# A Fundamental Assessment of the Concept of Mean Beam Length for Application for Multi-dimensional Non-Gray Radiative Heat Transfer 

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#### Abstract

The traditional concept of mean beam length (MBL) and its recommended empirical expression are demonstrated to be inaccurate for general application for the evaluation of multi-dimensional non-gray radiative heat transfer. A new concept, namely Point Mean Beam Length (PMBL), is proposed and the formulation of PMBL is provided. The mathematical properties of PMBL for three common geometries including sphere, cylinder, and slab are presented. Results show that PMBL is more effective in generating an accurate evaluation of radiative heat transfer from a differential area to any finite area at the boundary of an enclosure with an isothermal absorbing/emitting medium. The deficiency of the traditional mean beam length empirical expression is illustrated. A concept of "optimal" point mean beam length (OPMBL) is demonstrated to be a more accurate length scale for practical applications. In contrast to the traditional MBL, a single value of OPMBL is applicable for all gas absorption bands, independent of the strength and shape of the absorption bands. The proposed work provide a mathematically validated approach to efficiently and accurately evaluate the radiation heat transfer within an isothermal, non-gray, multi-dimensional medium.


Keywords: radiation heat transfer, point mean beam length, optimal mean beam length, multi-dimensional, nongray medium.

## 1. Introduction

Radiative heat transfer is an important and often the dominant mode of heat transfer in many high-temperature industrial applications such as furnaces, boilers, gas turbines, and high-temperature fibrous thermal protection systems. Accurate engineering analysis of these systems requires solutions to the radiative transfer equation (RTE) in systems with multi-dimensional geometry, non-gray radiative properties, and inhomogeneous spatial distribution in temperature and species concentration. Over the years, a significant amount of effort has been made to develop accurate solutions to the RTE. Since the geometric effect of radiative heat transfer and the spectral effect of the absorption properties of the medium are treated independently by the RTE, much of the research is focused on the two effects separately. For example, different solution methods, such as the Zonal Method [13], Discrete Ordinate Method [4,5], Finite Volume Method [6], P-N (Spherical Harmonics) method [7,8], natural element method [9], and Monte Carlo Method [10-12] have been developed to address the multi-dimensional effect. They have been demonstrated to be effective for multi-dimensional radiative heat transfer in a gray medium. Different spectral models, such as the various narrow-band models [13-15], the k-distribution (and correlated k-distribution) method [16-17], and the weighted gray gas models [18-20] have been developed to address the highly complex non-gray spectral absorption behavior of combustion gases. Some of these models have been verified to be accurate by comparison with line-by-line direct integration $[21,22]$ and demonstrated to be effective in evaluating the total absorptivity/emissivity of nongray mediums such as combustion gases in a onedimensional system.

For the evaluation of multi-dimensional radiative heat transfer in a nongray system, however, the progress of the research is limited. Many attempts to develop solutions to multi-dimensional radiative transfer in a nongray isothermal medium by combining the different solution methods with the different spectral models have been reported in the literature [23-27]. While these efforts are valuable in providing benchmark solutions, particularly in assessing the accuracy of approximate solutions, the approaches are still too computationally intensive to be implemented by the practical engineering community. For example, in transient analysis of non-gray radiative heat transfer in a rectangular enclosure with an isothermal combustion gas using the zonal method and a narrow-band model with a $10 \times 10 \times 10$ grid nodalization, to update the radiative heat transfer between the differential volume and area zones numerically (without any approximation) would require over 400 million numerical integrations at every time step, as the temperature and the species concentration of the medium are changing with time [28,29]. Similar computational efforts are required using other solution methods (e.g. Monte Carlo, Discrete Ordinate Method) and spectral models (e.g. k-distribution and line-by-line integration). Simplification and/or approximations are required if the assessment of radiative heat transfer is needed in the design of practical engineering systems.

Over the years, many approximate approaches have been reported to address the mathematical complexity of multi-dimensional radiative heat transfer in nongray systems. Few of them, however, have made sufficient progress to be accepted broadly by the industry. Currently, the most commonly accepted approximate approach for multidimensional nongray radiative heat transfer is to utilize the concept of mean beam length (MBL). Introduced by Hottel [1] and studied by many researchers [30-34] over the years, the MBL is used as a length scale so that the one-dimensional results can be used to approximate the total absorptivity/emissivity for radiative exchange between a three-
dimensional volume and its total boundary. The MBL concept was only being verified to be used in predicting the total emissivity of combustion gases in enclosures with simple geometry (e.g. sphere, cube) [30-34]. An empirical expression for the MBL ( $4 * \mathrm{C} * \mathrm{~V} / \mathrm{A}$, with C being the correction factor , and V and A being the volume and boundary area of the enclosure) was introduced for enclosures with arbitrary three-dimensional geometries. In recent years, the concept of MBL is also used to generate approximate solutions for multidimensional nongray radiative heat transfer in a non-isothermal inhomogeneous medium. Specifically, a local absorption coefficient for a computational cell is generated by the onedimensional total emissivity using $\operatorname{MBL}\left(4 * \mathrm{C} * \mathrm{~V}_{\mathrm{c}} / \mathrm{A}_{\mathrm{c}}\right.$ with $\mathrm{V}_{\mathrm{c}}$ and $\mathrm{A}_{\mathrm{c}}$ being the volume and boundary of the computational cell) and the local radiative properties of the medium, thus accounting for the nonisothermal and inhomogeneous effect. The local absorption coefficient is then used in the full computation with a particular radiation solver. Results using this approach have appeared in the literature $[35,36]$ and this approach has also adopted by some CFD codes (e.g. FLUENT, CFAST, FDS) [37-39] as an option for the user to simulate the radiative heat transfer effect.

