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Abstract

Cities are greenhouse gas emission hotspots, making them targets for emission reduction policies.
Effective emission reduction policies must be supported by accurate and transparent emissions accounting. Top-down approaches to emissions estimation, based on atmospheric greenhouse gas measurements, are an important and complementary tool to assess, improve and update the emission inventories on which policy decisions are based and assessed.

27 In this study we present results from nine research flights measuring CO₂ and CH₄ around New 28 York City during the non-growing seasons of 2018 to 2020. We used an ensemble of dispersion 29 model runs in a Bayesian inverse modelling framework to derive campaign-average posterior emission estimates for the New York-Newark, N.J. urban area of (125 ± 39) kmol CO₂ s⁻¹ and 30 (0.62 ± 0.19) kmol CH₄ s⁻¹ (reported as mean $\pm 1\sigma$ variability across the nine flights). We also 31 32 derived emission estimates of (45 ± 18) kmol CO₂ s⁻¹ and (0.20 ± 0.07) kmol CH₄ s⁻¹ for the five 33 boroughs of New York City. These emission rates, among the first top-down estimates for New 34 York City, are consistent with inventory estimates for CO₂ but are 2.4 times larger than the gridded 35 EPA CH₄ inventory, consistent with previous work suggesting CH₄ emissions from cities 36 throughout the northeast U.S. are currently underestimated.

Keywords: urban emissions; greenhouse gas emissions; methane; carbon dioxide; Bayesian
inverse modelling; New York City

39 Introduction

40 Cities are large sources of greenhouse gas emissions, with an estimated 36.8% of total global
41 emissions coming from within urban extents in the year 2000 (Marcotullio et al., 2013). In North
42 America this urban share of greenhouse gas emissions was estimated to be even larger (49.2%;
43 Marcotullio et al., 2013).

To reduce emissions and mitigate climate change, many cities are implementing new policy practices and regulations (Trencher et al., 2016; Sethi et al., 2020). New York City has legally binding emission reduction targets of 40% by 2030 and 80% by 2050, relative to 2005 levels (New York City Mayor's Office of Sustainability, 2016). As part of the legislative effort to meet these targets, the city council passed the Climate Mobilization Act, which introduces emission limits on large and medium-sized buildings under Local Law 97 (Climate Mobilization Act, 2019).

50 Progress towards emission targets and the efficacy of emission reduction policies can be assessed 51 through the compilation of city-specific inventories, often referred to as self-reported inventories. 52 These inventories estimate greenhouse gas emissions using a bottom-up approach, where the total 53 emission from each source category is calculated by multiplying activity data (e.g., fuel sales) by 54 an emission factor (e.g., greenhouse gas emissions per unit of fuel sold). Self-reported inventories 55 typically provide emission estimates at the whole-city level, broken down by emission source. 56 These estimates can include direct emissions within the city limits (scope 1 emissions), emissions 57 associated with electricity used within the city but generated elsewhere (scope 2 emissions) and 58 other indirect emissions that occur elsewhere (e.g., landfill CH₄) as a result of activity (e.g., waste 59 production) within the city (scope 3 emissions; Nangini et al., 2019). The New York City 60 emissions inventory (MacWhinney and Barnett, 2019) is compiled using a mixed-scope approach known as the city-induced framework (Fong et al., 2014), which is designed to account for 61

emissions attributable to activities within the city limits, regardless of emission location. This mixed-scope approach includes some emissions from each of scope 1, 2 and 3, but does not include all the emissions from any single scope. Quantifying indirect emissions is important from a policy perspective, but it is challenging to assess mixed-scope inventories with atmospheric measurements, which are only sensitive to scope 1 emissions.

67 Spatially-resolved inventories of scope 1 emissions have been compiled at the national level, 68 either using bottom-up approaches (Gately and Hutyra, 2017; Gurney et al., 2020) or using proxy 69 data to spatially disaggregate national emission totals (Maasakkers et al., 2016; Oda et al., 2018; 70 Janssens-Maenhout et al., 2019). These can be used to assess and improve the self-reported 71 inventories or adopted as the primary method by which cities tailor and assess their emission 72 reduction policies (Hutyra et al., 2014; Gurney and Shepson, 2021). A recent study by Gurney et 73 al. (2021) compared scope 1 emissions from the national Vulcan inventory with self-reported 74 inventories from 48 U.S. cities and found that most cities underreported emissions. The spatial 75 information in gridded national inventories allows them to be combined with atmospheric transport 76 models to estimate atmospheric mole fractions, allowing direct comparison to measurements and 77 thus facilitating top-down approaches to estimating emissions.

