NIST Technical Note 2163

P-Flash – A Machine Learning based Flashover Prediction Model to Enable Smart Firefighting for Compartment Fires

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> > June 2021



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National Institute of Standards and Technology Technical Note 2163 Natl. Inst. Stand. Technol. Tech. Note 2163, 52 pages (June 2021) CODEN: NTNOEF

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Abstract

This report provides additional technical details to an article entitled *P*-Flash – A Machine Learning-based Model for Flashover Prediction using Recovered Temperature Data.

Research was conducted to examine the use of Support Vector Regression (SVR) to build a model to forecast the potential occurrence of flashover in a single-floor, multi-room compartment fire. Synthetic temperature data for heat detectors in different rooms were generated, 1000 simulation cases are considered, and a total of 8 million data points are utilized for model development. An operating temperature limitation is placed on heat detectors where they fail at a fixed exposure temperature of 150 °C and no longer provide data to more closely follow actual performance.

The forecast model, P-Flash (Prediction model for <u>Flashover</u> occurrence), is developed to use an array of heat detector temperature data, including in adjacent spaces, to recover temperature data from the room of fire origin and predict potential for flashover. Two special treatments, sequence segmentation and learning from fitting, are proposed to overcome the temperature limitation of heat detectors in real-life fire scenarios and to enhance prediction capabilities to determine if the flashover condition is met even with situations where there is no temperature data from all detectors. Experimental evaluation shows that P-Flash offers reliable prediction. The model performance is approximately 83 % and 81 %, respectively, for current and future flashover occurrence, considering heat detector failure at 150 °C. Results demonstrate that P-Flash, a new data-driven model, has potential to provide fire fighters real-time, trustworthy, and actionable information to enhance situational awareness, operational effectiveness, and safety for firefighting.

Key words

Machine learning; flashover prediction; fire modeling; heat detector; smart firefighting.

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1. Introduction

Over the five-year period from 2013 - 2017, the fire departments in the United States responded to an average of 500,000 structure fires annually [1]. These fires resulted in approximately 2,500 civilian fire deaths, 14,000 civilian fire injuries, and more than \$10 billion dollars in direct property losses. In addition, more than 31,000 firefighters were injured, and approximately 360 of them were killed on the fire ground [2]. Statistics show that rapid fire development caused by extreme fire behaviors such as flashover is identified as one for the major causes of fatal injury for fire fighters during structural firefighting. Although flashover conditions (i.e., hot layer gas temperature approximately $600 \,^{\circ}$ C and/or average heat flux at the floor level reaching 20 kW/m2) are well known in the fire research community, this kind of detailed information about the interior thermal conditions is usually unavailable. It is rather difficult for fire fighters to understand the potential fire hazards inside the compartment. In a structural fire, rollover [3] is one possible indicator. Visually, it can be seen as flames rolling across the ceiling. When rollover phenomenon is observed, a potential flashover is likely to occur. However, this extreme fire indicator is not easy to recognize, and it could take many years of experience to build up the necessary proficiency. Therefore, if fire fighters do not have such a high level of situational awareness, the flashover threat presents itself as an unpredictable life-threatening hazard.

Several research efforts have been conducted to develop data-driven models that can estimate the heat release rate (HRR) based on information obtained from sensors in real-time. Davis and Forney [4] developed an inverse fire model based on empirical correlations. Provided the estimated HRR, the location of the fire and the fire size could be obtained using an inverse modeling technique. Yet, the model is only suitable for one-room compartments. Based on a generic algorithm, Neviackas and Trouvé [5] obtained a generalized HRR which can be used to determine flashover conditions in multi-room geometries. Overholt and Ezekoye [6] also developed an inverse model using a predictor-corrected method. Based on smoke layer temperature measurements, the prediction accuracy of the model was shown to be within 60 s. However, a challenging problem exists in which all models [4-6] rely on complete measurement data sets acquired using laboratory equipment. In practical situations, sensors such as heat and/or smoke detectors will stop functioning at a certain elevated temperature [7]. If the required temperature/smoke data is missing, the estimated HRR obtained from these models will become highly uncertain and presumably, the prediction of flashover occurrence based on the estimated HRR will be unreliable.

Unlike the previous attempts [4-6], the temperature limitation for sensors, such as heat detectors, are considered in this present work with the objective to develop a machine learning model, P-Flash (Prediction model for Flashover occurrence) that can predict the flashover occurrence even with missing temperature data due to malfunctioning heat detectors. In the next section, the synthetic data being used to develop the model will first be described. Then, the model development of P-Flash will be presented. In order to demonstrate the prediction capability of P-Flash, two study cases are included, and Section 4 provides results and discussion. Section 5 provides additional model testing to highlight the current model limitation. Finally, some concluding remarks on P-Flash and future work are presented in Section 6.

2. Data Generation

Scarcity of real-world data from building sensors during fire events is one of the challenges for the use of the machine learning (ML) paradigm. The data problem has been raised in different literature, such as [7]. For the fire safety community, it can be noted that acquiring the desired sensor data is not trivial because 1) fire events do not happen frequently, 2) time series data associated with fire events in building environments are not available to the public data warehouse [8], and 3) physically conducting full-scale fire experiments in buildings such as [9] is extremely costly and time-consuming. Moreover, no prior research work has been carried out to provide guidance on the data requirements for ML applications. With that, there may be a high probability that the obtained experimental data is not usable. When the conventional ML paradigm demands a large amount of training data, the CFAST Fire Data Generator (CData) [10] is utilized to generate synthetic data to facilitate the use of ML paradigms for prediction of fire hazards in buildings.

In general, CData is a computational tool with its front-end written in Python¹. The code was developed to generate time series data for typical devices/sensors (i.e., heat detector, smoke detector, and other targets) in any user-specified fire environments within a building structure. CFAST [11] is used as the simulation engine in CData for two reasons. First, the fire simulation program is mathematically verified and is validated with experimental data [12]. The verification and validation (V&V) process is an active and continuous effort at the National Institute of Standards and Technology (NIST) to ensure the fidelity of the code. Second, CFAST is numerically efficient. Using the Fire Research Division computer cluster at NIST, more than ten thousand simulation cases with various geometric and fire configurations specified in this study can be completed in a single day. This advantage provides the flexibility and capability to conduct parametric studies for obtaining the most relevant and high quality synthetic data set for researching the use of ML paradigms. It should be noted that the authors² understood the inherent model assumptions being made in CFAST. When the feasibility of using synthetic data for the development of ML models is warranted, a more sophisticated fire simulation program, such as the Fire Dynamic Simulator [13], and/or even full-scale experimental data can be utilized in future studies. These higher fidelity data would allow the ML model to account for other realistic conditions, such as the effect of hot gas movement to the detectors, to improve the model performance.

2.1. Numerical Setup

Consider a single-story building with three compartments as shown in Fig. 1. The dimensions of Room 1 are $3.5 \text{ m} \times 3.5 \text{ m}$, and the dimensions of Room 2 and Corridor are $4.5 \text{ m} \times 4.5 \text{ m}$ and $3.5 \text{ m} \times 1 \text{ m}$, respectively. The ceiling height is 2.5 m, and it is identical for all compartments. For simplicity, the material of all walls, ceilings, and floors is gypsum wallboard. As seen in Fig. 1, there are 4 openings: 1) a window in Room 1, 2) a door between Room 1 and Corridor, 3) a door between Corridor and Room 2, and 4) an exit-door in Room 2. The openings are fully opened. There is one heat detector in every compartment, and they are all located at the center of each compartment about 4.5 cm away from the ceiling. The

¹ Certain commercial equipment, instruments, or materials are identified in this paper in order to specify the procedures adequately. Such identification is not intended to imply recommendation or endorsement by the National Institute of Standards and Technology, nor is it intended to imply that the materials or equipment identified are necessarily the best available for the purpose.

² Richard Peacock and Paul Reneke at NIST are both the principal investigators for continuous development and maintenance of CFAST.

response time index for the heat detector is 35 $(m \cdot s)^{0.5}$. The outdoor conditions are typical with the temperature at 20 °C and atmospheric pressure of 101 kPa. Table 1 provides the summary of the thermal properties of the gypsum wallboard and the geometric configurations of the openings.



Fig 1. Schematic of the single-story three compartments with a fire in action.

	Conductivity	Specific heat	Density	Thickness	Emissivity
	(W/[m·K])	(J/[kg·K])	(kg/m³)	(m)	(-)
Gypsum	0.276	1.017	752	0.0159	0.94
	Erom	То	\\/idth	Longth	Distance away
	FIOIII	10	wiath	Length	from ceiling
	(-)	(-)	(m)	(m)	(m)
Window	Room 1	Exterior	0.3	0.5	0.5
Door 1	Room 1	Corridor	0.75	2	0.5
Door 2	Corridor	Room 2	0.75	2	0.5
Exit door	Room 2	Exterior	0.75	2	0.5

Table 1. Summary of thermal properties and geometric configurations.

Given the experimental setup, a t-squared fire is placed at the center in Room 1. In this study, simple three-stage t-squared fires are considered. It has a growing stage, a plateau, and a decay stage. Basically, a fire will grow at a rate proportional to the time raised to the second power. When the fire reaches its peak, it will sustain for some time (denoted as plateau). It then dies down (denoted as fire decay) and is extinguished. Based on references provided in [14,15], a range of fires are selected to describe the fire growing stage. Figure 2 shows the scatter plot of peak heat release rate (HRR) and time to peak for the 1000 cases. It can be seen that the peak HRR and the time to peak ranges from approximately 50 kW to 2200 kW and from 50 s to

1400 s, respectively. The selected range of peak HRR and time to peak cover various burning items from an office trash can with a slow fire growth rate to an upholstered furniture fire with an ultra-fast fire growth rate. In terms of duration for plateau and fire decay, they are assumed to be constant. The duration for plateau and fire decay are set to be 2000 s and 1500 s, respectively.



Fig. 2. Scatter plot for peak HRR vs time to peak.

2.2. CData Settings

This subsection demonstrates how CData is utilized to configure fire cases as mentioned in Sec 2.1. Appendix A shows the complete CData input file being used in this study. In general, the CData input file has similar namelists to that of CFAST input files except that CData has additional namelists to facilitate data sampling. Based on the descriptions provided in the previous section, there are two varying conditions for fires: i) the peak HRR and ii) the time to peak HRR. In order to sample the desired fire conditions, a namelist, MRND, is used. As shown in the appendix, two lines of code are involved to sample fire conditions uniformly across the domain of interest. The corresponding information is summarized in the following table:

MRND							
ID	Distribution Type	Value Type	Minimum	Maximum			
Peak HRR Generator	Uniform	Real	50 000	2 200 000			
End of Growth Time Generator	Uniform	Real	75	1400			

Table 2. MRND that specifies random number generator for peak HRR and time to peak HRR.