However, due to the lack of numerically efficient and accurate calculation methods, the MBL approach has been used as an approximation. In the fire research community, the MBL is often being used to evaluate the localized effect of radiation heat transfer [40,41]. Yet, the use of MBL has not been validated for the evaluation of local radiative heat transfer, even for an isothermal medium in enclosures with simple geometry (e.g. cylinder, cube). For a design calculation using a CFD code, while the use of the MBL concept in the evaluation of the local absorption coefficient in a computational cell is physically reasonable, the accuracy of this approach has also not been rigorously verified. Therefore, results generated by such computations thus have uncertain accuracy and improvements are needed in the computation of radiative heat transfer in non-gray multi-dimensional systems.

Given the fact that the MBL concept is a key component in implementing the nongray multi-dimensional applications, the objective of this work, together with results presented in reference [42], is to systematically assess the accuracy of the traditional MBL approach and to develop modifications of the concept which can extend the accuracy of its implementation in enclosures with different geometries. Specifically, a concept of point mean beam length (PMBL), is introduced. In contrast to the traditional MBL, PMBL is defined as the length scale for the radiative heat transfer between a differential area and a finite area with an intervening absorbing/emitting medium. In general, the traditional MBL can be generated from PMBL by an integration over the emitting area. While PMBL is still a function of wavelength, the effect on the differential exchange factor due to the spectral variation of PMBL is not strong and an "optimal" PMBL (OPMBL) can be identified as a constant length scale for the evaluation of the radiative heat transfer over the whole range of optical thickness. As illustrations, PMBL is implemented with the zonal method to generate accurate and computationally efficient solutions to radiative heat transfer in some two-dimensional and three-dimensional enclosures. These solutions will be valuable for benchmark purposes.

In reference [42], results are presented for radiative exchange between rectangular surfaces in various parallel and perpendicular configurations, which are important for the analysis of non-gray radiative heat transfer in a rectangular enclosure. In the present work, the accuracy and mathematical properties of the PMBL concept for three general 3D and

2D geometries (sphere, cylinder, and slab) are further investigated. The limitation of the traditional MBL in these 3D and 2D enclosures is illustrated by comparison with the OPMBL results.

## 2. The concept of point mean beam length (PMBL)

For a diffusely emitting area $d A_{1}$ and a second finite area $A_{2}$, the differential exchange factor for radiative transfer is given by

$$
\begin{equation*}
d s_{1} s_{2}=d A_{1} \int_{A_{2}} \frac{\cos \theta_{1} \cos \theta_{2}}{\pi L^{2}} e^{-a L} d A_{2} \tag{1}
\end{equation*}
$$

where $\theta_{i}(i=1,2)$ is the angle between the unit surface normal at the two differential surface $d A_{i}(i=1,2)$ and the line of sight between the two differential surfaces. $L$ is the length of the line of sight and $a$ is the absorption coefficient of the intervening medium. A point mean beam length, $L_{p m b}$, is defined to be the equivalent length scale such that the geometrical mean transmittance between the differential area $d A_{1}$ and the finite area $A_{2}$, $\tau_{d 1-2}$, can be written in a one-dimensional form as

$$
\begin{equation*}
\tau_{d 1-2}=\frac{d s_{1} s_{2}}{d A_{1} F_{d 1-2}}=e^{-a L_{p m b}} \tag{2}
\end{equation*}
$$

where the differential view factor, $F_{d 1-2}$ is defined by

$$
\begin{equation*}
F_{d 1-2}=\int_{A_{2}} \frac{\cos \theta_{1} \cos \theta_{2}}{\pi L^{2}} d A_{2} \tag{3}
\end{equation*}
$$

Eq. (1) can be integrated over the emitting area $A_{l}$ to yield the exchange factor between the two finite areas

$$
\begin{equation*}
s_{1} s_{2}=\int_{A_{1}} \int_{A_{2}} \frac{\cos \theta_{1} \cos \theta_{2}}{\pi L^{2}} e^{-a L} d A_{2} d A_{1} \tag{4}
\end{equation*}
$$

The traditional mean beam length, MBL, for the two finite areas $A_{1}$ and $A_{2}$ is defined as

$$
\begin{equation*}
\tau_{1-2}=\frac{s_{1} s_{2}}{A_{1} F_{1-2}}=e^{-a L_{m b}} \tag{5}
\end{equation*}
$$

with $F_{1-2}$ being the view factor given by

$$
F_{1-2}=\int_{A_{1}} \int_{A_{2}} \frac{\cos \theta_{1} \cos \theta_{2}}{\pi L^{2}} d A_{2} d A_{1}
$$

A comparison between Eqs. (2) and (5) yields the following relation between PMBL and MBL,

$$
\begin{equation*}
e^{-a L_{m b}}=\frac{1}{A_{1} F_{1-2}} \int_{A_{1}} F_{d 1-2} e^{-a L_{p m b}} d A_{1} \tag{6}
\end{equation*}
$$

It should be noted that for a general enclosure, PMBL is defined for a local differential area and is generally not the same as the traditional MBL. For enclosures with geometrical symmetry such as a sphere, infinite cylinder, and slab, PMBL and MBL are identical when the emitting surface $A_{1}$ and the absorbing surface $A_{2}$ are the total bounding surface of the enclosure since PMBL is identical at every point of the emitting surface $A_{l}$ due to symmetry. To further understand its mathematical behavior, the PMBL for three simple geometrical configurations (sphere, cylinder, and slab) are presented in the following sections.