Many top-down studies have used tower-based measurements of greenhouse gas mole fractions in an inverse modelling approach to estimate urban emissions (Bréon et al., 2015; Lamb et al., 2016; Lauvaux et al., 2016; 2020; Staufer et al., 2016; Deng et al., 2017; Huang et al., 2019; Nickless et al., 2019; Yadav et al., 2019). Tower-based sites allow for continuous year-round observations, enabling top-down fluxes to be estimated at annual timescales. On the other hand, an individual tower has limited spatial sensitivity, so multiple towers may be required to provide the necessary spatial coverage to accurately estimate whole-city emissions. Aircraft-based 85 measurements cannot provide the continuous temporal coverage of tower observations. However, 86 by sampling a wide area in a short period of time, well-tailored flight tracks enable aircraft to 87 provide useful snapshot estimates of whole-city emissions, with the ready ability to define and 88 change the area of study.

89 Aircraft measurements can be used in an inverse modelling framework to estimate urban 90 emissions. This approach incorporates information regarding the prior fluxes, transport model and 91 measurements, including the error covariance structure for each of these elements. Several 92 previous studies have applied such a framework to estimate urban fluxes using aircraft 93 measurements (Brioude et al., 2011; 2013; Pisso et al., 2019; Lopez-Coto et al., 2020). However, 94 this approach has yet to be applied to estimate New York City greenhouse gas emissions. In this 95 study we use measurements from nine research flights (during the non-growing season) and an 96 ensemble of dispersion model runs in an inverse modelling approach to estimate carbon dioxide 97 and methane emission rates for the New York-Newark, N.J. urban area and the five boroughs of 98 New York City.

99

100 Methods

101 Aircraft measurements

Measurements were made on board the Purdue University Airborne Laboratory for Atmospheric Research (ALAR), a modified Beechcraft Duchess. Full details of the aircraft payload and sampling configuration are provided by Cambaliza et al. (2014). Carbon dioxide (CO₂) and methane (CH₄) mole fractions were measured using a Picarro Cavity Ringdown Spectrometer (Crosson, 2008), calibrated in flight using three calibration cylinders traceable to the National Oceanic and Atmospheric Administration (NOAA) reference scales for CO₂ (X2007; Tans et al., 2017) and CH₄ (X2004A; Dlugokencky et al., 2005). The cylinders were prepared, filled and
certified by NOAA; details are provided in SI Table S1.1.

110 Three Picarro analysers were used over the course of the campaign: two different G2301-f 111 analysers and one G2401-m analyser. The two G2301-f analysers were operated in low-flow mode, 112 with each species measured at approximately 1.2 s intervals on one analyser and 1.4 s intervals on 113 the other. The G2401-m analyser took a measurement of each species at approximately 2.3 s 114 intervals. These analysers exhibited typical precisions of 0.2 ppm (μ mol mol⁻¹) for CO₂ and 3 ppb 115 (nmol mol⁻¹) for CH₄, based on analysis of data gathered during in-flight and ground-based 116 calibrations. A linear calibration curve was derived for each flight day using in-flight 117 measurements of all three calibrations cylinders on board the aircraft. In all cases we obtained r^2 118 values greater than 0.999, demonstrating good instrument linearity.

Flights were performed on nine separate days between November 2018 and March 2020, with all flights taking place in either November, February or March. Flight tracks are shown in Figure S4.1, which also gives the dates and times of the flights. The total flight duration for each day (as measured from the first usable measurement to the final usable measurement) varied between 2.5 hours to 5.5 hours.

124 Transport modelling

The surface influence, or footprint, of the sampled air was determined using HYSPLIT v5.0.0 (Hybrid Single Particle Lagrangian Integrated Trajectory Model; Draxler and Hess, 1998; Stein et al., 2015; Loughner et al., 2021), a Lagrangian particle dispersion model developed by the NOAA Air Resources Laboratory (ARL). This version of HYSPLIT incorporates elements of STILT (Stochastic Time-Inverted Lagrangian Transport Model; Gerbig et al., 2003; Lin et al., 2003; Fasoli et al., 2018), a related model that branched off an earlier version of HYSPLIT. This combines features from STILT, including options for a different vertical turbulence scheme that
prevents well-mixed particles from accumulating in low-turbulence regions (Thomson et al.,
1997), a varying vertical Lagrangian timescale (Hanna, 1982) and an additional boundary layer
turbulence parameterisation (Hanna, 1982), with recent model development and bug fixes within
HYSPLIT (Loughner et al., 2021).