There are five parameters in MRND: 1) ID, 2) distribution type, 3) value type, 4) minimum, and 5) maximum. The first parameter defines the unique name of the desired generator. The second parameter specifies the required distribution function which would be used for sampling. In the current version of CData [10], it supports 8 different well-defined distribution functions, such as uniform, triangle, normal, truncate normal, log normal, truncated log normal, beta, and linear. Since a set of uniformly distributed fire cases are needed to facilitate the model training, the uniform distribution is utilized. For value type, real number is chosen because the bounding conditions are expected to be defined by numerical values. Lastly, minimum and maximum specify the lower bound and the upper bound of the fire conditions, respectively.

The random number generators, Peak HRR Generator and End of Growth Time Generator, specify the fire growing stage. In order to construct the three-stage t-squared fires, another namelist, MFIR, is utilized to combine a number of MRND namelists to generate the namelist that CFAST would recognize. Specifically, the plateau and the fire decay are specified using Peak HHR (2nd value) and Plateau End Time, and End of Fire HRR and Fire End Time, respectively. Since the total number of 1000 cases³ are required, the parameter NUBMBER_OF_CASES from MHDR namelist is set to be 1000.

2.3. Data Profiles

For all simulation runs, a fire is started in Room 1. Subsequently, the upper layer gas temperature rises, and the layer thickness increases. Some hot gases leave the building structure, and some flow through the door. Air mixing between Room 1 and Corridor occurs. Due to the mixing, the upper gas layer temperature in Corridor also increases. Similar mass transfer and heat transfer processes take place between Corridor and Room 2, and the Room 2 upper gas layer temperature gradually rises. Figs. 3 show Room 1, Corridor, and Room 2 temperature profiles for two selecting cases: a) a fast growth fire with low peak HRR case and b) a medium growth fire with high peak HRR case. The total simulation time for each simulation run is 8400 s, and the temperature output interval is 20 s.



Fig. 3. Room 1, Corridor, and Room 2 temperature profiles for a) a fast growth fire with low peak HRR case and b) a medium growth fire with high peak HRR case.

³ The selected number of simulation runs was determined based on a parametric study. Five sets (100, 500, 1000, 2000, and 5000 cases) of data were considered. Using the experimental setup mentioned in Section 2.1, the model performance for the prediction of flashover achieves convergency when the number of cases reaches 1000 cases. The full dataset including all input files associated with the 1000 cases can be found at https://doi.org/10.18434/M32258.

Figure 4 shows the mean temperature profiles for the three detectors as a function of time. As shown in the figure, the temperature profiles in Corridor and Room 2 are lower than that of Room 1, and the dashed lines represent two times the standard deviation of detector temperature profiles. Although this study uses only temperature data, in principle other time series data such as smoke concentration obtained from smoke detectors, can also be used for the model development. Moreover, building structures with different compartments (in terms of quantity, orientation, and door connection) and fires involving various fire growth behavior can also be considered in the data generation so that a more generalized ML model can be developed for actual use. This research effort is under way, and the findings will be reported in future publications.



Fig. 4. Mean detector temperature profiles and its deviation in different compartments.

3. Model Development of P-Flash

Given a set of data, two additional steps including data preprocessing and model training are required for the development of P-Flash. Fig. 4 depicts the processes associated with the data preprocessing and the corresponding main codes are provided in Appendix B1.

3.1. Sequence Segmentation

Loss of detector temperature signal is one of the primary difficulties for the development of an accurate machine learning-based flashover prediction model. For actual fire scenarios, heat detectors cannot survive at elevated temperature [7] and would fail at temperatures well below the estimated flashover temperature (~ $600 \,^{\circ}$ C). It is well known that developing a ML model based on unphysical data significantly jeopardizes the model performance. With the malfunctioning detectors, the temperature can be unphysical, and a special treatment is needed to preprocess the data such that unphysical data can be eliminated.

Knowing that detectors⁴ stop functioning at elevated temperature (here assumed as 150 °C), the detailed view shown in Fig. 5 presents the temperature profiles from ideal detectors (dashed

⁴ In reference [16], there are 7 classes for heat detector. Each class has different maximum operating temperature range at the ceiling. The selected cut-off temperature (150 \mathbb{C}) is based on the *extra high* class heat detector.



Fig. 5. Machine learning pipeline for P-Flash (from raw data to feature extraction).

lines) and those with a cut-off temperature at $150 \,^{\circ}$ C (solid lines) for a simulation run with a fast-growth fire originating in Room 1. As shown in the plot, the available data for the detector in Room 1 is limited. At t_i , the temperature signal from Room 1 is lost. For simplicity, when the temperature signal is lost, the temperature is artificially turned into a constant in this study (i.e., a value of zero). In general, it is rather difficult for any models, even ML models, to provide any reliable flashover prediction with these limited temperature data (i.e., up to only $150 \,^{\circ}$ C). However, it is seen that temperature signals from other compartments do exist. Given this observation, it is believed that the use of the available temperature data from other compartments helps to "recover" the detector temperature in Room 1 which can be used to determine the flashover condition. In order to facilitate this process, a sequence segmentation is applied to the temperature data set.

Using the sequence segmentation, a new data structure is laid out. As shown in same plot, there are 3 vertical lines, dividing the temperature profiles into 4 phases. Each of the phases contains different available temperature signals. For example, signals from all detectors are present in Phase I ($t_0 - t_1$). In Phase II ($t_1 - t_2$), signals from only Corridor and Room 2 are available. In Phase III ($t_2 - t_3$), the last available signals are from Room 2. No temperature signals exist in Phase IV, and additional treatment is needed to facilitate the prediction of flashover conditions. Three benefits are found from using the segmented data: 1) the unphysical information due to any malfunctioning detectors is eliminated, 2) the ML model can take full advantage of the available data associated with a specified phase, and 3) the new data structure provides the basis for the model development of P-Flash. It is worth noting that only temperature data less than or equal to 150 °C are used for model development.

3.2. Feature Extraction

Feature extraction [17] is an essential ML task to facilitate the development of a model. In this process, the raw data (i.e., discrete temperature data which is uncorrelated in time) is transformed into a data set with a reduced number of variables which contains more discriminative information. An example of discriminative information can be the rate of change of temperature which relates the temperature increase over a period of time. It can be understood that a large rate of change in temperature indicates a higher chance of having more rapid fire growth which would possibly lead to a flashover if sufficient oxygen is available and the fire continues to grow. This higher level information facilitates the learning process for a ML model which helps develop a more accurate model.

The feature extraction section depicted in Fig. 5 shows the feature vectors⁵, *F*, being extracted from the detector temperature profiles in different phases, and there are five different feature vectors: F_{p1}^{Corr} , F_{p2}^{R2} , F_{p2}^{Corr} , F_{p2}^{R2} , and F_{p3}^{R2} . In terms of notation, the superscript denotes the extracted features corresponding to the compartment, and the subscript denotes the extracted features associated with a specific phase. For general practice, the construction of features and the required number of feature vectors are based on three factors: 1) the structure of the data (refer to Section 3.1), 2) how often the prediction is needed, and 3) the architecture of the ML model.

In Phase I, since no prediction is required, the features are extracted based on a complete timewindow with the intention of encoding the relationships among the temperatures associated

⁵ A feature vector contains a number of different features.

with Room 1 (T^{R_1}), Corridor (T^{Corr}), and Room 2 (T^{R_2}). In this study, two types of features are obtained, and they are temperature-based features and trend-based features. Table 3 provides a list of extracted features. In ML, the temperature based-features provide the overall statistics of the temperature data and the trend based-features provide the overall temperature behavior with respect of time. For example, the temperature-based feature, *mean of* $T^X(t_0:t_1)$, can be understood as the average temperature in between t_0 and t_1 . For the trend-based feature, the dT^X/dt represents the first derivative of temperature which describes the rate of change of temperature over a period of time. The superscript X describes three different compartments: Room 1 (R1), Corridor (Corr), and Room 2 (R2). It should be noted that the differential time (dt) being used to obtain the first derivative of the temperature is different than the length of the complete time-window. Since the overall behavior of the temperature profile is relatively smooth, the differential time is taken to be one time-step (20 s). As shown in the table, six different features are being extracted in Phase I, and they are added to form the feature vector.

	Phase I	Phase II	Phase III
Temperature-	Mean and Max.	Mean and Max.	Mean and Max.
based	of	of	of
features	$T^X(t_0:t_1)$	$T^{Y}(t_{i}:t_{i+rolling_window})$	T ^Z (t _i :t _{i+rolling_window})
Turad based	Min., Mean, and Max.	Min., Mean, and Max.	Min., Mean, and Max.
	of	of	of
	dT^X/dt	dT^{Y}/dt	dT ^z /dt
features	Index of Max.	Index of Max.	Index of Max.
	of	of	of
	dT^X/dt	dT^{Y}/dt	dT^Z/dt
	divided by length of	divided by length of	divided by length of
	fixed window	rolling window	rolling window

Table 3. Summary of extracted features.

X represents R1, Corr, and R2. Y represents Corr and R2 and Z represents R2. The abbreviation Min. and Max. denotes minimum and maximum, respectively.

In Phase II and III, although similar process is being carried out, the extracted features are obtained based on a rolling window [17]. Basically, the rolling window contains a sub-data set. After a feature extraction is executed, the window shifts onwards for one time-step. A numerical experiment is conducted to determine the optimal size of the rolling window. For real-time detection, the window size is taken to be six time-steps. In general, the use of rolling windows helps to provide extracted features containing more localized information. For Phase IV, since no temperature data is available, no features are being extracted. It is worth noting that the symbol, \bigoplus , as shown in Fig. 4 represents concatenation of two vectors. When the feature extraction process is complete, three feature vectors: $(1) = F_{p1}^{Corr} \oplus F_{p2}^{Corr}$, $(2) = F_{p1}^{R2} \oplus F_{p2}^{R2}$, and $(3) = F_{p1}^{R2} \oplus F_{p3}^{R2}$, are obtained, and they are used to train/develop the models for P-Flash. In the next section, the descriptions of model training are presented. It should also

be noted that feature selection, such as use of collinearity check and variable importance, can be made to select the features that contribute the most to the predictions. The corresponding source codes for data pre-processing and feature extraction are provided in Appendix B3.