### 2.1 Sphere

Using the coordinate system as shown in Fig. 1, Eq. (1) becomes (see Appendix for detail)

$$
\begin{equation*}
d s_{1} d s_{2}=\frac{R^{2}(1+\cos \theta)^{2}}{\pi L^{4}} e^{-a L} d A_{1} d A_{2} \tag{7}
\end{equation*}
$$

Consider $A_{2}$ as the upper portion of the spherical surface (i.e. a spherical cap with $0<$ $\theta<\theta_{c}$ ), Eq. (7) can be integrated to yield (see Appendix for the detail)

$$
\begin{gather*}
\frac{d s_{1} s_{2}}{d A_{1}}=-\frac{1}{2 a R}\left[2 e^{-2 a R}-\sqrt{2\left(\cos \theta_{c}+1\right)} e^{-\sqrt{2\left(\cos \theta_{c}+1\right)} a R}\right]+ \\
\frac{1}{2(a R)^{2}}\left(e^{-\sqrt{2\left(\cos \theta_{c}+1\right)} a R}-e^{-2 a R}\right) \tag{8}
\end{gather*}
$$

The view factor is given by

$$
\begin{equation*}
F_{d 1-2}=\frac{1}{2}\left[1-\cos \theta_{c}\right] \tag{9}
\end{equation*}
$$

and based on Eq. (2), the PMBL is

$$
\begin{gather*}
\frac{L_{p m b}}{R}=-\frac{1}{a R\left[1-\cos \theta_{c}\right]} \ln \left[2 e^{-2 a R}-\sqrt{2\left(\cos \theta_{c}+1\right)} e^{-\sqrt{2\left(\cos \theta_{c}+1\right)} a R}+\right. \\
\left.\frac{1}{a R}\left(e^{-\sqrt{2\left(\cos \theta_{c}+1\right)} a R}-e^{-2 a R}\right)\right] \tag{10}
\end{gather*}
$$

In the optically thin limit $(a R \rightarrow 0)$, the PMBL becomes

$$
\begin{equation*}
\frac{L_{p m b, 0}}{R}=\frac{\frac{8}{\frac{1}{1}-\frac{1}{3}\left[2\left(\cos \theta_{c}+1\right)\right]^{\frac{3}{2}}}}{1-\cos \theta_{c}} \tag{11}
\end{equation*}
$$

In the limit of $A_{2}$ being the whole spherical surface $\left(\theta_{c}=\pi\right)$, Eqs. (8), (10) and (11) are identical to those presented in a separate publication [42]. The PMBL for an absorbing area $A_{2}$ with different values of $\theta_{c}$ are presented as functions of optical thickness $a R$ in Fig. 2.

Numerically, it can be shown that from the perspective of the evaluation of the exchange factor ( $d s_{1} s_{2}$ at a specific wavelength), the effect of the variation of PMBL with
optical thickness is generally not strong and a constant length scale can be selected to generate an accurate approximation to the exchange factor over all wavelengths. To give this length scale a precise mathematical definition, a concept of "optimal" point mean beam length (OPMBL) is introduced. Specifically, for a length scale $L$, the error between the actual exchange factor and the approximate value generated by $L$ for a specific absorption coefficient can be written as

$$
\begin{equation*}
E(L)=\left|\frac{d s_{1} s_{2}}{d A_{1}}-F_{d 1-2} e^{-a R\left(\frac{L}{R}\right)}\right| \tag{12a}
\end{equation*}
$$

To assess the overall error of the approximation, an average sum of the square of the error is evaluated to be

$$
\begin{equation*}
S(L)=\frac{1}{(a R)_{0.01}} \int_{0}^{(a R)_{0.01}} E(L)^{2} d(a R) \tag{12b}
\end{equation*}
$$

The upper limit of the integration in Eq. $(12 b),(a R)_{0.01}$, is taken to be the optical thickness at which the geometric mean transmittance $\left(\tau_{d 1-2}\right)$ is 0.01 because beyond this optical thickness, both the approximate and exact expression of the transmissivity is close to zero and the value of $E(L)$ is negligibly small and insignificant. The length scale which has the minimum value of $S(L)$ is identified as the OPMBL. The values of OPMBL for the absorbing area with different $\theta_{c}$ are identified as single points at the various PMBL curves in Fig. 2. The overall effect of geometry $\left(\theta_{c}\right)$ on OPMBL is illustrated by Fig. 3. It is interesting to note that the value of the traditional mean beam length ( 1.2 R , correspond to the value of $3.6 \mathrm{~V} / \mathrm{A}$ for a sphere) agrees well with the OPMBL when the absorbing area, $A_{2}$, is the whole spherical surface $\left(\theta_{c}=\pi\right)$.

To illustrate the accuracy of using OPMBL and also the deficiency of the traditional MBL in generating accurate approximations, the exchange factor generated by the OPMBL $\left(s_{1} s_{2}=A_{1} F_{12} \exp \left(-a L_{p m b, o}\right)\right)$ together with the approximate exchange factor generated by the traditional MBL $\left(s_{1} s_{2}=A_{1} F_{12} \exp (-1.2 a R)\right)$ are compared with the exact solution (a direct integration of Eq.(4) at a specific optical thickness) with $A_{2}$ being a hemispherical surface with $\theta_{c}=\pi / 2$. The results are shown in Fig. 4. The agreement between the OPMBL approximation and the exact solution is excellent with negligible error ( $<0.01$ ) as lines representing the two solutions are practically indistinguishable in the figure. The error of the approximation of using the traditional MBL, on the other hand, is quite large with a maximum absolute error greater than 0.06 . The corresponding relative error in the region of optical thickness with the maximum absolute error is quite large. For example, with $a R=1.0$, both the exact and PMBL solution for the exchange factor, $s_{1} s_{2}$, is 0.09 . The value predicted by MBL expression ( $s_{1} s_{2}=A_{1} F_{12} \exp (-1.2 a R)$ ), on the other hand, is 0.15 . The relative error is $67 \%$.