136 Each of our HYSPLIT runs was repeated using four different choices of input meteorology and 137 two different turbulence parameterisations (Hanna, 1982; Kantha and Clayson, 2000) giving us an 138 eight-member ensemble of dispersion model runs (hereafter referred to as the transport model 139 ensemble). The input meteorology was taken from four publicly available archived products: the 140 European Centre for Medium Range Weather Forecasts Fifth Reanalysis (ERA5), the NOAA 141 Global Forecast System (GFS) model, the NOAA North American Mesoscale Forecast System 142 (NAM) model, and the NOAA High-Resolution Rapid Refresh (HRRR) model (see SI section S2 143 for more details on each product).

A separate HYSPLIT model run was conducted for every minute of each flight that included aircraft sampling within the boundary layer. The mean measured mole fraction for each minute was calculated as an average over all measurement points where the aircraft was within the boundary layer, with the corresponding model particle release consisting of ~1000 particles distributed equally across these measurement locations (covering a horizontal distance of ~ 3 km to 4 km at typical aircraft speeds). In this way we ensured that the model run was representative of the measurements we included in our average.

151 Tiered multi-resolution Bayesian inversion framework

Fluxes were optimised separately for each flight using a Bayesian inversion framework, after first subtracting the background mole fraction from the aircraft measurements (where the background is defined as the mole fraction of CO_2 or CH_4 within the measured air prior to it entering the domain; see SI section S9 for details). This process consisted of multiple stages:

156 1) Optimise fluxes on a large domain at coarse spatial resolution $(0.08^{\circ} \times 0.08^{\circ})$.

- 157 2) Use the posterior flux map from step 1) to estimate spatial variability in the mole fractions 158 of CO_2 and CH_4 flowing into a smaller, high resolution ($0.02^\circ \times 0.02^\circ$) domain, nested within 159 the large domain and centred on New York City.
- 3) Optimise fluxes on the smaller, high-resolution domain, taking into account the background
 variability calculated in step 2).

The large domain (henceforth referred to as the d01 domain) was bounded by 34.4°N, 44.4°N, 83.7°W, 69.7°W, while the smaller nested domain (henceforth the d03 domain) was bounded by 39.2°N, 42.0°N, 75.7°W, 72.1°W (see SI Figure S3.1 for map). This approach takes account of upwind sources that influenced our measurements and provides an optimised representation of their influence. This allows us to better isolate the specific contribution from the area of interest (e.g., the New York-Newark urban area) by providing an optimised background for each minute of the flight.

A gridded footprint (representing the influence of surface fluxes on the sampled air) was calculated on both the d01 and d03 domains for each minute of the flight. Modelled mole fraction enhancements (in units of μ mol mol⁻¹; commonly referred to as ppm) were derived by multiplying these gridded footprints (in units of ppm (μ mol m⁻² s⁻¹)⁻¹) by surface fluxes (in units of μ mol m⁻² s⁻¹) of CO₂ and CH₄. The inventories used to provide prior fluxes are described in the following section. For both the initial d01 inversion and the nested d03 inversion, optimised posterior fluxes were obtained by minimising the cost function $J(\mathbf{x})$:

176
$$J(x) = \frac{1}{2} [(x - x_b)^T \mathbf{P}_b^{-1} (x - x_b) + (\mathbf{H}x - y)^T \mathbf{R}^{-1} (\mathbf{H}x - y)]$$
(1)

177 This cost function assumes normally distributed uncertainties and has the following analytical178 solution (Enting, 2002; Tarantola, 2005):

179
$$\mathbf{x}_{a} = \mathbf{x}_{b} + \mathbf{P}_{b}\mathbf{H}^{\mathrm{T}}(\mathbf{H}\mathbf{P}_{b}\mathbf{H}^{\mathrm{T}} + \mathbf{R})^{-1}(\mathbf{y} - \mathbf{H}\mathbf{x}_{b})$$
(2)

Here x is a vector containing the fluxes that are to be optimised, x_a contains the posterior (opti-180 181 mised) fluxes, x_b contains prior fluxes derived from an emissions inventory and H is a matrix 182 containing the modelled footprint for each minute of the flight. The vector y contains the measured 183 mole fraction enhancements for each minute of the flight, relative to a background value repre-184 senting the mole fraction present in the sampled air when it entered the domain. For the d01 inver-185 sion, this background value was taken to be constant, while for the d03 inversion a spatially-vary-186 ing background was calculated based on the posterior fluxes within the d01 domain (see SI section 187 S9 for more details, including details of a sensitivity analysis to determine the impact of the nested 188 inversion approach). The error covariance matrices P_b and R represent uncertainty in the prior 189 fluxes and model-measurement mismatch respectively.