3.3. Training and Testing

Figure 6 depicts the overview of the model architecture for P-Flash. P-Flash consists of two regression models (R_{cor} and R_{R2}) and a memory component (M). The primary difference between the two models is that R_{cor} is trained based on feature vector ①, and R_{R2} is trained based on feature vectors ② and ③. In theory, a single regression model might work. However, the training process for such a model involving more information is numerically more difficult and overfitting⁶ might occur and this is attributed to the fact that all the temperature behaviors from three different sensors will have to be learned by only one regression model. Since using either of the approaches (two regression models or single regression model) will provide relatively the same prediction, the two regression model approach is utilized for training efficiency. The memory component, M, is a hybrid module: it performs as a storage to contain outputs from R_{corr} and R_{R2} and provides temperature prediction of Room 1 based on the historical information. This model architecture provides robust and flexible prediction capabilities to adapt to more complex cases with a larger number and different types of detectors.



Fig. 6. The overview of model architecture for P-Flash.

Due to the fact that the model first sees temperature data of three compartments for Phase I and Phase II, both regression models, R_{Corr} and R_{R2} , are executed simultaneously and two separate temperature predictions for Room 1 in Phase II are obtained. In order to compensate for the numeric difference, averaging is conducted, and the temperature prediction is stored in the memory component. Since only the temperature in Room 2 exists in Phase III, only R_{R2} is executed and the temperature of Room 1 in Phase III is obtained. Similarly, the output is stored in the memory component. The ML algorithm being used for training and the details of model testing are provided in the next subsection.

⁶ Overfitting is a modeling error that occurs when a function is too closely fit to a limited set of data points. For example, rather than learning the overall trend inherent to the data set, the model attempts to memorize the noise from the data.

3.3.1. Regression Models

Support vector regression (SVR) [18] is used to develop the two regression models (R_{corr} and R_{R2}). Fundamentally, SVR finds a decision boundary, known as a hyperplane, to correlate data instances and maximizes the constrained margin such that the distance between the data instances is optimal to achieve greatest model generalizability. For example, given a training dataset $T = \{(X_1, y_1), (X_2, y_2), ..., (X_n, y_n)\}$ which can be linearly separated, the hyperplane denoted as p can be written as:

$$w \bullet X + b = 0 \tag{1}$$

where X_n is the sample of n^{th} instance and y_n is the target/ground truth. In this study, X_n will be the three feature vectors and y_n will be the Room 1 temperature. w and b are the weight and the bias of the hyperplane, respectively. Based on the definition provided in [19], the distance between the instances for different classes is:

$$d = \min_{i=1,2,...,n} y_i(\frac{w}{\|w\|} \cdot X_i + \frac{b}{\|w\|})$$
(2)

where ||w|| is norm of w. For SVR, the distance is known as margin. Therefore, SVR determines the hyperplane with the largest margin by solving the optimization problem:

$$\arg\max_{w,b} (\min_{i=1,2,...,n} y_i(\frac{w}{\|w\|} \cdot X_i + \frac{b}{\|w\|}))$$
(3)

Figure 7a provides an example case with data in linear behavior. The hyperplane is obtained to best correlate the data and the margin is determined to include each data point. As shown in the figure, this form of SVR is similar to the best of fit with a simple linear regression.



Figs. 7. Example of a regression model from a) a linear SVR and b) non-linear SVR.

For real-life applications, fire data are often more complex, and they are not linearly separable (See Fig. 7b). In order to overcome the numerical difficulty, there are two options. The first option is called the "kernel trick" [19], and there are four commonly used nonlinear kernel

functions: 1) polynomial kernel, 2) Gaussian kernel, 3) radial basis function (RBF), and 4) sigmoid kernel. The use of a kernel function allows the transformation of data into a higher dimensional space such that the instances X_n for different classes separated by a hyperplane (i.e., nonlinear) exists. The second option is to introduce a regularization/slack variable. With the implementation for the regularization variable, C, a small proportion of the data are ignored (see ξ in Fig. 7b). Although there is trade-off for the use of these options, it generally provides a more generalized model and helps to avoid over-fitting. This implies the situation where the model only memorizes the data without obtaining any useful patterns and relationships for the data behavior. If over-fitting occurs, the model performance will be very poor.

In this study, a 5-fold cross validation method [8] is utilized to facilitate the training and testing process. In principle, the entire dataset from 1000 simulation runs is randomly divided into five subsets, and each subset/fold contains 200 sessions. In general, one fold of data is being used as testing data, and the remaining four folds are being used as training data. This process is carried out iteratively for five times until all five different folds of data are being used as the testing set. The trained regression models provide Room 1 temperature predictions in Phase II to Phase III. Utilizing grid search [8], the optimal configurations for SVR are C = 1000 and Gamma = 0.05 with RBF kernel. The corresponding source codes for the development of the two regression models are provided in Appendix B4.

3.3.2. Learning from Fitting

In Phase IV, since all detectors are lost, no inputs are available, and therefore no reliable predictions can be made from the regression models. In order to overcome this physical limit, learning from fitting is implemented to facilitate the extrapolation of the temperature in Room 1 using the historical data (i.e., the available temperature in Phase I and predicted temperature obtained in Phase II and III). Given the current set of data, there can be two possible scenarios in Phase IV: 1) a scenario where the predicted temperature of Room 1 is sufficiently long enough to observe a logarithmic temperature increase or 2) the fire is so large (in terms of peak HRR with short time to peak) that the temperature rise appears to be an exponential function. For that, two mathematical expressions, a sigmoidal binding function and a 5th order polynomial, are considered. The sigmoidal binding function is used for the first scenario:

$$p_i = (b\sqrt{t_i})/(\sqrt{t_i} + a) + c \tag{4}$$

whereas the high order polynomial is used for the second scenario:

$$p_i = d_5 t_i^5 + d_4 t_i^4 + d_3 t_i^3 + d_2 t_i^2 + d_1 t_i + d_0 f$$
⁽⁵⁾

where p_i is the prediction and t_i is the time associated with index *i*. Optimization is carried to obtain *a*, *b*, *c*, and *d* to produce a best fit to generalize the Room 1 temperature data in Phase I to III. Given the best fit, Room 1 temperature in Phase IV can be extrapolated. The corresponding source codes for carrying out the fitting are provided in Appendix B5.

4. Results and Discussion

Figures 8 show the temperature predictions obtained from P-Flash for two selected cases: 1) a fast growth fire with low peak HRR case and 2) a medium growth fire with high peak HRR case. There are three sets of curves in each figure: i) ground truth/Room 1 temperature, ii) prediction with learning from fitting (LFF), and iii) prediction without LFF. For each prediction curve, it can be composed of up to two lines: a) red line represents the Room 1 temperature predictions associated with Phase II and III and b) blue line is for predictions in Phase IV. Since no prediction is needed for Phase I, comparison is omitted.

In Fig.8a, it can be seen that P-Flash provides accurate temperature predictions of Room 1 in all phases, and the benefit of using LFF is noticeable. After approximately 1150 s, when all detectors are lost, P-Flash is still capable to provide predictions with similar trend and magnitude. For P-Flash without LFF, the prediction relies on the regression models, and it can be shown that the temperature prediction is unrealistic (i.e., showing a temperature increase to as high as 910 °C). This observation demonstrates that unphysical inputs will lead to unphysical outputs. Also, it is worth noting that the discrepancy observed at around 250 s is probably due to the change of temperature increase in the available detector temperature. Physically, it is the pivot point of its 1st derivative where the rate of change of temperature changes from positive sign to negative sign. Additional effort is under way to reduce such fluctuation.

In Fig. 8b, it can be seen that the temperature of Room 1 being recovered from Phase II and III is still growing exponentially. In the current version, P-Flash does not have additional information to predict the temperature decays. However, it is capable to project the temperature increase in which the determination of flashover (i.e., temperature approaching 600 °C) in Room 1 can be made. As shown in the figure, the results obtained based on P-Flash without LFF are over-estimated.



Fig. 8. Comparison between ground truth and predictions obtained from P-Flash with and without LFF.

In order to evaluate the model performance over the 1000 different cases, the mean absolute error (MAE) is being determined, and it is defined as:

$$MAE = \sum_{i=1}^{m} \frac{1}{m} \sum_{j=1}^{n_i} \frac{1}{n_i} \left| p_{i,j} - y_{i,j} \right|$$
(6)

where p is the prediction and y is the ground truth. The variables m and n represent the number of simulation runs and the number of prediction points for each phase associated to each case, respectively. The number of simulation runs is 1000 in this study, and since the extrapolation of a 5th order polynomial increases dramatically, the number of prediction points for each case in Phase IV is determined based on the flashover temperature condition. That means the comparison is omitted if the ground truth is larger than 600 °C. Table 4 shows the MAE associated with different phases. It should be noted that the above results are denoted as "current prediction" and this is due to the fact that the prediction at time t is based on information obtained in time t.

Given the prediction and the ground truth, an additional assessment can be carried out to examine the overall model accuracy in terms of flashover occurrence prediction. The flashover occurrence is true when the temperature is larger than 600 °C. The overall accuracy is determined as the ratio of correct prediction within 20 s of the time of flashover to the total number of flashover occurrence in 1000 cases. Two example cases can be found in Figs. 8. In case 1, since the ground truth does not meet the potential flashover occurrence criteria (i.e., ~ 600°C), no flashover is observed. As compared to prediction from P-Flash, the recovered Room 1 temperature does not meet the potential flashover occurrence, false to flashover is also observed. For that, the prediction from P-Flash is determined to be correct. In case 2, a potential flashover occurrence is observed at about 1050 s. However, the recovered Room 1 temperature based on P-Flash does not reach 600 °C at that time stamp. For that, P-Flash fails to predict the potential occurrence of flashover and this is a miss prediction. In order to discriminate the miss prediction, it is further divided into two categories: i) early prediction and ii) late prediction where the early prediction and the late prediction indicate that the Room 1 temperature recovered based on P-Flash reaches flashover occurrence criteria about more than 20 s prior to or more than 20 s after the flashover condition is met based on the ground true, respectively. Table 5 shows the overall model accuracy for the prediction of flashover occurrence to be approximately 83 %. The early prediction and the late prediction are shown to be 8 % and 9 %, respectively.

Since the current model is developed simple fire and vent opening conditions, Appendix C presents additional evaluation to reveal the current limitation of P-Flash and to provide guidelines about data requirement for the development of a more robust flashover prediction model in multi-compartment buildings.