Over the years, many researchers have made efforts to identify different MBL's for different gas absorption bands [30-34]. For a spherical enclosure [30,34], for example, the traditional MBL for a weakly absorbing band was established to be $4 R / 3$, which is equivalent to the optically thin limit of $L_{p m b}$ for the whole spherical surface, as shown in Fig. 2. The traditional MBL for a strongly absorbing band (the square-root limit) was determined to be $6 R / 5$, which is close to the value of OPMBL. Physically, an absorption
band is the summation of individual absorption lines that follow the exponential attenuation behavior of radiative absorption. Since OPMBL is demonstrated to be effective in generating an accurate approximation to the exchange factor over the whole range of the absorption coefficient with exponential attenuation, it is applicable for all absorption bands, independent of the strength (i.e. the optical thickness) and the shape of the absorption bands. The selection of a specific quantitative definition of OPMBL (based on Eqs. (12a) and (12b)) and the approximation used in the development of the different gas absorption band models are the reasons for the slight difference between OPMBL and the different traditional MBL's recommended for the different bands.

### 2.2 Cylinder

For an infinite cylinder, Fig. 1, interpreted as a two-dimensional planar system, can still be used as the geometry and coordinate system for mathematical development. Based on the mathematical development presented in the Appendix, the exchange factor between the two differential area $d A_{1}$ and $d A_{2}$ is given by

$$
\begin{equation*}
\frac{d s_{1} d s_{2}}{d A_{1}}=S_{3}(2 a R \cos \beta) \cos \beta d \beta \tag{14}
\end{equation*}
$$

where $S_{3}(x)$ is the two-dimensional radiation function given by [43]

$$
\begin{equation*}
S_{3}(x)=\frac{2}{\pi} \int_{1}^{\infty} \frac{e^{-x t}}{t^{3}\left(t^{2}-1\right)^{1 / 2}} d t \tag{15}
\end{equation*}
$$

Numerical values for $S_{3}(x)$ are tabulated and available in reference [43]. Note that for the two-dimensional planar system, $d A_{1}$ and $d A_{2}$ are infinitesimal strips of infinite length in the direction perpendicular to the two-dimensional x-z plane.

For an angular section extending from $\theta=0$ to $\theta=\theta_{c}$, equation (14) can be integrated to yield the exchange factor

$$
\begin{equation*}
\frac{d s_{1} s_{2}}{d A_{1}}=\int_{0}^{\frac{\theta_{c}}{2}} S_{3}(2 a R \cos \beta) \cos \beta d \beta \tag{16}
\end{equation*}
$$

The view factor is

$$
\begin{equation*}
F_{d 1-2}=\frac{d s_{1} s_{2}}{d A_{1}}(a R=0)=\frac{1}{2} \sin \frac{\theta_{c}}{2} \tag{17}
\end{equation*}
$$

and the PMBL is given by

$$
\begin{equation*}
\frac{L_{p m b}}{R}=-\frac{1}{a R} \ln \left[\frac{2}{\sin \frac{\theta_{c}}{2}} \int_{0}^{\frac{\theta_{c}}{2}} S_{3}(2 a R \cos \beta) \cos \beta d \beta\right] \tag{18}
\end{equation*}
$$

In the optically thin limit $(a R \rightarrow 0)$, the PMBL is reduced to

$$
\begin{equation*}
\frac{L_{p m b, 0}}{R}=\frac{4}{\pi}\left[\frac{\frac{\theta_{c}}{2}+\frac{1}{2} \sin \theta_{c}}{\sin \frac{\theta_{c}}{2}}\right] \tag{19}
\end{equation*}
$$

The PMBL for different absorbing circular sections with different values of $\theta_{c}$ is shown in Fig. 5. The corresponding OPMBL are identified in the same figure and also presented as a function of $\theta_{c}$ in Fig. 6. Similar to a spherical enclosure, the OPMBL for the whole cylindrical surface $(1.707 R)$ agrees well with the traditional MBL value of $1.8 R$, as well as the traditional MBL evaluated for different gas absorption bands [34]. It is interesting to note that the PMBL (and OPMBL) in some cases can be greater than the diameter ( 2 R ) of the cylindrical enclosure. Physically, the radiative exchange between two areas in a twodimensional cylindrical surface includes the radiative exchange between differential areas outside of the two-dimensional plane for which the line-of-sight length scale is greater than the diameter of the two-dimensional circular cross-section. The PMBL (and OPMBL) can thus be greater than the diameter of the circular cross-section. The traditional MBL cannot account for this important physical effect.

The effectiveness of the OPMBL and the deficiency of the traditional MBL in generating approximations to the differential exchange factor is demonstrated in Fig. 7 for the half-circular upper section $\left(\theta_{c}=\pi / 2\right)$. The error of the traditional MBL is substantial with a relative error of more than $40 \%$ in the region of moderate optical thickness.

Using the principle of superposition, the OPMBL results generated for the upper circular section of the surface can be used to generate the exchange factor between two arbitrary circular arcs with geometry as shown in Fig. 8. The exchange factor can be written as a single integration as

$$
s_{1} s_{2}=\int_{A_{1}}\left[\begin{array}{l}
F_{d 1-2 U}\left(\theta_{d 1-2 U}\right) e^{-a L_{p m b, o}\left(\theta_{d 1-2 U}\right)}  \tag{20}\\
-F_{d 1-2 L}\left(\theta_{d 1-2 L}\right) e^{-a L_{p m b, o}\left(\theta_{d 1-2 L}\right)}
\end{array}\right] d A_{1}
$$

where $\theta_{d 1-2 U}$ and $\theta_{d 1-2 L}$ are the angular coordinates at the lower and upper edge of $A_{2}$ relative to $d A_{1}$ as shown in Fig. 8. Since OPMBL is independent of the absorption coefficient, this procedure can be used to generate the radiative heat transfer between the two circular arcs with any absorbing non-gray medium with known spectral absorption characteristics. Solutions for a $\mathrm{CO}_{2} / \mathrm{H}_{2} \mathrm{O} /$ soot mixture using RADNNET [44] as the spectral solver are currently under consideration and the computer code will be made available to the community in future publications.