190 Error covariances

191 Following previous studies (Lauvaux et al., 2016; 2020; Lopez-Coto et al., 2017; 2020), the off-192 diagonal components of the error covariance matrix P_b were populated using an exponential 193 covariance model (in space). The diagonal elements of P_b were populated on the assumption that 194 the 1σ flux uncertainty in each grid cell equalled 100% of the prior flux within that grid cell, 195 following the values used by Lopez-Coto et al. (2017; 2020). For comparison, Andres et al. (2016) 196 reported 2σ grid-cell-level uncertainties for a global CO₂ inventory ranging from 4% to more than 197 190%, averaging about 120%. Gately and Hutyra (2017) reported 50% to 250% differences 198 between ACES (Anthropogenic Carbon Emissions System; version 1) and three global 199 disaggregated CO₂ inventories at city scales, with grid-cell-level differences of over 100% for half of the grid cells (urban and rural) in the northeast U.S. For CH₄ there are no good estimates of grid-cell-level uncertainty, but considering recent work indicating inventories significantly underestimate urban CH₄ emissions, and the lack of knowledge about CH₄ sources at urban scales, we can only assume that the relative uncertainties are at least as large as for CO₂. A lower limit uncertainty in each grid cell was set to 1 μ mol m⁻² s⁻¹ and 1 nmol m⁻² s⁻¹ for CO₂ and CH₄ respectively, allowing some correction in grid cells with very low prior fluxes.

206 The off-diagonal elements of the prior flux error covariance matrix, representing the correlation 207 between prior flux errors in different grid cells, were calculated according to an exponential decay 208 model based on the distance between grid cells (Lauvaux et al., 2012; 2016; 2020; Lopez-Coto et 209 al., 2017; 2020). The correlation length was set to 10 km following Lopez-Coto et al. (2017) who 210 found this value to be appropriate for studies at urban scales. A variogram analysis of the spread 211 of the prior flux ensemble indicated that the exponential covariance model and the correlation 212 length used here are appropriate for both species in both domains (see SI section S11). The same 213 approach to constructing $\mathbf{P}_{\mathbf{h}}$ was used for both the d01 and d03 inversions.

214 A double exponential covariance model (in space and time) was selected for the model-meas-215 urement mismatch error covariance matrix **R**, with a correlation length of 1 km and a correlation 216 time of 1 hour based on the short correlation length and time scales reported for atmospheric trace 217 gases in urban environments (Shusterman et al., 2018; Turner et al., 2020). The diagonal elements 218 of **R** represent the combined uncertainty due to random error in the measurements, model and 219 background for each minute of the flight. This was calculated by combining background uncer-220 tainty (see below) with the variance across the eight transport model ensemble members for a given 221 minute and the variance in measured mole fraction during that minute. In all cases, low limits for the uncertainty of 0.2 ppm (μ mol mol⁻¹) and 3 ppb (nmol mol⁻¹) were used for CO₂ and CH₄ respectively, based on an analysis of instrument precision from calibration data.

The background uncertainty for the d01 inversion was derived by calculating the respective variances in measured and modelled mole fractions across the background data points, then summing these variances (see SI section S9 for the definition of the background points). For the d03 inversion these terms were combined with the variance of the spatially-varying component of the background (i.e., the outside contribution derived from the posterior d01 fluxes), taken across the eight transport model ensemble members.

230 **Prior fluxes**

231 Separate inversions were performed using three different CO₂ flux priors and four different CH₄ 232 flux priors. For CO₂ we used fluxes from Vulcan v3.0 (Gurney et al., 2020), ACES v2.0 (Gately 233 and Hutyra, 2017) and EDGAR v5.0 (Emission Database for Global Atmospheric Research; 234 European Commission Joint Research Centre (JRC)/Netherlands Environmental Assessment 235 Agency (PBL), 2019; Crippa et al., 2020). For CH₄ we used fluxes from EDGAR v5.0, EDGAR 236 v4.2 (European Commission Joint Research Centre (JRC)/Netherlands Environmental Assessment 237 Agency (PBL), 2011) and the gridded Environmental Protection Agency (GEPA) inventory 238 (Maasakkers et al., 2016). Because EDGAR v4.2 uses a population proxy to distribute fluxes, it 239 contains much larger emissions from urban areas compared to EDGAR v5.0 and the GEPA 240 inventory (conversely it is known to underestimate emissions in oil and natural gas production 241 regions). To bridge this large emissions gap between inventories, we also used a composite CH₄ 242 prior containing the average of the GEPA fluxes and the EDGAR v4.2 fluxes in each grid cell. 243 In all cases we used annual average emissions for the most recent year available: 2015 for

244 Vulcan, 2017 for ACES, 2018 for EDGAR v5.0 CO₂, 2015 for EDGAR v5.0 CH₄, 2012 for the

245 GEPA, and 2008 for EDGAR v4.2. The use of annual average fluxes (even for those inventories 246 for which hourly fluxes are available) was motivated by the fact that we did not have inventory 247 fluxes for the actual flight days (which were more recent than the latest available inventory data). 248 Furthermore, holding the prior emission rates constant for each flight ensures that flight-to-flight 249 differences in posterior emission rates are not a consequence of prior temporal variability. While 250 prior constraints are important for solving ill-posed problems, it is known that the choice of prior 251 flux map can influence the posterior fluxes (Lauvaux et al., 2020). By using multiple priors for 252 each gas we reduce the dependency of our mean posterior fluxes on one specific prior.