	Phase II	Phase III	Phase IV
	MAE (C)	MAE (C)	MAE (C)
Current Prediction	11	13	30
Future Prediction	13	16	37

Table 4. Performance summary for P-Flash.

	Accuracy	Early	Late
	%	%	%
Current Prediction	83	8	9
Future Prediction	81	15	4

Table 5. Overall model accuracy with early and late prediction for potential occurrence of flashover.

In actual firefighting, it is best if fire fighters can obtain the condition of the room of the fire origin ahead of time because they can optimize their rescue strategies and fire fighting tactics. For that, it is interesting to examine how well P-Flash can forecast temperature in advance (i.e., 150 s). In this scenario, the prediction at time t+150 s is based on information obtained in time t. Since the temperature information for all compartments tends to have a monotonic increasing behavior, the temperature relationship at current time, t, can correlate well with flashover occurrence in future time, t+150 s. As shown in Table 3 and Table 5, the MAE associated with this kind of scenario (denoted as future prediction) only increases slightly and the overall accuracy of P-Flash is relatively the same. These observations are expected as the temperature increase behaviors are well captured by the regression models and the fittings. However, the early prediction for the future prediction cases has noticeable increase and this is due to the fact that the temperature information being used generally has large temperature increase rate at time, t, as compared to time, t+150 s.

5. Conclusions and Outlook

The development of P-Flash is presented. The realistic treatment of modeled sensor data that is not continuously available, but is subject to data loss due to thermal failure, though a challenge, was shown to be overcome successfully by the SVR modeling techniques and P-Flash is capable of recovering required detector temperatures for the determination of flashover conditions in the room of fire origin. P-Flash is under further development to handle more realistic conditions and these conditions include realistic multi-compartment building structures, fire located in any compartments, experimentally validated fire growth behavior of burning items, arbitrary vent opening conditions for windows and doors, and sensor limits. In order to facilitate data-driven fire fighting, collaborative works are required to develop smart fire protection systems and/or information transmission infrastructure. In the near future, P-Flash or a similar forecasting model could provide fire fighters with trustworthy and actionable information about fire scenes under the cognomen smart firefighting.

Acknowledgments

The authors wish to thank Dr. Michael Huang for helpful discussion.

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Appendix A: CData Input File

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RTI = 35 / &DEVC ID = 'HD1_5_7' COMP_ID = 'Comp 3' LOCATION = 1.15, 2.95, 1.865 TYPE = 'HEAT_DETECTOR' SETPOINT = 65, RTI = 35 / &DEVC ID = 'HD1_6_1' COMP_ID = 'Comp 3' LOCATION = 1.75, 2.95, 2.465 TYPE = 'HEAT_DETECTOR' SETPOINT = 65, RTI = 35 / &DEVC ID = 'HD1 6 2' COMP ID = 'Comp 3' LOCATION = 1.75, 2.95, 2.365 TYPE = 'HEAT DETECTOR' SETPOINT = 65, RTI = 35 / &DEVC ID = 'HD1_6_3' COMP_ID = 'Comp 3' LOCATION = 1.75, 2.95, 2.265 TYPE = 'HEAT_DETECTOR' SETPOINT = 65, RTI = 35 / &DEVC ID = 'HD1_6_4' COMP_ID = 'Comp 3' LOCATION = 1.75, 2.95, 2.165 TYPE = 'HEAT_DETECTOR' SETPOINT = 65, RTI = 35 / &DEVC ID = 'HD1_6_5' COMP_ID = 'Comp 3' LOCATION = 1.75, 2.95, 2.065 TYPE = 'HEAT_DETECTOR' SETPOINT = 65, RTI = 35 / &DEVC ID = 'HD1 6 6' COMP ID = 'Comp 3' LOCATION = 1.75, 2.95, 1.965 TYPE = 'HEAT DETECTOR' SETPOINT = 65, RTI = 35 / &DEVC ID = 'HD1_6_7' COMP_ID = 'Comp 3' LOCATION = 1.75, 2.95, 1.865 TYPE = 'HEAT_DETECTOR' SETPOINT = 65, RTI = 35 / &DEVC ID = 'HD1_7_1' COMP_ID = 'Comp 3' LOCATION = 3.45, 3, 1.95 TYPE = 'HEAT_DETECTOR' SETPOINT = 65, RTI = 35 / &DEVC ID = 'HD2_1_1' COMP_ID = 'Comp 2' LOCATION = 0.5, 1.75, 2.465 TYPE = 'HEAT_DETECTOR' SETPOINT = 65, RTI = 40 / &DEVC ID = 'HD2_1_2' COMP_ID = 'Comp 2' LOCATION = 0.5, 1.75, 2.465 TYPE = 'HEAT_DETECTOR' SETPOINT = 65, RTI = 35 / &DEVC ID = 'HD2_1_3' COMP_ID = 'Comp 2' LOCATION = 0.5, 1.75, 2.465 TYPE = 'HEAT_DETECTOR' SETPOINT = 65, RTI = 30 / &DEVC ID = 'HD2_1_4' COMP_ID = 'Comp 2' LOCATION = 0.5, 1.75, 2.465 TYPE = 'HEAT_DETECTOR' SETPOINT = 65, RTI = 25 / &DEVC ID = 'HD2_1_5' COMP_ID = 'Comp 2' LOCATION = 0.5, 1.75, 2.465 TYPE = 'HEAT_DETECTOR' SETPOINT = 65, RTI = 20 / &DEVC ID = 'HD2 1 6' COMP ID = 'Comp 2' LOCATION = 0.5, 1.75, 2.465 TYPE = 'HEAT DETECTOR' SETPOINT = 65, RTI = 15 / &DEVC ID = 'HD2_2_1' COMP_ID = 'COMP 2' LOCATION = 0.05, 3, 1.95 TYPE = 'HEAT_DETECTOR' SETPOINT = 65, RTI = 35 / &DEVC ID = 'HD2_3_1' COMP_ID = 'Comp 2' LOCATION = 0.5, 0.05, 1.95 TYPE = 'HEAT_DETECTOR' SETPOINT = 65, RTI = 35 / &DEVC ID = 'HD3_1_1' COMP_ID = 'Comp 1' LOCATION = 2, 2, 2.465 TYPE = 'HEAT_DETECTOR' SETPOINT = 65, RTI = 40 / &DEVC ID = 'HD3_1_2' COMP_ID = 'Comp 1' LOCATION = 2, 2, 2.465 TYPE = 'HEAT_DETECTOR' SETPOINT = 65, RTI = 35 / &DEVC ID = 'HD3_1_3' COMP_ID = 'Comp 1' LOCATION = 2, 2, 2.465 TYPE = 'HEAT_DETECTOR' SETPOINT = 65, RTI = 30 / &DEVC ID = 'HD3_1_4' COMP_ID = 'Comp 1' LOCATION = 2, 2, 2.465 TYPE = 'HEAT_DETECTOR' SETPOINT = 65, RTI = 25 / &DEVC ID = 'HD3 1 5' COMP ID = 'Comp 1' LOCATION = 2, 2, 2.465 TYPE = 'HEAT DETECTOR' SETPOINT = 65, RTI = 20 / &DEVC ID = 'HD3_1_6' COMP_ID = 'Comp 1' LOCATION = 2, 2, 2.465 TYPE = 'HEAT_DETECTOR' SETPOINT = 65, RTI = 15 / &DEVC ID = 'HD3_2_1' COMP_ID = 'Comp 1' LOCATION = 4, 4.45, 1.95 TYPE = 'HEAT_DETECTOR' SETPOINT = 65, RTI = 35 /

&TAIL /

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Appendix B: P-Flash Source Codes

Appendix B consists of 5 parts: B1 to B5. Appendix B1 provides the main codes for P-Flash. Appendix B2 presents codes that read the data and assign them to an appropriate format. Appendix B3 provides codes for data pre-processing and feature extraction. Appendix B4 provides codes for model training and testing. Appendix B5 presents codes for the memory component and fitting. The logic flow of the codes strictly follows the model descriptions provided in the main text.

To execute the codes, the reader only needs the original data which can be downloaded from <u>https://doi.org/10.18434/M32258</u> and combines the codes in a single file.

Appendix B1: Main

Load libraries import numpy as np from sklearn.svm import SVR from sklearn.preprocessing import StandardScaler from sklearn.model selection import GridSearchCV from sklearn.metrics import mean_absolute_error from scipy.optimize import curve_fit # Load scripts import CsvReader import Utility # Main codes # Input files DataFile = 'C:\\Users\\xxx\\IdeaProjects\\3compartment\\Inputs\\case1000.csv' # Output locations resultDir = 'C:\\Users\\xxx\\IdeaProjects\\3compartment\\Results\\' # Cross-validation setting CV = 5

2 major steps are done here: data pro-processing and feature extraction # Look at Appendix B2 and B3 SP = SignalPreprocessing(DataFile, resultDir) # Get only allInstances allInstances = SP.allInstances

Construct appropriate training and testing sets for "current" prediction or "future" prediction learningTestingDict, TestInstancesGroup = Instance.Instances2GroupLists_multiRoomV3(Instances = allInstances, cv=CV, typeLabel= 'current') # or Future

Start to carry out training and testing for the 5 different subsets (CV = 5) # Another 2 major steps are done here: modeling development and fitting # Look at Appendix B4 and B5 for i in range(0, CV): Xs_train_fast = learningTestingDict['fast_train'][0][i] y_train_fast = learningTestingDict['fast_train'][1][i] Xs_test_fast = learningTestingDict['fast_test'][0][i] y_test_fast = learningTestingDict['fast_test'][1][i] Xs_train_slow = learningTestingDict['slow_train'][0][i] y_train_slow = learningTestingDict['slow_train'][1][i] Xs_test_slow = learningTestingDict['slow_test'][0][i] y_test_slow = learningTestingDict['slow_test'][1][i]