### 2.3 Slab

For an infinite two-dimensional slab, the radiative exchange is considered for two cases with $d A_{l}$ is either parallel or perpendicular to the absorbing surface as shown in Figs. 9a and 9b. The differential exchange factor for the case with parallel $d A_{l}$ (Fig. 9a) is given by (see Appendix for the detailed derivation)

$$
\begin{equation*}
\left[\frac{d s_{1} s_{2}}{d A_{1}}\right]_{p p}=\int_{0}^{L / D} \frac{1}{\left(\eta^{2}+1\right)^{\frac{3}{2}}} S_{3}\left[a D \sqrt{\eta^{2}+1}\right] d \eta \tag{21}
\end{equation*}
$$

with $\eta=x / D$. The two length scales, $L$ and $D$, correspond to the width of the finite area $A_{2}$ and the distance between $d A_{1}$ and $A_{2}$, as shown in Fig. 9 a. The view factor is

$$
\begin{equation*}
\left[F_{d 1-2}\right]_{p p}=\left[\frac{d s_{1} s_{2}}{d A_{1}}\right]_{p p}(a D=0)=\frac{1}{2} \frac{L}{\sqrt{L^{2}+D^{2}}} \tag{22}
\end{equation*}
$$

The PMBL is

$$
\begin{equation*}
\frac{L_{p m b, p p}}{D}=-\frac{1}{a D} \ln \left[2 \sqrt{1+\frac{D^{2}}{L^{2}}} \int_{0}^{L / D} \frac{1}{\left(\eta^{2}+1\right)^{\frac{3}{2}}} S_{3}\left[a D \sqrt{\eta^{2}+1}\right] d \eta\right] \tag{23}
\end{equation*}
$$

In the optically thin limit $(a D \rightarrow 0)$,

$$
\begin{equation*}
\frac{L_{p m b, p p, 0}}{D}=\frac{4}{\pi} \frac{\sqrt{L^{2}+D^{2}}}{L} \tan ^{-1} \frac{L}{D} \tag{24}
\end{equation*}
$$

The corresponding expressions for the case with a perpendicular $d A_{l}$, with the geometry as shown in Fig. 9b, are

$$
\begin{gather*}
{\left[\frac{d s_{1} s_{2}}{d A_{1}}\right]_{p d}=\int_{0}^{L / D} \frac{\eta}{\left(\eta^{2}+1\right)^{\frac{3}{2}}} S_{3}\left[a D \sqrt{\eta^{2}+1}\right] d \eta}  \tag{25}\\
{\left[F_{d 1-2}\right]_{p d}=\left[\frac{d s_{1} s_{2}}{d A_{1}}\right]_{p d}(a D=0)=\frac{1}{2}\left(1-\frac{D}{\sqrt{L^{2}+D^{2}}}\right)}  \tag{26}\\
\frac{L_{p m b, p d}}{D}=-\frac{1}{a D} \ln \left[2 \frac{\sqrt{D^{2}+L^{2}}}{\sqrt{D^{2}+L^{2}-D}} \int_{0}^{L / D} \frac{\eta}{\left(\eta^{2}+1\right)^{\frac{3}{2}}} S_{3}\left[a D \sqrt{\eta^{2}+1}\right] d \eta\right]  \tag{27}\\
\frac{L_{p m b, p d, 0}}{D}=\frac{2}{\pi} \frac{\sqrt{D^{2}+L^{2}}}{\sqrt{D^{2}+L^{2}}-D} \ln \left(1+\frac{L^{2}}{D^{2}}\right) \tag{28}
\end{gather*}
$$

The PMBL for the two different orientations of $d A_{l}$ is presented in Figs. 10a and 10b. The corresponding OPMBL is shown in Fig. 11. It is interesting to note that the value of OPMBL differs significantly from the traditional MBL of 1.8D for both cases. The OPMBL with a perpendicular $d A_{1}, L_{p m b, p d, o}$, is generally greater than the OPMBL with a parallel $d A_{1}, L_{p m b, p p, o}$ (more than a factor of 2 in the region of large optical thickness). Physically, the energy emitted from a perpendicular $d A_{l}$ can penetrate much further along the upper surface than energy emitted from a parallel $d A_{l}$. This accounts for the large increase in the PMBL and OPMBL.

The error of the traditional MBL is illustrated in Figs. 12a and 12b for an upper surface with $\mathrm{L} / \mathrm{D}=5$ (close to the infinite slab for the parallel case). While the approximate
exchange factor with OPMBL agrees well with the exact solution, the approximate exchange factor generated with the traditional MBL has significant errors (with a maximum absolute error of 0.03 and a relative error of more than $30 \%$ in the region of moderate optical thickness).

For two-dimensional finite areas as shown in Figs. 13a and 13b, the exchange factor can be generated using the OPMBL results by superposition as follow

$$
\left[s_{1} s_{2}\right]_{p p}=\int_{A_{1}}\left[\begin{array}{l}
F_{d 1-2 U, p p}\left(\left(L_{U}-x\right) / D\right) e^{-a L_{p m b, p p, o}\left(L_{U} / D\right)}  \tag{20a}\\
-F_{d 1-2 L, p p}\left(\left(L_{L}-x\right) / D\right) e^{-a L_{p m b, p p, o}\left(L_{L} / D\right)}
\end{array}\right] d A_{1}
$$

for the case with two parallel areas (Fig. 13a), and

$$
\left[s_{1} s_{2}\right]_{p d}=\int_{A_{1}}\left[\begin{array}{l}
F_{d 1-2 U, p d}\left(L_{U} /(D-z)\right) e^{-a L_{p m b, p d, o}\left(L_{U} /(D-z)\right)}  \tag{20b}\\
-F_{d 1-2 L, p d}\left(L_{L} /(D-z)\right) e^{-a L_{p m b, p d, o}\left(L_{L} /(D-z)\right)}
\end{array}\right] d A_{1}
$$

for the case with two perpendicular areas (Fig. 13b). Similar to the 3D total exchange factors developed for rectangular areas [42], Eqs. (20a) and (20b) can be considered as fundamental solutions for general 2D non-gray radiative heat transfer using superposition with a specific spectral radiation solver. Using RADNNET [44] as the spectral solver, these solutions are currently being developed and computer software will be made available to the community in future publications.