A conservative method was used to regrid each prior to the extent and resolution of the d01 and d03 domains (Zhuang, 2020). Canadian emissions for the U.S.-specific priors (Vulcan, ACES and GEPA) were taken from EDGAR v5.0. A more detailed discussion of prior fluxes is given in SI section S3.

257 Sensitivity analysis

In addition to our base case ensemble of inversions, we performed a sensitivity analysis to better understand the impact of different background choices and prior error covariance parameters in our posterior results, as well as to quantify uncertainties in the methodology. A full description of the sensitivity test cases is provided in SI sections S10 and S11.

262

263 **Results and discussion**

Total posterior emission rates were calculated for both the five boroughs of New York City (NYC) and the wider New York-Newark urban area (see SI section S3 for area definitions). The wider urban area better represents the area of sensitivity for our flights (see SI Figure S4.1 for footprint maps), therefore these wider urban area emission totals are the focus of analysis in this section. Emission rate estimates for the five boroughs of NYC are also presented due to the highpolicy relevance of this area.

270 Urban area posterior emission rates

271 Figure 1 shows total emission rates within the New York-Newark urban area boundary, broken 272 down by flight, prior and transport model. The mean posterior emission rate for CO₂ was (125 \pm 39) kmol s⁻¹, where the reported uncertainty represents the 1 σ variability across the nine flights 273 274 (using ensemble-average totals for each flight). Also shown (in purple) are inventory emissions 275 from the hourly ACES inventory and hourly Vulcan inventory, calculated using only dates and 276 hours that were representative of our flights (see SI section S5 for details). The mean value of these representative inventory emissions was (145 ± 21) kmol s⁻¹ for ACES (15.5% larger than our mean 277 posterior estimate) and (124 ± 20) kmol s⁻¹ for Vulcan (0.9% lower than our mean posterior 278 279 estimate). The inventory variability reported here represents 1σ across 45 representative days in 280 each inventory. Both our mean posterior emission rate and these representative inventory emission rates are larger than the corresponding annual average emission rates (116 kmol s⁻¹ for ACES and 281 105 kmol s⁻¹ for Vulcan) that we used as priors. While we do not expect these representative 282 283 inventory values (from previous years) to agree perfectly with our mean posterior emissions rates, 284 the agreement shown here is well within the observed flight-to-flight variability of our estimates 285 as well as the expected daily variability of the inventories.





The posterior CO_2 emission estimates represent total emissions and are influenced by any contribution from biospheric respiration and photosynthesis, while the inventories only include anthropogenic fluxes. However, the flights in this study were conducted during the non-growing season and the estimated biospheric contribution was very small, ~ 2% on average (see SI section S6 for details).

The posterior CH₄ emission rates calculated for the New York-Newark urban area using all four priors are much larger than emission rates from the GEPA and EDGAR v5.0 inventories, but much smaller than the emission rate from EDGAR v4.2. The mean posterior CH₄ emission rate was (0.62 \pm 0.19) kmol s⁻¹ (1 σ variability across flights). This mean posterior total is 2.4 times larger than the annual value from the GEPA inventory.

309 The temporal variability of urban CH₄ emissions on diurnal, weekly and seasonal timescales is 310 poorly understood. None of the CH₄ inventories used in this study provide emission estimates on 311 hourly timescales, so it is not possible to repeat the calculation of representative inventory totals 312 presented above for CO₂. Recent studies in Los Angeles (Yadav et al., 2019) and Washington, DC-313 Baltimore (Huang et al., 2019) found large seasonal cycles in urban CH₄ emissions. Floerchinger 314 et al. (2021) observed significant seasonal variability in the biogenic fraction of CH₄ emissions for 315 several cities, including New York. More flights are required to provide the annual coverage 316 necessary to confirm if strong seasonality also exists in total CH₄ emissions for the New York-317 Newark urban area.

