp boundaries militates against a rational treatment of uncertainty. To say that a decision is mandatory is to concede that you will accept an arbitrary decision. Even if there were no uncertainty about the counts, a tied result would not support the making of a decision. Uncertainty intervals increase the number of situations in which we consider counts to be effectively equal, where there is little or no confidence in a finding that one is greater than the other.

Several different sources of uncertainty may apply:

- When the number of votes is less than the population size, whether due to abstentions or to limited enfranchisement, there is sampling uncertainty in treating the consensus of voters as the consensus of the population. It is not a given that the sense of the non-voting subpopulation is relevant to the question, as the next section will further explain, but one cannot legitimately claim to have evidence of consensus if the poll was widely boycotted.
- There is the possibility that the votes cast by individuals were not what they intended or would have intended in the absence of confounding factors.
- A voter might cast a vote that is unclear, creating uncertainty about the voter’s intent.
- There is the possibility of individual votes being recorded, transmitted, or counted incorrectly.
- There is the possibility of fraud within the voting process.

### 5.2 Treatment of abstentions

From a measurement viewpoint, yes means yes, no means no, and *null means null*. We may have insufficient evidence to say whether or not a consensus exists. Uncertainty may completely occlude the result.

Interpreting silence as support of or opposition to a choice adds a positive or negative bias to the outcome, respectively. Typically, when a yes-or-no question is being voted, the default choice is *no* to a proposed change. Absence of support for a change does not imply consensus in favor of the status quo, but the status quo is reinforced all the same, producing an imbalance of power in favor of vested interests.

Compulsory voting may reduce abstention but does not necessarily ensure a more valid result, as other properties enumerated in [Section 3.3.1](#) will be undermined.

### 5.3 In public elections

The distinct characteristics of public elections create additional issues for the management of uncertainty, but they also have a regulated process that adds mitigations for uncertainty:

- The population that is allowed to vote is determined through voter registration.
- Ballot instructions are provided according to best practices and regulations. Beyond that, however, the burden is on voters to understand the ballot and to verify that their votes are correctly presented to the recording system. Since votes are secret, there is no verification that the vote was cast as intended.
- Public elections are highly scrutinized both by political parties and by election authorities. The risk of errors in transmission or counting (such as those from poorly calibrated equipment, misprinting of ballots, or other systematic issues) is mitigated by audits performed before the vote is finalized. There is, by design, no traceability from the published totals back to an individual's cast vote. Cryptographic methods have been proposed to establish this traceability while preserving properties of privacy and secrecy (end-to-end auditable voting systems), but they are not standardized, and current methods provide only the ability for individual voters to check whether their votes were correctly counted.
- Fraud is controlled through procedures and law enforcement. Although some forms of fraud can be detected and their magnitudes estimated through statistical methods, it is typically reduced to a yes-or-no finding that an election is "free and fair" or not, separate from the results being reported. Factors outside of the voting system such as coercion may be harder to detect.

Calculation of uncertainty intervals for counts in public elections is more complicated than it at first appears:

- False detection of a mark on a paper ballot can cause an overvote condition, which causes any valid vote in that contest to be discarded.
- Failure to detect a mark on a paper ballot can lead to an undervote condition or the counting of a vote when it was actually overvoted.
- If write-ins are allowed, the number of choices may not be fixed beforehand, and there are additional exceptions to deal with.

The acceptable error in a public election vote count, as related by some election administrators, is one fewer than the margin of victory. The closer the election results, the greater the risk for errors to change the outcome. Risk-limiting audits are a new mitigation that is required by new standards. They limit the risk of an incorrect *decision* [38].

### 5.4 In committees and groups

The distinct characteristics of voting in committees and groups work to control some sources of uncertainty:

- In organized meetings, sampling uncertainty may be limited by a sufficiently large quorum.
- Members can raise points of order and request clarification of any unclear aspects of the poll.
- Since the process is conducted without secrecy, voters can in most cases witness that all votes were correctly recorded and counted.

## 5.5 In social media polls

In contrast, most sources of uncertainty are intensified in social media polls:

- The size of the population and, hence, sampling uncertainty are unpredictable.
- Ballot instructions are neither regulated by election law nor subject to clarification through procedural motions, so voters could easily be confused about what they are voting on or the impact of a choice.
- A fault in the platform could produce systematic error in the recording, transmission, or counting of votes that, in the absence of any audit, would not be detected.
- The barriers to fraud are low.

## 6 Other uses of consensus

### 6.1 Scientific consensus

Concepts such as *scientific consensus* or *medical consensus* pertain to what is generally accepted by the relevant population of scientists or other professionals. Such acceptance is practically never unanimous. Some level of skepticism of and divergence from widely-held beliefs is considered healthy as long as it is consistent with available empirical evidence.

In practice, scientific consensus is either characterized through the agreement of a committee or group (Section 4.1.2) or asserted by gatekeeper fiat (Section 2.2). There is no attempt at measuring the consensus of the population as a whole except inasmuch as a committee or group might constitute a representative sample.

Measuring the weight of evidence behind a theory is independent of measuring whether scientific consensus is with or against it. Unfortunately, in gatekeeping processes it can happen that an existing scientific consensus is used as a measure of the plausibility of new evidence, with the result that a self-sustaining orthodoxy develops that is resistant to or incapable of change.

### 6.2 Consensus values in international metrology

The term *consensus value* was introduced in international metrology to refer to a statistically-derived estimate of a measurand that national metrology institutes could agree to use [39]:

The purpose of this article is to discuss the problem of calculating “best” estimates from a series of experimental results. It will be convenient to refer to these estimates as consensus values.

Calculating such a value is a different thing than measuring the social consensus of a group and is, thus, out of scope for this discussion.

### 6.3 Consensus in multi-agent systems

In computer science, *consensus protocols* are used to decide an outcome in the presence of unreliable communications and unreliable or malicious agents. Although the word *consensus* is the same, the nature of the problem is different. There exists a ground truth in light of which the actions of individual agents and the outcome of the process are deemed correct or incorrect. This means that social concepts of consent and fairness to all parties concerned are out of scope, and software consensus protocols are thus out of scope for this discussion. But one concept that can be generalized to other contexts is the fault tolerance threshold: no consensus process can ensure a correct decision if too many agents behave incorrectly.

## 7 Conclusion

This article investigated the nature and limitations of the measurement model of consensus. Beginning with qualitative approaches to consensus, we saw that “unity” is an attractive goal, but it is difficult to distinguish it from the elusive state of unanimous agreement. We then proceeded to examine definitions, measurement, and uncertainty for consensus as a quantity, which can be measured in an automatable process and reduced to a dichotomic scale through decision rules.

For those seeking the social qualities of unity and cooperation, the compromises made in the process of quantifying consensus may amount to entirely missing the point, making the quantity an illegitimate *surrogate measure* (Section 3.3.3). But once unity and cooperation become unobtainable for any reason, the alternatives to measurement amount to the end of functioning as a group, one way or another (paralysis, war, schism, or dissolution).

We conclude with a few observations that are true under any reasonable definition of consensus:

- If no choice is supported by a simple majority, there is no consensus.
- If a choice is being made between exclusive alternatives, consensus cannot exist without a strong Condorcet winner—one option that would unambiguously be the group’s favorite.
- Biased control of the agenda and the ballot is incompatible with valid measurement of consensus.
- A group decision-making system in which a single participant can dictate the outcome or prevent a conclusion from being reached is not a consensus system.

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