## 3. Conclusion

A new concept of point mean beam length (PMBL) is presented. Numerical results for PMBL are generated for three specific geometries (sphere, cylinder, and parallel slab). For all three geometries, the effect of the variation of PMBL with the optical thickness on the evaluation of the exchange factor is not strong and a constant length scale can be used to generate an accurate evaluation of the exchange factor over the full range of optical thicknesses. An "optimal" point mean beam length (OPMBL) is identified as the appropriate length scale.

For radiative exchange between the full bounding surface and itself in enclosures with simple geometries (sphere, cylinder, and parallel slab), the OPMBL and the traditional MBL (3.6V/A) are approximately equal. The two concepts, therefore, are equally effective in predicting the non-gray exchange factor for those cases. But for radiative exchange between different parts of the enclosed surface, results generated by the traditional MBL have significant errors, while results generated by the OPMBL approach agree well with exact solutions.

For enclosures with simple geometries (sphere, cylinder, and parallel slab), analytical expressions for OPMBL for a part of the bounding surface are developed and numerical solutions are presented. For a two-dimensional infinite cylinder and parallel slab, these OPMBL results can be further used to generate fundamental solutions for twodimensional non-gray radiative heat transfer in enclosures with arbitrary geometries.

While the current work is limited only to isothermal media, the solutions provide valuable benchmarks which can be used to validate approaches using other RTE solvers
and differential spectroscopic models. Extension of the method to non-isothermal media will be the focus of future works.

## 4. Nomenclature

| $a$ | absorption coefficient, $1 / \mathrm{m}$ |
| :---: | :---: |
| $A_{i}$ | area ( $\mathrm{i}=1,2$ ), $\mathrm{m}^{2}$ |
| $d A_{i}$ | differential area ( $\mathrm{i}=1,2$ ), $\mathrm{m}^{2}$ |
| $d s_{1} s_{2}$ | differential exchange factor between differential area $d A_{1}$ and finite area $A_{2}, \mathrm{~m}^{2}$ |
| D | dimensional variables, m, Figs, 9a, 9b, 13a, 13b |
| E | error using a constant length scale to approximate the transmissivity between $d A_{1}$ and $A_{2}$, Eq. (12b) |
| $F_{d 1-2}$ | differential view factor between differential area $d A_{1}$ and finite area $A_{2}$ |
| $F_{1-2}$ | differential view factor between finite area $A_{1}$ and finite area $A_{2}$ |
| $L$ | pathlength, m |
| $L_{U}$ | dimensional variables, Fig. 13a, 13b |
| $L_{L}$ | dimensional variables, Fig. 13a, 13b |
| $L_{p m b}$ | point mean beam length, m |
| $L_{p m b, o}$ | optimal point mean beam length, $m$ |
| $L_{m b}$ | traditional mean beam length, m |
| $\vec{n}_{i}$ | unit normal vector of surface i |
| $R$ | radius of sphere (cylinder) in Fig. 1 |
| $\vec{r}_{i}$ | vector location of area $d A_{i}$ |
| $\vec{r}_{i j}$ | vector point from $d A_{i}$ to $d A_{j}$ |
| $s_{1} S_{2}$ | exchange factor between finite area $A_{1}$ and finite area $A_{2}, \mathrm{~m}^{2}$ |
| $S_{3}$ | two dimensional integral function, Eq. (15) |
| $S$ | error function used to determine OPMBL, Eq. (10a) |
| $x$ | dimensional coordinate, Figs. 9a, 9b, 13a, 13b |
| $y$ | dimensional coordinate, Figs. 9a, 9b, 13a, 13b |
| $z$ | dimensional coordinate, Figs. 9a, 9b, 13a, 13b |

subscripts
pp parallel case
$p d \quad$ perpendicular case

## Greek Symbol

$\beta \quad$ angular variable, Fig. 1
$\eta \quad$ dimensionless variable, Eq. (21)
$\theta$ angular variable, Fig. 1
$\theta_{c} \quad$ angular variable of the spherical cap
$\theta_{i} \quad$ angular variable ( $\mathrm{i}=1,2$ ), Eq. (1)
$\theta_{d 1-2 U}$ angle between $d A_{l}$ and the upper section of $A_{2}$, Fig. 8
$\theta_{d 1-2 L}$ angle between $d A_{l}$ and the lower section of $A_{2}$, Fig. 8
$\tau_{d 1-2}$ geometric mean transmittance between area $d A_{1}$ and $A_{2}$, Eq. (2)
$\tau_{1-2} \quad$ geometric mean transmittance between area $A_{l}$ and $A_{2}$, Eq. (5)

## 5. Appendix

The mathematical development leading to the various PMBL and OPMBL expressions is presented in this Appendix.