It is important to emphasise that our mean posterior emission rates (for both CO_2 and CH_4) do not represent estimates of annual average emissions, but can be regarded as the current best topdown estimate for the non-growing-season, daytime value. However, the finding that emissions are underestimated in the GEPA inventory is likely to hold at the annual timescale, as emissions 322 during much of the rest of the year would have to be almost zero in order to offset the 2.4 times

323 larger CH₄ emissions observed during November, February and March in this study.

324 Sources of variability and uncertainty analysis

325 The flight-to-flight variability in urban area posterior emission rate was 31% for both CO₂ and 326 CH_4 (1 σ , relative to the mean posterior emission rate). These values for relative flight-to-flight 327 variability are similar to those reported by Lopez-Coto et al. (2020) for the Washington, DC-328 Baltimore urban area. Table 1 gives the 1σ spread in posterior emission rate across base case 329 ensemble members (transport models and priors) and sensitivity test ensemble members (prior 330 error covariance parameters and background definitions - see SI for more details), including the 331 average spread for a single flight and the spread in campaign-average emissions. For both species, 332 flight-to-flight variability in posterior emission rate was larger than the combined spread across 333 the ensembles (calculated by adding individual ensemble spreads in quadrature). It is noteworthy 334 that the combined ensemble spread for CH₄ is much smaller than the difference between the mean 335 posterior emission rate and the inventory values.

336

Table 1: 1σ spread in posterior emission rate for the New York-Newark urban area across each
ensemble, relative to the base case ensemble mean.

	Single-flight	t	Campaign-a	average
	ensemble spread		ensemble spread	
Ensemble	CO ₂ (%)	CH4 (%)	CO ₂ (%)	CH4 (%)
Transport model	13	12	3.8	3.6
Prior	8.2	18	7.9	18
Prior flux covariance parameters	4.6	4.2	3.7	2.8
Background	4.6	8.6	4.3	7.7
Combined	16	24	10	20

To provide a rough estimate of expected variability in true CO₂ emissions from flight to flight, we calculated the variance in inventory emissions for the urban area using dates and hours corresponding to each flight (see SI section S5 for details). The standard deviation in inventory emissions across 45 representative days in ACES was equal to 15% of the average emissions across these days, while for Vulcan this value was 16% (boxplots showing these representative emissions for both inventories are shown in purple in Figure 1).

345 There are multiple potential reasons why the flight-to-flight variability (31%) of our posterior 346 emissions is larger than that calculated using representative inventory emissions. Differences in 347 sampling pattern for each flight (shown in SI Figure S4.1) mean that different parts of the urban 348 area were sampled on different flights. Because the measurements are not sensitive to the whole 349 urban area for each flight, emissions in unsampled areas default to the emission rate of the prior. 350 In addition, different areas were sampled at different times within each flight, which for sources 351 with large hourly variability in emission rate can result in apparent flight-to-flight variability in 352 posterior emissions. Thus, this irregular sampling combined with large spatio-temporal variability 353 in fluxes can become aliased as apparent temporal variability, as demonstrated by Lopez-Coto et 354 al. (2020). In addition, for a given ensemble (e.g., transport or background), errors in the ensemble 355 mean can differ in magnitude and direction for each flight, thus increasing the observed flight-to-356 flight variability.

Finally, the variability in inventory emissions may not be truly representative of real emission variability because the temporal emission profiles in the inventories are partly based on interpolation and/or downscaling using proxy data (resulting in smoothed temporal emission profiles). It is also worth considering that inventory emissions are for previous years, which may have had lower variability than the flight days, and that the flights were conducted in two different winters (2018 to 2019 and 2019 to 2020) while the inventories are only for a single year each, so
potential interannual variability is not accounted for.

364 Quantifying the accuracy of the emission rate estimates is challenging since the true value is not 365 known. On one hand, the combined campaign-average ensemble spreads (10% for CO₂, 20% for 366 CH₄) could be larger than the uncertainty of the mean posterior emission rate, because this mean 367 value represents an average over the base case ensemble members. Conversely, the potential 368 methodological sources of flight-to-flight variability discussed above (e.g., emission aliasing) are 369 not accounted for in the campaign-average ensemble spread, but nonetheless contribute towards 370 the overall uncertainty. In general we focus on flight-to-flight variability when reporting results, 371 rather than the campaign-average ensemble spread, but it is important to note that the 1σ flight-to-372 flight variability includes both real variability in emissions as well as methodological uncertainty.