TestInstances = TestInstancesGroup[i]

```
# Normalization
scaler_fast = StandardScaler()
Xs_train_fast = scaler_fast.fit_transform(Xs_train_fast)
Xs_test_fast = scaler_fast.transform(Xs_test_fast)
scaler_slow = StandardScaler()
Xs_train_slow = scaler_slow.fit_transform(Xs_train_slow)
Xs_test_slow = scaler_slow.transform(Xs_test_slow)
```

```
# Initialize model
FTR = FireTemperatureRegression()
# 2 SVR models: r1 and r2
# r1 exists in Phase 2
# r2 exists in Phase 2 and 3
FTR.fit(
  Xs r1 = Xs train fast,
  y r1 = y train fast,
  Xs_r2 = Xs_train_slow,
  y_r2 = y_train_slow
)
for i test in range(0, len(TestInstances)):
  testI = TestInstances[i test]
  if len(testI[2]) > 0:
    currentID = testI[-1]
    # Carrying out fitting
    predict_values, real_values, p2, r2, p3, r3, p23, r23, p4, r4, fit_type = FTR.predict_instancesV2(
       fvs_fast = testI[0],
       fvs\_slow = testI[1],
       reals = testI[2],
       types = testI[3],
       ts = testI[5],
```

```
scale_fast = scaler_fast,
scale_slow = scaler_slow
)
# Determine overall MAE in Phase 2 to Phase 4
MAE, num = FTR.getMAE(predict_values, real_values)
# Determine MAE in Phase 2 only
try:
MAE_p2, _ = FTR.getMAE(p2, r2)
except ValueError:
MAE_p2 = 0
# Determine MAE in Phase 3 only
MAE_p3, _ = FTR.getMAE(p3, r3)
# Determine overall MAE in Phase 2 and 3
```

MAE_p23, _ = FTR.getMAE(p23, r23) # Determine MAE in Phase 4 only MAE_p4, _ = FTR.getMAE(p4, r4)

End of Main codes

```
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```

Appendix B2: Read Data

```
# Step 1 to get data
class SignalPreprocessing(object):
  # Getting raw data
  def __init__(self, signal_fn, resultDir):
     readingModule = CsvReader.CsvReader(signal_fn)
     Data = readingModule.getData(
       indexs = [0,1,2,3,4,5],
       hasHeader = 1.
       needHandleNegativeOneIndex = [],
       flag = None
    )
    self.ids_list = Data[0]
     self.times_list = Data[1]
    self.t1s_list = Data[2]
     self.t2s_list = Data[3]
     self.t3s_list = Data[4]
     self.tps_list = Data[5]
     self._buildInstances()
  def _buildInstances(self):
     self.allInstances = []
    temp_ids = []
     idxRanges = []
     lastID = self.ids_list[0]
     startIdx = 0
     for i in range(0, len(self.ids_list)):
       print(i)
       currentID = self.ids_list[i]
       if currentID != lastID:
          endIdx = i
          idxRanges.append([startIdx, endIdx])
          temp_ids.append(lastID)
         # Refresh
         lastID = currentID
          startIdx = i
```

```
# Append last one
idxRanges.append([startIdx, len(self.ids_list)])
temp_ids.append(lastID)
for i in range(0, len(idxRanges)):
    print(i)
    currentRng = idxRanges[i]
    newInstance = Instance(
        temp_ids[i],
        self.times_list[currentRng[0]: currentRng[1]],
        self.t1s_list[currentRng[0]: currentRng[1]],
        self.t2s_list[currentRng[0]: currentRng[1]],
        self.t3s_list[currentRng[0]: currentRng[1]],
        self.t9_list[currentRng[0]: currentRng[1]],
        self.t9_list[currentRng[0]: currentRng[1]],
        self.t9_list[currentRng[0]: currentRng[1]])
        self.allInstances.append(newInstance)
# End of step 1
```

Appendix B3: Data Pre-Processing and Feature Extraction

```
# Step 2 to do data pre-processing and feature extraction
class Instance(object):
  @staticmethod
  def Instances2GroupLists multiRoomV3(Instances, cv, typeLabel):
    Xs_train_group_fastRoom = []
    Xs_test_group_fastRoom = []
    y_train_group_fastRoom = []
    y_test_group_fastRoom = []
    Xs_train_group_slowRoom = []
    Xs_test_group_slowRoom = []
    y_train_group_slowRoom = []
    y_test_group_slowRoom = []
    TestInstances group = []
    totalLength = len(Instances)
    step = totalLength / float(cv)
    chunkIdxs = np.arange(0, totalLength, step).tolist()
    for i in range(0, len(chunkIdxs)):
      startIdx = chunkIdxs[i]
      if i + 1 < len(chunkIdxs):
         endIdx = chunkIdxs[i + 1]
      else:
         endIdx = len(Instances)
      # Training and Testing subsets
      # Build Xs and Ys
      Xs_train_fast = []
      Xs_test_fast = []
      Xs train slow = []
      Xs_test_slow = []
      # -----
      y train fast = []
      y_test_fast = []
      y_train_slow = []
      y test slow = []
      # -----
      TestInstance = []
      # -----
```

```
for i_instance in range(0, len(Instances)):
  currentInstance = Instances[i instance]
  if i instance >= startIdx and i instance < endIdx:
     Xs_test_slow.extend(currentInstance.instances_r1_fvs)
     Xs test fast.extend(currentInstance.instances r2 fvs)
     if typeLabel == 'current':
       currentTestInstance = [
          currentInstance.test_fvs_fast_current,
          currentInstance.test_fvs_slow_current,
          currentInstance.test Labels current,
          currentInstance.test types current,
          currentInstance.times_refine[currentInstance.thresholdPoint_t1],
          currentInstance.test_t_current,
          currentInstance.id
       1
       TestInstance.append(currentTestInstance)
     else:
        currentTestInstance = [
          currentInstance.test_fvs_fast_future,
          currentInstance.test fvs slow future,
          currentInstance.test_Labels_future,
          currentInstance.test_types_future,
          currentInstance.times refine[currentInstance.thresholdPoint t1],
          currentInstance.test t future,
          currentInstance.id
        1
       TestInstance.append(currentTestInstance)
  else:
     Xs train slow.extend(currentInstance.instances r1 fvs)
     Xs_train_fast.extend(currentInstance.instances_r2_fvs)
     if typeLabel == 'current':
       y train slow.extend(currentInstance.regression r1 lb0s)
       y train fast.extend(currentInstance.regression r2 lb0s)
     else:
       y_train_slow.extend(currentInstance.regression_r1_lbns)
       y_train_fast.extend(currentInstance.regression_r2_lbns)
Xs train group fastRoom.append(Xs train fast)
```

```
Xs_test_group_fastRoom.append(Xs_test_fast)
```

y_train_group_fastRoom.append(y_train_fast) y_test_group_fastRoom.append(y_test_fast) Xs_train_group_slowRoom.append(Xs_train_slow) Xs_test_group_slowRoom.append(Xs_test_slow) y train group slowRoom.append(y train slow) y test group slowRoom.append(y test slow) TestInstances_group.append(TestInstance) return { 'fast_train': [Xs_train_group_fastRoom, y_train_group_fastRoom], 'fast_test': [Xs_test_group_fastRoom, y_test_group_fastRoom], 'slow_train': [Xs_train_group_slowRoom, y_train_group_slowRoom], 'slow_test': [Xs_test_group_slowRoom, y_test_group_slowRoom] }, TestInstances_group # Carrying out data pre-processing def __init__(self, id, times, t1s, t2s, t3s, ps, threshold=150, predictTempThreshold=600): # Read values self.id = idself.times = times self.t1s = t1s self.t2s = t2sself.t3s = t3sself.ps = psself.threshold = threshold self.predictTempThreshold = predictTempThreshold # Process starts here self._preprocess() self._determine_labels() self. applyTemperatureThreshold() self. extract features flash() self._extractRegressionFeaturesAndLabels(3, 6) self. buildPhaseTimeRanges() self. buildTestingInstance(3, 6) print('d') def _preprocess(self): flag = (self.ps[0] == self.ps[1])while flag: self.times = self.times[1:]

```
self.t1s = self.t1s[1:]
  self.t2s = self.t2s[1:]
  self.t3s = self.t3s[1:]
  self.ps = self.ps[1:]
  flag = (self.ps[0] == self.ps[1])
# Get front data value (for refine use)
self.front_p = float(self.ps[0])
self.front t1 = float(self.t1s[0])
self.front_t2 = float(self.t2s[0])
self.front_t3 = float(self.t3s[0])
# Convert to float
self.times = [float(ele) - float(self.times[0]) for ele in self.times]
self.t1s = [float(ele) - float(self.t1s[0]) for ele in self.t1s]
self.t2s = [float(ele) - float(self.t2s[0]) for ele in self.t2s]
self.t3s = [float(ele) - float(self.t3s[0]) for ele in self.t3s]
self.ps = [float(ele) - float(self.ps[0]) for ele in self.ps]
# Recover original signal
self.ps_ori = [e+self.front_p for e in self.ps]
self.t1s_ori = [e+self.front_t1 for e in self.t1s]
self.t2s ori = [e+self.front t2 for e in self.t2s]
self.t3s_ori = [e+self.front_t3 for e in self.t3s]
# Cut off right hand part
flag = (self.ps[-1] < self.ps[-2])
while flag:
  self.times = self.times[:-1]
  self.t1s = self.t1s[:-1]
  self.t2s = self.t2s[:-1]
  self.t3s = self.t3s[:-1]
  self.ps = self.ps[:-1]
  flag = (self.ps[-1] < self.ps[-2])
# Generate other basic features
self.times_diff = self.times[1:]
self.diff ps = np.diff(np.array(self.ps)).tolist()
self.diff_t1s = np.diff(np.array(self.t1s)).tolist()
self.diff_t2s = np.diff(np.array(self.t2s)).tolist()
self.diff_t3s = np.diff(np.array(self.t3s)).tolist()
# Smoothing
self.diff ps = Utility.move average(self.diff ps, 4)
self.diff t1s = Utility.move average(self.diff t1s, 4)
```

```
self.diff_t2s = Utility.move_average(self.diff_t2s, 4)
  self.diff_t3s = Utility.move_average(self.diff_t3s, 4)
  # Padding
  self.times_gap = []
  self.t1s_gap = []
  self.t2s_gap = []
  self.t3s_gap = []
  for i in range(0, len(self.times)):
    self.times_gap.append(self.times[i])
    self.t1s_gap.append(self.ps_ori[i] - self.t1s_ori[i])
    self.t2s_gap.append(self.ps_ori[i] - self.t2s_ori[i])
    self.t3s_gap.append(self.ps_ori[i] - self.t3s_ori[i])
  print('d')
# Assign labels
def _determine_labels(self):
  if max(self.ps) >= self.predictTempThreshold:
     self.isFlash = True
  else:
     self.isFlash = False
# Apply temperature threshold
def applyTemperatureThreshold(self):
  self.times_refine = []
  self.ps_refine = []
  self.t1s_refine = []
  self.t2s_refine = []
  self.t3s_refine = []
  self.thresholdPoint p = None
  self.thresholdPoint t1 = None
  self.thresholdPoint_t2 = None
  self.thresholdPoint t3 = None
  for i in range(0, len(self.times)):
    self.times_refine.append(self.times[i])
    # Apply threshold
    current_p = self.ps[i] + self.front_p
    current_t1 = self.t1s[i] + self.front_t1
    current t2 = self.t2s[i] + self.front t2
```