### 5.1 Sphere

For the geometry as shown in Fig. 1 for the spherical system, the differential exchange factor between $d A_{1}$ and $d A_{2}$ is given by

$$
\begin{equation*}
d s_{1} d s_{2}=\frac{\left|\vec{r}_{21} \cdot \vec{n}_{1}\right|\left|\vec{r}_{21} \cdot \vec{n}_{2}\right|}{\pi L^{4}} e^{-a L} d A_{1} d A_{2} \tag{A1}
\end{equation*}
$$

with $\vec{n}_{1}$ and $\vec{n}_{2}$ being the normal vector of area $d A_{l}$ and $d A_{2}$ defined as

$$
\begin{equation*}
\vec{n}_{1}=(0,0,1), \vec{n}_{2}=(-\sin \theta \cos \varphi,-\sin \theta \sin \varphi,-\cos \theta) \tag{A2}
\end{equation*}
$$

The location of $d A_{1}$ and $d A_{2}$ expressed in a vector notation are

$$
\begin{equation*}
\vec{r}_{1}=(0,0,-R), \vec{r}_{2}=(R \sin \theta \cos \varphi, R \sin \theta \sin \varphi, R \cos \theta) \tag{A3}
\end{equation*}
$$

$\vec{r}_{21}$ is a vector originated from $d A_{1}$ to $d A_{2}$ given by

$$
\begin{equation*}
\vec{r}_{21}=(R \sin \theta \cos \varphi, R \sin \theta \sin \varphi, R(1+\cos \theta)) \tag{A4}
\end{equation*}
$$

Substituting Eqs. (A2), (A3) and (A4) into Eq. (A1) yields

$$
\begin{equation*}
d s_{1} d s_{2}=\frac{R^{2}(1+\cos \theta)^{2}}{\pi L^{4}} e^{-a L} d A_{1} d A_{2} \tag{A5}
\end{equation*}
$$

which is equivalent to Eq. (7) in the main text. L is the length of the vector $\vec{r}_{21}$ given by

$$
\begin{equation*}
L=\left|\vec{r}_{21}\right|=\sqrt{2 R^{2}(1+\cos \theta)} \tag{A6}
\end{equation*}
$$

Substituting Eq. (A6) into Eq. (A5) and set

$$
\begin{equation*}
d A_{2}=R^{2} \sin \theta d \theta d \varphi \tag{A7}
\end{equation*}
$$

Eq. (A1) becomes

$$
\begin{equation*}
d s_{1} d s_{2}=\frac{d A_{1}}{4 \pi} e^{-a R \sqrt{2(1+\cos \theta)}} \sin \theta d \theta d \varphi \tag{A8}
\end{equation*}
$$

For $A_{2}$ being the upper spherical section with $0<\theta<\theta_{c}$, Eq. (A8) can be integrated to yield

$$
\begin{gather*}
\frac{d s_{1} s_{2}}{d A_{1}}=-\frac{1}{2 a R}\left[2 e^{-2 a R}-\sqrt{2\left(\cos \theta_{c}+1\right)} e^{-\sqrt{2\left(\cos \theta_{c}+1\right)} a R}\right]+ \\
\frac{1}{2(a R)^{2}}\left(e^{-\sqrt{2\left(\cos \theta_{c}+1\right)} a R}-e^{-2 a R}\right) \tag{A9}
\end{gather*}
$$

which is identical to Eq. (8).

### 5.2 Cylinder

Consider the geometry and coordinate system in Fig. 1 as that in a two-dimensional plane, the differential exchange factor is formally identical to the general expression shown in Eq. (A1). Choosing a coordinate system with $d A_{1}$ situated at the origin ( $0,0,0$ ), the various vectors are modified for the 2D planar system as follow:

$$
\begin{align*}
& \vec{n}_{1}=(0,0,1), \quad \vec{n}_{2}=(\sin \theta, 0, \cos \theta)  \tag{A10}\\
& \vec{r}_{1}=(0,0,0), \vec{r}_{2}=(R \sin \beta, y, R \cos \beta) \tag{A11}
\end{align*}
$$

Note that $d A_{I}$ is a differential area at the $\mathrm{y}=0$ plane while $d A_{2}$ is a differential area at an arbitrary value of y . The vector $\vec{r}_{21}$ and the line of sight distance is given by

$$
\begin{align*}
& \vec{r}_{21}=(L \sin \beta, y, L \cos \beta)  \tag{A12}\\
& S=\left|\vec{r}_{21}\right|=\sqrt{L^{2}+y^{2}} \tag{A13}
\end{align*}
$$

The directional cosine at the differential area $d A_{l}$ is

$$
\begin{equation*}
\frac{\left|\vec{r}_{21} \cdot \vec{n}_{1}\right|}{s}=\frac{L \cos \beta}{s} \tag{A14}
\end{equation*}
$$

The directional cosine at the differential area $d A_{2}$ is

$$
\begin{equation*}
\frac{\left|\vec{r}_{21} \cdot \vec{n}_{2}\right|}{S}=\frac{L(\sin \beta \sin \theta+\cos \beta \cos \theta)}{S} \tag{A15}
\end{equation*}
$$

Using the following expression for the differential area of $d A_{2}$,

$$
\begin{equation*}
d A_{2}=d y d l_{2} \tag{A16}
\end{equation*}
$$

where $d l_{2}$ is the width of the infinite strip corresponds to $d A_{2}$ measured relative to $\theta$, the two-dimensional angular coordinate of the unit normal. The product of the directional cosine and differential area is

$$
\begin{equation*}
\frac{\left|\vec{r}_{21} \cdot \vec{n}_{2}\right|}{S} d A_{2}=\frac{L(\sin \beta \sin \theta+\cos \beta \cos \theta)}{S} d y d l_{2}=\frac{L}{S} d y d l_{2, n} \tag{A17}
\end{equation*}
$$

with

$$
\begin{equation*}
d l_{2, n}=d l_{2}(\sin \beta \sin \theta+\cos \beta \cos \theta)=L d \beta \tag{A18}
\end{equation*}
$$

being the width of the infinite strip measured relative to $\beta$, the angular coordinate of the vector $\vec{r}_{21}$. The differential exchange factor becomes

$$
\begin{equation*}
d s_{1} d s_{2}=\frac{L^{3} \cos \beta}{\pi S^{4}} e^{-a s} d A_{1} d \beta d y \tag{A19}
\end{equation*}
$$

Integrating over the $y$-direction yields

$$
\begin{equation*}
\frac{1}{\pi} \int_{-\infty}^{\infty} \frac{L^{3}}{S^{4}} e^{-a S} d y=\frac{2}{\pi} \int_{1}^{\infty} \frac{1}{\eta^{3}} e^{-a L \eta} \frac{d \eta}{\sqrt{\eta^{2}-1}}=S_{3}(a L) \tag{A20}
\end{equation*}
$$

Substituting Eq. (A20) into Eq. (A19) leads to Eq. (18).