373 NYC posterior emission rates

374 We also calculated mean posterior emission rates for the five boroughs of NYC: (45 ± 18) kmol CO₂ s⁻¹ and (0.20 \pm 0.07) kmol CH₄ s⁻¹ (1 σ variability across flights). As was the case for the 375 376 urban area totals, inventory CO₂ emission rates calculated for NYC using dates and hours 377 representative of our flights are consistent with our posterior values. The representative NYC emission rate for ACES was (45 ± 9) kmol CO₂ s⁻¹, while for Vulcan it was (52 ± 10) kmol CO₂ 378 379 s^{-1} . The fact that the mean NYC posterior emission rate for CO₂ is in line with expectations based 380 on representative inventory emissions (within 15% for both inventories) is an encouraging sign 381 that the inversion is able to estimate emissions at spatial scales smaller than the wider urban area. 382 Further details of the spatial structure of prior and posterior fluxes in central NYC are given in SI 383 section S8.

384 It is difficult to compare our posterior emission rates directly to the NYC self-reported inventory 385 (SRI), because that inventory includes a mixture of scope 1, 2 and 3 emissions and does not provide scope 1 totals for each emitted species. The 2019 SRI total for CH_4 is 0.21 kmol s⁻¹ (New York 386 387 City Mayor's Office of Sustainability, 2020), but this is dominated by waste emissions (0.17 kmol 388 s^{-1}), which are mainly scope 3 (as landfill waste is exported from the city; MacWhinney and 389 Klagsbald, 2017). The SRI CH₄ emission estimate for natural gas distribution leakage is a scope 1 390 value; for 2019 this was calculated to be 0.041 kmol s^{-1} (21% of our posterior emission total). 391 Considering that previous studies (Plant et al., 2019; Floerchinger et al., 2021) have shown that 392 the majority of New York CH₄ emissions are from thermogenic (i.e. natural gas) sources, it is 393 likely that the SRI underestimates scope 1 thermogenic emissions. More measurements of NYC 394 C₂H₆ emissions could enable a direct quantitative assessment of thermogenic SRI CH₄ emissions. 395 CO₂ emissions in the NYC SRI are also comprised of multiple scopes, but a recent study (Gurney 396 et al., 2021) has shown that total emissions from scope-1-only source categories in the NYC SRI 397 are lower than the corresponding total Vulcan emissions for these categories by 19%.

398 Posterior-prior spatial differences

399 The spatial distributions of the difference between posterior and prior fluxes are shown in Figure 400 2. Prior emissions were adjusted upwards throughout the urban area for Edgar v5.0 CO₂, Edgar 401 v5.0 CH₄ and GEPA CH₄. Conversely the large prior CH₄ emissions in Edgar v4.2 (distributed 402 according to population) were adjusted downwards throughout the urban area. Posterior fluxes 403 estimated using the Vulcan and ACES CO₂ priors showed an upwards adjustment throughout most 404 of the urban area, but a downwards adjustment in central New York City (specifically in the 405 southern part of Manhattan – see SI Figure S8.1 for a zoomed in map). The spread across posterior 406 fluxes using three different priors for this area is smaller than the spread across the prior fluxes

407 themselves. However, further research is required, including higher resolution transport models, 408 to understand whether small scale spatial features observed in these posterior emission maps reflect 409 real spatial patterns in emissions or artefacts of the relatively coarse resolution of the transport 410 models used (see SI section S2 for more details regarding the transport model configuration). New 411 York City is a very complex land/urban/water interface and increased resolution would allow for 412 better representation of smaller spatial features that could alter the local circulations.

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415 Figure 2. Maps showing the campaign-average difference between posterior and prior fluxes.

416 Results are shown for CO_2 (a–c) and CH_4 (d–f). The New York-Newark urban area boundary is

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⁴¹⁷ shown in black. Colour scale is saturated at the shown limits.

419 Emission ratio

420 The average posterior CH₄:CO₂ emission ratio for the New York-Newark urban area is $(4.9 \pm$ 0.7) nmol μ mol⁻¹ (1 σ variability across flights), and for New York City it is (4.4 ± 1.1) nmol 421 422 µmol⁻¹. As for the posterior CO₂ and CH₄ emission rate estimates, this ratio should be interpreted 423 as an average over the dates and times (daytime, non-growing season) of our flights, not an 424 annually representative value. Nonetheless, it is interesting to compare our emission ratio against 425 enhancement ratios for the New York-Newark urban area reported by previous studies. Plant et al. 426 (2019) reported an average CH₄:CO₂ enhancement ratio of 7.2 (+1.4/-1.0) nmol μ mol⁻¹ (95%) 427 confidence interval), taken over 10 flight days during April and May 2018. A lower enhancement 428 ratio of 3.7 (+0.3/-0.2) nmol µmol⁻¹ (95% confidence interval) was reported by Floerchinger et 429 al. (2021) for a single ("winter") flight in March 2018 (see SI Figure S7.1 for a comparison plot). 430 Plant et al. (2019) also estimated a CH₄ emission rate for the urban area, which they calculated 431 as the product of their CH₄:CO₂ enhancement ratio and an inventory estimate of CO₂ emissions. 432 They derived a total CH₄ emission rate that was 2.7 times larger than the GEPA inventory value, 433 in relatively close agreement to the results of our study (2.4 times larger than the GEPA inventory). 434 At first sight, this appears at odds with the fact that the Plant et al. (2019) enhancement ratio is 435 significantly larger than our estimated emission ratio. This apparent discrepancy is reconciled by 436 considering that the CO₂ inventory emission rate used by Plant et al. (2019) is lower than our mean 437 posterior CO_2 emissions. This is not unexpected, as CO_2 emission inventories suggest emissions 438 during April and May are typically lower than emissions during November, February and March 439 (as shown in SI Figure S5.1).