```
current_t3 = self.t3s[i] + self.front_t3
     if current p < self.threshold:
       self.ps_refine.append(current_p)
     else:
       self.ps refine.append(-1)
       if self.thresholdPoint p == None:
          self.thresholdPoint_p = i
    if current t1 < self.threshold:
       self.t1s_refine.append(current_t1)
    else:
       self.t1s refine.append(-1)
       if self.thresholdPoint t1 == None:
          self.thresholdPoint t1 = i
    if current t_2 < self.threshold:
       self.t2s refine.append(current t2)
    else:
       self.t2s_refine.append(-1)
       if self.thresholdPoint_t2 == None:
          self.thresholdPoint_t2 = i
    if current t3 < self.threshold:
       self.t3s refine.append(current t3)
    else:
       self.t3s refine.append(-1)
       if self.thresholdPoint t3 == None:
          self.thresholdPoint t3 = i
# Construct different phases
def _buildPhaseTimeRanges(self):
  if self.thresholdPoint p == None:
     self.thresholdPoint p = len(self.times refine)-1
  if self.thresholdPoint_t1 == None:
     self.thresholdPoint t1 = len(self.times refine)-1
  if self.thresholdPoint t2 == None:
     self.thresholdPoint_t2 = len(self.times_refine)-1
  self.phase1Range = [self.times_refine[self.thresholdPoint_p], self.times_refine[self.thresholdPoint_t2]]
  self.phase2Range = [self.times_refine[self.thresholdPoint_t2], self.times_refine[self.thresholdPoint_t1]]
  self.phase3Range = [self.times_refine[self.thresholdPoint_t1], 999999] # just make sure it is large enough
```

Subroutine of _extract_features_flash

```
@staticmethod
def _FEATURE_single_TS(times, temps, startIndex, endIndex):
  # compute delta time
  deltaT = times[endIndex] - times[startIndex]
  # f1
  deltaTemp = temps[endIndex] - temps[startIndex]
  # f2
  avgDeltaTempRate = float(deltaTemp) / float(deltaT)
  # compute instant change
  instantValueChanges = []
  for i in range(startIndex+1, endIndex+1):
    dt_instant = times[i] - times[i-1]
    dv_{instant} = temps[i] - temps[i-1]
    speed instant = float(dv instant) / float(dt instant)
    instantValueChanges.append(speed instant)
  # f3 min instant speed
  min instantValue = min(instantValueChanges)
  # f4 max instant speed
  max_instantValue = max(instantValueChanges)
  # f5 avg instant speed
  avg_instantValue = np.array(instantValueChanges).mean()
  # f6 largest index position
  maxIndax = instantValueChanges.index(max(instantValueChanges))
  position ratio = float(maxIndax) / float(len(instantValueChanges))
  # f7 trend
  # build points
  X = np.arange(len(instantValueChanges))
  Y = np.array(instantValueChanges)
  A = np.vstack([X, np.ones(len(X))]).T
  m_{all}, _ = np.linalg.lstsq(A, Y)[0]
  X = np.arange(len(instantValueChanges))
  Y = np.array(instantValueChanges)
  A = np.vstack([X, np.ones(len(X))]).T
  m_{all}, = np.linalg.lstsq(A, Y)[0]
  # first part and second part
  middleIndex = int(len(instantValueChanges)/2)+1
  # first part
  X = np.arange(len(instantValueChanges[0:middleIndex]))
  Y = np.array(instantValueChanges[0:middleIndex])
```

```
A = np.vstack([X, np.ones(len(X))]).T
  m_{front}, _ = np.linalg.lstsq(A, Y)[0]
  # back part
  X = np.arange(len(instantValueChanges[middleIndex:]))
  if len(X.tolist()) == 0:
    m back = m front
  else:
    Y = np.array(instantValueChanges[middleIndex:])
    A = np.vstack([X, np.ones(len(X))]).T
    m_{back}, _ = np.linalg.lstsq(A, Y)[0]
  # fv
  fv = [deltaT, deltaTemp, avgDeltaTempRate, min instantValue, max instantValue, avg instantValue, position ratio, m all, m front, m back]
  return fv
# Obtain features for Room 1 in Phase 1
def _extract_features_flash(self):
  if self.thresholdPoint_p != None:
    self.fv_full = []
    fv_p_temp = Instance._FEATURE_single_TS(times=self.times_refine, temps=self.ps_refine, startIndex=0, endIndex=self.thresholdPoint_p-1)
    fv p diff = Instance. FEATURE single TS(times=self.times diff, temps=self.diff ps, startIndex=0, endIndex=self.thresholdPoint p-1)
    self.fv_full.extend(fv_p_temp)
    self.fv_full.extend(fv_p_diff)
  else:
    self.fv full = None
# Obtain features for 1) Corridor in Phase 1 to 2 and 2) Room 2 in Phase 1 to 3
def_extractRegressionFeaturesAndLabels(self, n_space, windowLength = 6):
  self.isRegression_valid = False
  self.r1 window end ts = []
  self.instances r1 fvs = []
  self.regression_r1_lb0s = []
  self.regression r1 lbns = []
  self.r2 window end ts = []
  self.instances_r2_fvs = []
  self.regression_r2_lb0s = []
  self.regression_r2_lbns = []
  # check
```

```
self.isRegression valid = True
```

```
if self.thresholdPoint_p == None:
       self.isRegression valid = False
       self.fv fix slow = None
       self.fv_fix_fast = None
    else:
       if self.thresholdPoint t1 == None:
         self.thresholdPoint_t1 = len(self.times_refine)-1
       if self.thresholdPoint t2 == None:
         self.thresholdPoint_t2 = len(self.times_refine)-1
       # Get basic
       idxRange fixing = [0, self.thresholdPoint p-1]
       idxRange changing r1 = [self.thresholdPoint p, self.thresholdPoint t1-1]
       idxRange_changing_r2 = [self.thresholdPoint_p, self.thresholdPoint_t2-1]
       # Phase 1
       fv fix r1, self.mean r1 value, self.mean r1 change = Instance. FEATURE regression(self.times refine, self.ps refine, self.t1s, idxRange fixing[0],
idxRange fixing[1])
       fv fix r2, self.mean r2 value, self.mean r2 change = Instance. FEATURE regression(self.times refine, self.ps refine, self.t2s, idxRange fixing[0],
idxRange_fixing[1])
       self.fv_fix_slow = fv_fix_r1
       self.fv fix fast = fv fix r2
       # Phase 2 and 3
       # r1 first ---
       # Apply moving window
       r1 mv idxRanges = Instance. movingWindow(
         frontIndex=0,
         endIndex=idxRange changing r1[1],
         lengthWindow=windowLength,
         stepIndex=1
       )
       for i in range(0, len(r1 mv idxRanges)):
         currentRange = r1_mv_idxRanges[i]
         changing fv = Instance. FEATURE regression(self.times refine, self.ps refine, self.t1s refine, currentRange[0], currentRange[1], isFix=False,
deltaT=self.times refine[currentRange[-1]]-self.times refine[self.thresholdPoint p],mean t value=self.mean r1 value, mean t change=self.mean r1 change)
         fv full = []
         fv full.extend(changing fv)
         fv_full.extend(fv_fix_r1)
         # Get label
         currentLabel0 = self.ps ori[currentRange[-1]]
         currentLabeln = self.ps ori[min(len(self.ps ori)-1, currentRange[-1]+n space)]
```

```
# Append
         self.r1 window end ts.append(self.times refine[currentRange[-1]])
         self.instances_r1_fvs.append(fv_full)
         self.regression_r1_lb0s.append(currentLabel0)
         self.regression r1 lbns.append(currentLabeln)
       # Then r2 ----
       # Apply moving window
      r2 mv idxRanges = Instance. movingWindow(
         frontIndex=0.
         endIndex=idxRange_changing_r2[1],
         lengthWindow=windowLength,
         stepIndex=1
       )
      for i in range(0, len(r2_mv_idxRanges)):
         currentRange = r2 \text{ mv idxRanges[i]}
         changing_fv = Instance._FEATURE_regression(self.times_refine, self.ps_refine, self.t2s_refine, currentRange[0], currentRange[1], isFix=False,
deltaT=self.times refine[currentRange[-1]]-self.times refine[self.thresholdPoint p], mean t value=self.mean r1 value, mean t change=self.mean r1 change)
         fv full = []
         fv_full.extend(changing_fv)
         fv full.extend(fv fix r2)
         # Get label
         currentLabel0 = self.ps_ori[currentRange[-1]]
         currentLabeln = self.ps ori[min(len(self.ps ori) - 1, currentRange[-1] + n space)]
         # Append
         self.r2_window_end_ts.append(self.times_refine[currentRange[-1]])
         self.instances_r2_fvs.append(fv_full)
         self.regression_r2_lb0s.append(currentLabel0)
         self.regression_r2_lbns.append(currentLabeln)
  # Subroutine of extractRegressionFeaturesAndLabels
  @staticmethod
  def _FEATURE_regression(times, ps, ts, startIndex, endIndex, isFix = True, deltaT = None, mean_t_value = None, mean_t_change=None):
    # ps is the fire room
    # ts is other room
    mean_ps_v = np.array(ps[startIndex:endIndex+1]).mean()
     mean_ts_v = np.array(ts[startIndex:endIndex+1]).mean()
    instantValueChanges_ps = []
    for i in range(startIndex + 1, endIndex + 1):
      dt instant = times[i] - times[i - 1]
```