### 5.3 Slab

Using the geometry and coordinate system as shown in Fig. 13a, the exchange factor between $d A_{1}$ and $d A_{2}$ is given by

$$
\begin{equation*}
d s_{1} d s_{2}=\frac{D^{2}}{\pi S^{4}} e^{-a s} d A_{1} d A_{2}=\frac{D^{2}}{\pi s^{4}} e^{-a S} d A_{1} d x d y \tag{A21}
\end{equation*}
$$

with

$$
\begin{equation*}
S^{2}=x^{2}+y^{2}+D^{2} \tag{A22}
\end{equation*}
$$

Integrating over the y-direction yields

$$
\begin{equation*}
\frac{1}{\pi} \int_{-\infty}^{\infty} \frac{D^{2}}{s^{4}} e^{-a s} d y=\frac{D^{2}}{\left(x^{2}+D^{2}\right)^{\frac{3}{2}}} S_{3}\left[a \sqrt{x^{2}+D^{2}}\right] \tag{A23}
\end{equation*}
$$

For $A_{2}$ being a two dimensional area extended from $\mathrm{x}=0$ to $\mathrm{x}=\mathrm{L}$

$$
\begin{equation*}
\frac{d s_{1} s_{2}}{d A_{1}}=\int_{0}^{L / D} \frac{1}{\left(\eta^{2}+1\right)^{\frac{3}{2}}} S_{3}\left[a D \sqrt{\eta^{2}+1}\right] d \eta \tag{A24}
\end{equation*}
$$

For $d A_{l}$ in the vertical position as shown in Fig. 13b, the exchange factor is given by

$$
\begin{equation*}
d s_{1} d s_{2}=\frac{D z}{\pi S^{4}} e^{-a S} d A_{1} d A_{2}=\frac{D z}{\pi s^{4}} e^{-a S} d A_{1} d z d y \tag{A25}
\end{equation*}
$$

Following the same development, the exchange factor becomes

$$
\begin{equation*}
\frac{d s_{1} s_{2}}{d A_{1}}=\int_{0}^{L / D} \frac{\eta}{\left(\eta^{2}+1\right)^{\frac{3}{2}}} S_{3}\left[a D \sqrt{\eta^{2}+1}\right] d \eta \tag{A26}
\end{equation*}
$$

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Figure 1: Geometry and coordinate system for a spherical system.


Figure 2: The effect of optical thickness $(a R)$ on PMBL for radiative heat transfer to different sections of the surface of a spherical enclosure and the corresponding value of OPMBL.


Figure 3: The OPMBL for the different upper sections of the surface of a spherical enclosure.


Figure 4: Comparison between the exact exchange factor (generated by direct integration) and approximate exchange factor generated by OPMBL and the error of the approximation for a section of the spherical surface with $\theta_{c}=\pi / 2$ (note that the line for the exact solution of $d s_{1} s_{2}$ and the line for $F_{d 1-2} \exp \left(-a L_{p m b, o}\right)$ are indistinguishable from each other).


Figure 5: The effect of optical thickness $(a R)$ on PMBL for radiative heat transfer to different sections of the surface of an infinite cylindrical enclosure and the corresponding value of OPMBL.


Figure 6: The OPMBL for the different sections of the surface of a 2D cylindrical enclosure.


Figure 7: Comparison between the exact exchange factor (generated by direct integration) and approximate exchange factor generated by OPMBL and the error of the approximation for a section of the circular surface of an infinite cylinder with $\theta_{c}=\pi / 2$ (note that the line for the exact solution of $d s_{1} s_{2}$ and the line for $F_{d 1-2} \exp \left(-a L_{p m b, o}\right)$ are indistinguishable from each other).


Figure 8: Geometry and coordinate system for the exchange factor between two finite circular arcs at the surface of an infinite cylinder.


Figure 9: Geometry and coordinate system for a 2D slab with a parallel $d A_{I}$ (9a) and perpendicular $d A_{l}(9 \mathrm{~b})$.


Figure 10: PMBL for 2D slab with different L/D for the parallel $d A_{I}$ (10a) and perpendicular $d A_{l}(10 \mathrm{~b})$.


Figure 11: OPMBL for 2D slab with different L/D with a parallel $d A_{l}\left(L_{o p m b, p p}\right)$ and a perpendicular $d A_{l}\left(L_{o p m b, p d}\right)$.


Figure 12: Comparison between the exact exchange factor (generated by direct integration) and approximate exchange factor generated by OPMBL and the error of the approximation generated by the traditional MBL (1.8D) for a 2 D slab with $\mathrm{L} / \mathrm{D}=5$, a parallel $d A_{l}$ (12a) and perpendicular $d A_{l}(12 \mathrm{~b})$ (note that the line for the exact solution of $d s_{1} s_{2}$ and the line for $F_{d 1-2} \exp \left(-a L_{p m b, p p, o}\right)$ and the line for $F_{d 1-2} \exp \left(-a L_{p m b, p d, o}\right)$ are indistinguishable from each other).


Figure 13: Geometry and coordinate system for the exchange factor between two finite 2D areas with a parallel (13a) or perpendicular (13b) orientation.