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441

442 **Conclusions**

Our posterior emission rate estimates show good agreement with representative values from the ACES and Vulcan CO_2 inventories. In contrast, none of the available CH_4 inventories fell within a factor of 2 of our posterior estimates. It is of particular policy relevance that our posterior CH_4 emission rate estimate for the New York-Newark urban area was 2.4 times larger than the GEPA inventory. Taken together with previous studies in other cities, there is strong evidence that the GEPA inventory widely underestimates urban CH_4 emissions.

Underestimation of urban CH₄ emissions could impede urban emission reduction policies if cities neglect to address important (but difficult to quantify) emission sources such as natural gas leaks. Accurate, spatially-resolved bottom-up estimates of U.S. CH₄ emissions would allow cities to develop better informed emission reduction policies, but uncertainty in the magnitude and location of key sources (e.g., emissions from natural gas distribution) makes it difficult to compile such an inventory with the required accuracy.

455 Aircraft measurements enable top-down estimates of urban greenhouse gas emissions at spatial 456 scales representative of the whole urban area. To track changes in annual emissions, it is necessary 457 to design aircraft sampling campaigns to include repeat flights covering weekly and seasonal 458 timescales of emission variability. In addition, as suggested by Lopez-Coto et al. (2020), increasing 459 the number of simultaneous measurements might at least partially alleviate the flight-to-flight 460 variability caused by irregular sampling. In the case of New York City, increasing the seasonal 461 coverage of flights to better quantify the poorly understood seasonal cycle of CH₄ emissions is a 462 particular priority. Regular aircraft sampling could be especially valuable in cases such as New 463 York that lack an extensive network of urban tower measurements.

464 Inverse modelling can play a key role going forward by providing independent quantification of 465 emissions in near-real time. It can be used to evaluate emission estimates in the past (if 466 measurements exist) and it can be used to update inventories and tailor policy in the present. There 467 is an inherent positive feedback loop between top-down inverse modelling emission estimates and 468 inventory development. Top-down emission estimates can be used to improve the models and data 469 on which the inventories rely, resulting in better inventory products. These improved inventories 470 then provide more accurate priors for subsequent inverse modelling studies, resulting in improved 471 emission estimates and reduced posterior uncertainties. Together, top-down and bottom-up 472 emission estimation approaches can effectively guide emission reduction policy in urban areas.

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696 **Contributions**

- 697 Contributed to conception and design: JRP, ILC, KDH, CRF, AK, JRW, PBS
- 698 Contributed to acquisition of data: JRP, ILC, KDH, JT, RK, TJ, BHS, CPL, CKG, LRH, KRG,
- 699 GSR, JL, SG, PBS
- Contributed to analysis and interpretation of data: JRP, ILC, KDH, CRF, CKG, GSR, SG, AK,PBS
- 702 Drafted and/or revised the article: JRP, ILC, KDH, CPL, LRH, GSR, SG, AK, PBS
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- 710 Certain commercial equipment, instruments, or materials are identified in this paper in order to 711 specify the experimental procedure adequately. Such identification is not intended to imply 712 recommendation or endorsement by NIST nor is it intended to imply that the materials or 713 equipment identified are necessarily the best available for the purpose.

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720 **Competing interests**

- 721 The authors declare that no competing interests exist. Paul B. Shepson is an Associate Editor at
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723 Supplemental material

- 724 Appendix A. Further details regarding dispersion model configuration, domains, footprints,
- 725 inventory emissions, biospheric influence, emission ratios, posterior spatial distribution, inverse
- 726 modelling configuration and sensitivity tests. (PDF)
- 727 Appendix B. Prior and posterior emission rates from individual ensemble members, and
- representative inventory emission rates. (XLSX)

729 Data accessibility statement

Aircraft measurement data used in this study are available from the Harvard Dataverse at https://doi.org/10.7910/DVN/UECQXX.