```
dv_{instant} = ps[i] - ps[i - 1]
    speed instant = float(dv instant) / float(dt instant)
    instantValueChanges_ps.append(speed_instant)
  instantValueChanges_ts = []
  for i in range(startIndex + 1, endIndex + 1):
    dt instant = times[i] - times[i - 1]
    dv_{instant} = ts[i] - ts[i - 1]
    speed_instant = float(dv_instant) / float(dt_instant)
    instantValueChanges_ts.append(speed_instant)
  meanPs = np.array(instantValueChanges_ps).mean()
  maxPs = np.array(instantValueChanges_ps).max()
  minPs = np.array(instantValueChanges_ps).min()
  meanTs = np.array(instantValueChanges_ts).mean()
  maxTs = np.array(instantValueChanges_ts).max()
  minTs = np.array(instantValueChanges ts).min()
  # Compute ratio
  maxIndax = instantValueChanges_ps.index(max(instantValueChanges_ps))
  position_ratio_p = float(maxIndax) / float(len(instantValueChanges_ps))
  maxIndax = instantValueChanges_ts.index(max(instantValueChanges_ts))
  position ratio t = float(maxIndax) / float(len(instantValueChanges ts))
  if isFix == False:
    fv = [mean_ts_v,meanTs, maxTs, minTs, position_ratio_t, deltaT]
    return fv
  else:
    fv = [mean_ps_v, mean_ts_v, meanPs, maxPs, minPs, meanTs, maxTs, minTs, position_ratio_t]
    mean ts value = mean ts v
    mean_ts_change = meanTs
    return fv, mean_ts_value, mean_ts_change
# Subroutine of extractRegressionFeaturesAndLabels
@staticmethod
def movingWindow(frontIndex, endIndex, lengthWindow, stepIndex):
  eachWindowIndexRanges = []
  # paras
  totalLength = endIndex-frontIndex+1
  i = frontIndex
  while i < endIndex-lengthWindow:
    # iterate window
    currentWindowStartIdx = i
```

```
currentWindowEndIdx = i + lengthWindow
    eachWindowIndexRanges.append([currentWindowStartIdx, currentWindowEndIdx])
    # refresh
    i = i + stepIndex
  return eachWindowIndexRanges
# Subroutine of _extractRegressionFeaturesAndLabels
@staticmethod
def _isInIndexRange(idx, rng):
  # if idx \geq rng[0] and idx \leq rng[1]:
  # return True
  if idx<=rng[1]:
    return True
  else:
    return False
# Combine instances
def _buildTestingInstance(self, n_space, lengthWindow):
  if self.id == '3':
    print('d')
  if self.isRegression_valid == False:
    self.test_t_current = []
    self.test Labels current = []
    self.test t future = []
    self.test_Labels_future=[]
    self.test_types_future = [] # 'multi' or 'single'
    self.test_types_current = []
    self.test_fvs_slow_future = [] # 1
    self.test fvs fast future = [] # 2
    self.test_fvs_slow_current = [] # 1
    self.test_fvs_fast_current = [] # 2
    # logInfo ---
    self.test logInfo historyTemp slow = []
    self.test_logInfo_windowTemp_slow = []
    self.test_logInfo_deltaTs = []
  else:
    idxRange_changing_slow = [self.thresholdPoint_p, self.thresholdPoint_t1 - 1]
    idxRange_changing_fast = [self.thresholdPoint_p, self.thresholdPoint_t2 - 1]
    # Build test fvs and types (one room or two room) and labels
```

```
self.test t current = []
       self.test Labels current = []
       self.test t future = []
       self.test_Labels_future = []
       self.test types future = []
       self.test types current = []
       self.test_fvs_slow_future = [] # 1
       self.test fvs fast future = [] # 2
       self.test_fvs_slow_current = [] # 1
      self.test_fvs_fast_current = [] # 2
      # logInfo ---
       self.test logInfo historyTemp slow = []
       self.test_logInfo_windowTemp_slow = []
       self.test logInfo deltaTs = []
      # Build -- future
       for i in range(self.thresholdPoint_p, self.thresholdPoint_t1):
         # Determine window
         currentPredictIndex = i
         currentWindowEndIndex = max(0, currentPredictIndex-n_space)
         currentWindowStartIndex = max(0, currentWindowEndIndex - lengthWindow +1)
         if currentWindowEndIndex - currentWindowStartIndex+1 \le (1/2)^* lengthWindow:
            continue
         self.test Labels future.append(self.ps ori[currentPredictIndex])
         self.test t future.append(self.times refine[currentPredictIndex])
         # Determine type
         flag slow = Instance. isInIndexRange(currentWindowEndIndex, idxRange changing slow)
         flag_fast = Instance._isInIndexRange(currentWindowEndIndex, idxRange_changing_fast)
         if flag_slow == True and flag_fast == True:
            self.test types future.append('multi')
         else:
            # It should not go here
           self.test types future.append('single')
         # ----- test fv -----
         if flag slow == True:
            # Build fv
            changing_fv = Instance._FEATURE_regression(self.times_refine, self.ps_refine, self.t1s_refine,
                                     currentWindowStartIndex, currentWindowEndIndex, isFix=False,
                                      deltaT=self.times refine[currentWindowEndIndex] -self.times refine[self.thresholdPoint p],
mean t value=self.mean r1 value, mean t change=self.mean r1 change)
```

```
fv full = []
            fv full.extend(changing fv)
            fv full.extend(self.fv fix slow)
            # Append -- test fv
            self.test fvs slow future.append(fv full)
            # Append -- history temp for slow room
            self.test_logInfo_historyTemp_slow.append(
              self.t1s refine[0:currentWindowEndIndex+1]
            )
            self.test_logInfo_windowTemp_slow.append(
              self.t1s refine[currentWindowStartIndex:currentWindowEndIndex+1]
            )
            self.test_logInfo_deltaTs.append(
              self.times_refine[currentWindowEndIndex+1] - self.times_refine[self.thresholdPoint_p]
            )
         else:
            self.test fvs slow future.append(None)
            self.test_logInfo_historyTemp_slow.append(None)
            self.test_logInfo_deltaTs.append(None)
         if flag fast == True:
            # Build fv
            changing_fv = Instance._FEATURE_regression(self.times_refine, self.ps_refine, self.t2s_refine,
                                      currentWindowStartIndex, currentWindowEndIndex, isFix=False,
                                      deltaT=self.times refine[currentWindowEndIndex] - self.times refine[self.thresholdPoint p],
mean_t_value=self.mean_r2_value, mean_t_change=self.mean_r2_change)
            fv full = []
            fv_full.extend(changing_fv)
            fv_full.extend(self.fv_fix_fast)
            # Append
            self.test fvs fast future.append(fv full)
         else:
            self.test fvs fast future.append(None)
       for i in range(self.thresholdPoint_t1, len(self.times_refine)):
         self.test t future.append(self.times refine[i])
         self.test_Labels_future.append(self.ps_ori[i])
         self.test_types_future.append('trend')
       # Build -- current
       for i in range(self.thresholdPoint p, self.thresholdPoint t1):
```

```
# Determine window
         currentPredictIndex = i
         currentWindowEndIndex = max(currentPredictIndex, 0)
         currentWindowStartIndex = max(0, currentWindowEndIndex - lengthWindow + 1)
         if currentWindowEndIndex - currentWindowStartIndex + 1 \le (1/2) * lengthWindow:
           continue
         self.test_Labels_current.append(self.ps_ori[currentPredictIndex])
         self.test_t_current.append(self.times_refine[currentPredictIndex])
         # Determine type
         flag_slow = Instance._isInIndexRange(currentWindowEndIndex, idxRange_changing_slow)
         flag fast = Instance. isInIndexRange(currentWindowEndIndex, idxRange changing fast)
         if flag slow == True and flag fast == True:
           self.test_types_current.append('multi')
         else:
           # It should not go here
           self.test_types_current.append('single')
         # ----- test fv -----
         if flag slow == True:
           # Build fv
           changing fv = Instance. FEATURE regression(self.times refine, self.ps refine, self.t1s refine,
                                     currentWindowStartIndex, currentWindowEndIndex, isFix=False,
                                     deltaT=self.times_refine[currentWindowEndIndex] -self.times_refine[self.thresholdPoint_p],
mean t value=self.mean r1 value, mean t change=self.mean r1 change)
           f = Utility.list contain nan(changing fv)
           if f == True:
              print('a')
           fv_full = []
           fv full.extend(changing fv)
           fv full.extend(self.fv fix slow)
           # Append
           self.test fvs slow current.append(fv full)
         else:
           self.test_fvs_slow_current.append(None)
         if flag_fast == True:
           # Build fv
           changing_fv = Instance._FEATURE_regression(self.times_refine, self.ps_refine, self.t2s_refine,
                                     currentWindowStartIndex, currentWindowEndIndex, isFix=False,
                                     deltaT=self.times refine[currentWindowEndIndex] - self.times refine[self.thresholdPoint p],
```

print('d') # End of step 2

Appendix B4: Training and Testing

```
# Step 3 to do training and testing
class FireTemperatureRegression(object):
  # Initialize parameters
  def init (self):
    self.regressionModule room1 = None
    self.regressionModule_room2 = None
    # Time range
    self.Phase1TimeRange = None
    self.Phase2TimeRange = None
    self.Phase3TimeRange = None
  # Training and Testing the model
  def fit(self, Xs r1, y r1, Xs r2, y r2, isGrid = True):
    # r1
    gsc = GridSearchCV(
       estimator=SVR(kernel='rbf'),
       param_grid={
         'C': [0.1, 1, 100, 1000],
         'epsilon': [0.0001, 0.0005, 0.001, 0.005, 0.01, 0.05, 0.1, 0.5, 1, 5, 10],
         'gamma': [0.0001, 0.001, 0.005, 0.1, 1, 3, 5]
       },
       cv=5, scoring='neg mean squared error', verbose=0, n jobs=-1)
    grid_result = gsc.fit(Xs_r1, y_r1)
    best_params = grid_result.best_params_
    print('Room 1---C: ' + str(best_params["C"]))
    print('Room 1---epsilon: ' + str(best_params["epsilon"]))
    print('Room 1---gamma: ' + str(best_params["gamma"]))
    self.regressionModule room1 = SVR(kernel='rbf', C=best params["C"], epsilon=best params["epsilon"], gamma=best params["gamma"],
          coef0=0.1, shrinking=True,
           tol=0.001, cache_size=200, verbose=False, max_iter=-1)
    self.regressionModule room1.fit(Xs r1, y r1)
    # r2
    gsc = GridSearchCV(
       estimator=SVR(kernel='rbf'),
       param_grid={
         'C': [0.1, 1, 100, 1000],
         'epsilon': [0.0001, 0.0005, 0.001, 0.005, 0.01, 0.05, 0.1, 0.5, 1, 5, 10],
```

```
'gamma': [0.0001, 0.001, 0.005, 0.1, 1, 3, 5]
    },
    cv=5, scoring='neg_mean_squared_error', verbose=0, n_jobs=-1)
  grid\_result = gsc.fit(Xs_r2, y_r2)
  best params = grid result.best params
  print('Room 2---C: ' + str(best params["C"]))
  print('Room 2---epsilon: ' + str(best_params["epsilon"]))
  print('Room 2---gamma: ' + str(best params["gamma"]))
  self.regressionModule_room2 = SVR(kernel='rbf', C=best_params["C"], epsilon=best_params["epsilon"],
                      gamma=best_params["gamma"],
                      coef0=0.1, shrinking=True,
                      tol=0.001, cache size=200, verbose=False, max iter=-1)
  self.regressionModule_room2.fit(Xs_r2, y_r2)
# Padding and smoothing
@staticmethod
def MA(y, N=4):
  y_padded = np.pad(y, (N // 2, N - 1 - N // 2), mode='edge')
 y_smooth = np.convolve(y_padded, np.ones((N,)) / N, mode='valid')
  return y smooth
# Subroutine of predict_instancesV2
# To get fitting type (binding or polynomial)
@staticmethod
def predict_instance_trend(memory_ts, memory_temps, predict_ts):
  FTP trend = FireTemperaturePredictionForSameRoom()
  FTP_trend.fit(memory_ts, FireTemperatureRegression.MA(memory_temps))
  predict_temps = FTP_trend.predict(predict_ts)
  return predict temps, FTP trend.type
# Fitting
def predict instancesV2(self, fvs fast, fvs slow, reals, types, ts, scale fast, scale slow):
  p2 =[]
```

```
p_2 = []

r_2 = []

p_3 = []

r_3 = []
```

p23 = []

r23 = [] p4 = [] r4 = []

```
predict_values = []
i_trend = types.index('trend')
for i in range(0, i trend):
  currentType = types[i]
  fv_fast = fvs_fast[i]
  fv_slow = fvs_slow[i]
  if fv_fast != None:
     fv_fast = scale_fast.transform([fv_fast])[0]
  if fv slow != None:
     fv_slow = scale_slow.transform([fv_slow])[0]
  if currentType == 'multi':
     pred = self.predict instanceV2(
       fv_fast = fv_fast,
       fv_slow = fv_slow,
       type = 1
     )
     p2.append(pred)
     r2.append(reals[i])
     p23.append(pred)
     r23.append(reals[i])
  elif currentType == 'single':
     pred = self.predict_instanceV2(
       fv_fast=fv_fast,
       fv_slow=fv_slow,
       type=2
     )
     p3.append(pred)
     r3.append(reals[i])
     p23.append(pred)
     r23.append(reals[i])
  predict_values.append(pred)
predict_ts = ts[i_trend:]
predict_temps, fit_type = FireTemperatureRegression.predict_instance_trend(ts[:i_trend], predict_values, predict_ts)
predict_values.extend(predict_temps)
p4 = predict\_temps
r4 = reals[i trend:]
return predict_values, reals, p2, r2, p3, r3, p23, r23, p4, r4, fit_type
```

```
# To produce final results for Phase 2 and 3
def predict_instanceV2(self, fv_fast, fv_slow, type):
    if type == 1:
        temperature_r1 = self.regressionModule_room1.predict([fv_fast])[0]
        temperature_r2 = self.regressionModule_room2.predict([fv_slow])[0]
        return (temperature_r1 + temperature_r2) / 2.0
    elif type == 2:
        temperature_r2 = self.regressionModule_room2.predict([fv_slow])[0]
        return temperature_r2
# Calculate MAE
@staticmethod
def getMAE(preds, reals):
        mae = mean_absolute_error(preds, reals)
        return mae, len(preds)
```

End of step 3

Appendix B5: Fitting

```
# Step 4 to do fitting
class FireTemperaturePredictionForSameRoom(object):
  # Initialize the inner parameter
  def init (self):
    self.timeToFit = None
    self.temperatureToFit = None
  # Carrying fitting
  def fit(self, times, temperatures):
    self.timeToFit = times
    self.temperatureToFit = temperatures
    self.type = FireTemperaturePredictionForSameRoom._determine_fit_type(self.temperatureToFit)
    \# Type = 0, binding curve
    if self.type == 0:
       sigma = np.ones(len(self.timeToFit))
      sigma[[-2,-1]] = 0.001
       self.param = curve_fit(FireTemperaturePredictionForSameRoom._binding, self.timeToFit, self.temperatureToFit,
                     bounds=((0,0,0), (500,10000,500)), sigma=sigma, maxfev=np.inf)
    \# Type = 1, 3rd order polynomial
    elif self.type == 1:
       diff = np.diff(np.array(self.temperatureToFit)).tolist()
       idx = diff.index(max(diff))
       sigma = np.ones(len(self.timeToFit))
       sigma[[0, idx-1]] = 0.001
       self.param = curve_fit(FireTemperaturePredictionForSameRoom._poly3, self.timeToFit, self.temperatureToFit,
                     bounds=((0,-1,-1,-1000), (1,1,1,8000)),sigma=sigma, maxfev=np.inf)
     # 5th order polynomial
     else:
       diff = np.diff(np.array(self.temperatureToFit)).tolist()
       idx = diff.index(max(diff))
       sigma = np.ones(len(self.timeToFit))
       sigma[[0, idx-1]] = 0.001
       self.param = curve_fit(
         FireTemperaturePredictionForSameRoom._poly5, self.timeToFit, self.temperatureToFit,
         bounds=((0,-1,-1,-1,-1), (1,1,1,1,1)),maxfev=np.inf)
```

```
# Gather values
def predict(self, ts_predict):
  if self.type == 0:
     values a = FireTemperaturePredictionForSameRoom. binding(np.array(ts predict), *self.param[0])
  elif self.type == 1:
    values_a = FireTemperaturePredictionForSameRoom._poly3(np.array(ts_predict), *self.param[0])
  else:
     values_a = FireTemperaturePredictionForSameRoom._poly5(np.array(ts_predict), *self.param[0])
  values = values_a.tolist()
  return values
# Fitting options
@staticmethod
def _poly5(x,a,b,c,d,e,f):
  return a^{*}x^{**}5 + b^{*}x^{**}4 + c^{*}x^{**}3 + d^{*}x^{**}2 + e^{*}x + f
@staticmethod
def _binding(x, kd, bmax, e):
  return ((bmax * x^{**}.5) / (x^{**}.5 + kd))+e
@staticmethod
def \log(x, a, b):
  return a^{*}(np.log(x) / np.log(5)) + b
@staticmethod
def _poly3(x,a,b,c,d):
  return a*x**3+b*x**2+c*x+d
# To determine fitting type
@staticmethod
def determine fit type(values):
  # Type 0 \Rightarrow binding \parallel 1 \Rightarrow poly
  diffs = np.diff(np.array(values)).tolist()
  diffs = FireTemperatureRegression.MA(diffs).tolist()
  diffs = FireTemperatureRegression.MA(diffs).tolist()
  maxV = max(diffs)
  maxIdx = diffs.index(maxV)
  maxIdxRatio = float(maxIdx) / float(len(diffs))
  if maxIdxRatio < 0.65:
    return 0
  else:
```

return 1 # End of step 4 [Intentionally Left Blank]

Appendix C: P-Flash Limitations

In this section, P-Flash is tested against a new test set and it is believed that the following evaluation helps to reveal the current limitation of P-Flash and to provide guidelines about data requirement for the development of a more robust flashover prediction model in multi-compartment buildings.

The new test set accounts for three additional effects: 1) a different surface material, 2) arbitrary opening conditions of vents, and 3) a different fire growth behavior. For the new surface material concrete [12] is considered and the thermal conductivity, specific heat, density, thickness and surface emissivity is given as 1.75 W/m², 1 kJ/(kg·°C), 2200 kg/m³, 0.15 m, and 0.94, respectively. For vent conditions, all vents such as doors and windows are initially closed, but they can be opened at any time during a numerical experiment. Due to the arbitrary opening of the closed vents, a more complex fire growth behavior can also be introduced. For example, in Room 1 with two initially closed vents, a t-squared fire will begin to decay due to depletion of oxygen. When there is an opened door or window in Room 1, fresh air is entrained to the room. Given the added oxygen, a fire may continue to grow. Figure B1 shows the corresponding heat detector temperature profiles. This kind of event provide fires with double-peak growing behavior which is different from the t-squared fire. This example case is denoted as Case 3 and is discussed below. Similar to that described in Section 2, the remaining numerical setups are identical. In general, the simulation time for each numerical experiment is 8400 s, and the temperature output interval is 20 s. In total, there are 4000 different cases.

In order to provide insights on the influence of each of the additional effects, model performance against two limiting scenarios are first provided in Table B1. Scenario 1 consists of cases where only the effect of new surface material is accounted for where all vents are still open. For Scenario 2, besides having new surface material, cases with arbitrarily opening a Room 1 exterior window and the Room 2 exterior door are also considered. As shown in the table, the model performance for Scenario 1 remains similar to that of seen in Table 4. A physical interpretation for having relatively similar results is that since P-flash learns patterns associated with the higher level temperature information, such as the statistically-based rate of change in temperature for the heat detectors, and with the fact that the change of wall material does not lead to a significant change in temperature behavior, the model is capable of providing reliable predictions. However, model performance drops substantially for Scenario 2, especially in Phase IV where temperature signals from the heat detectors are no longer available, the MAE increases to more than 150 °C. Figure B2 presents temperature comparison between ground-truth (black dash line) and P-Flash predictions (red line for Phase II and III and blue line for Phase IV). As shown in the figure, the temperature predictions in Phase II and III capture the relative trend as compared to the ground-truth and same behavior is observed even for the 2nd temperature rise appearing at around 2150 s. However, it can be seen that the prediction in Phase IV captures neither the trend nor magnitude of the ground-truth. The large discrepancy in Phase IV is largely due to the assumption imposed on the memory component (M) that the overall temperature behavior assumes either the sigmoidal binding function or the high order polynomial function based on the initial temperature rise. Table B1 shows the overall model performance of P-Flash. An increase to MAE in both Phase II and III is observed and the decrease in model performance is primarily due to the cases where there are arbitrarily

opening doors between Room 1 and Corridor, and Corridor and Room 2 (when doors are closed, the temperature from the corresponding heat detector in a particular compartment remains essentially at room temperature). In order to overcome the data complexity inherent in the new test set, additional data is needed for modeling training and additional treatments are required to facilitate the learning during the training process. This work is currently underway.



Figure B1. Temperature profiles for an example case (Case 3) demonstrating the effect of arbitrarily opening to vents.

Table B1. P-Flash performance again new test set for current prediction.

	Phase II	Phase III	Phase IV
	MAE (C)	MAE (C)	MAE (C)
Scenario 1	10	14	33
Scenario 2	23	30	> 150
Overall	47	58	> 150



Figure B2. Comparison between ground truth and predictions (current) obtained from P- Flash for Case 3.