Scalable Workflow System for Whole Slide Microscopy Analyses Using Neural Networks

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Outline

- ▶ Part I Specific Application
 - Microscope Image Acquisition
 - ► In-Situ Image Based Measurements
 - Data Motion
 - Triggers from Acquisition Software
 - Scalable Data Processing
 - ▶ HTGS, Fast Image
- ▶ Part II Generalization
 - ▶ How to write software to scale with hardware
 - Problem Decomposition
 - Software developer efficiency

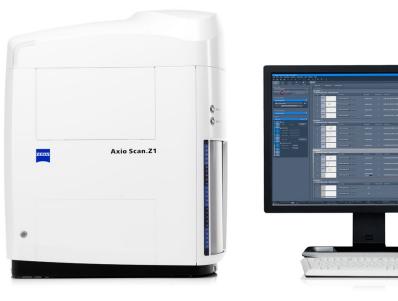






Motivating Problem

- Image-based measurements via Automated Microscopy
 - Automation increases data generation rate
- Microscopes can produce 100's of whole slide images per day
 - 5 gigapixel whole slide images
 - ▶ 100000 x 50000 pixels at 10x magnification
 - > 5 minutes to acquire each image
- Acquisition rate defines the compute budget for performing image-based measurements.



Zeiss AxioScan ZI Microscope

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Whole Slide Image Analysis Problem

Find all 100² pixel objects of interest within each 100,000 x 50,000 pixel slide

Example Slide

Goal: Automate tedious, error prone tasks



In Situ Image Analysis

- Perform analysis in semi-real-time while the next image is being acquired
- Brings image analysis into the wet-lab, providing immediate feedback/results

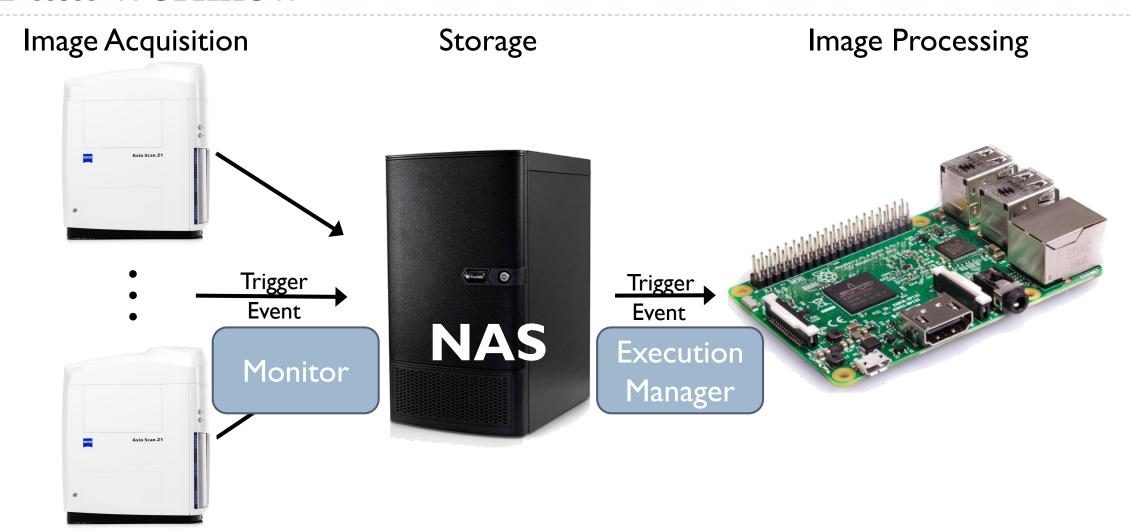
Challenges

- System must be robust and stable
- Microscope acquisition time defines compute budget

Benefits

- End to end solution, user scanned image results are available 90 seconds later
 - Concurrent image acquisition and image processing
- Data management
 - Integration with Zeiss Microscope to automatically copy image file to storage NAS
 - Processing computation initiated automatically when copy completes

Data Workflow



Microscope Acquisition System

- Queue up to 150 slides to be scanned
- AxioScan ZI is driven from an attached computer
- ▶ Zeiss software scans images one at a time
- Images saved locally
- No local compute is allowed
- Lightweight program monitors scan status

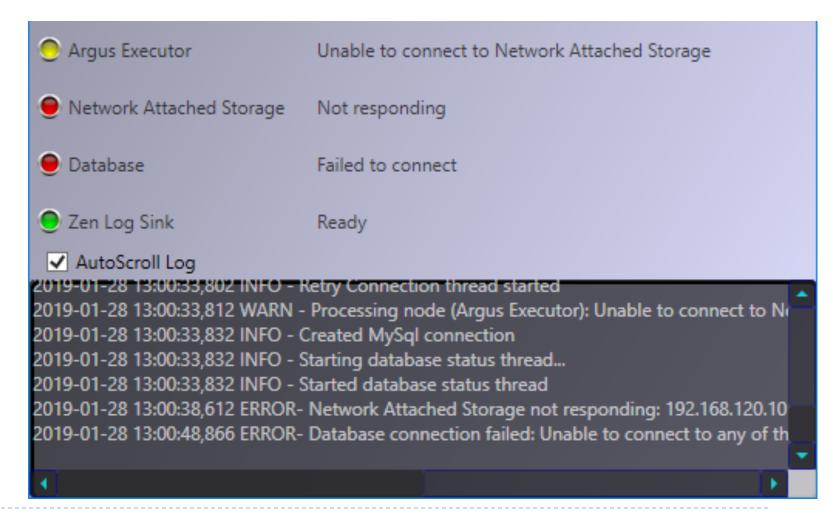




Zeiss AxioScan ZI Microscope

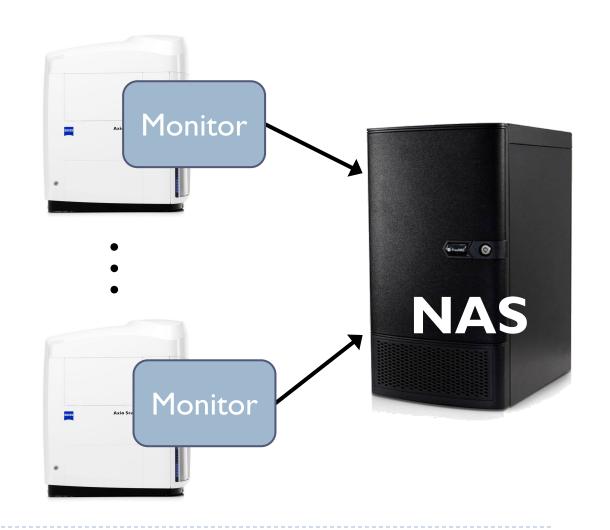
Acquisition Monitor

- Runs on Microscope Machine
- Two responsibilities
 - Showing System Status
 - Monitoring Zeiss log and copying completed scans to the NAS
- Green board means everything is up and running



Acquisition Monitor

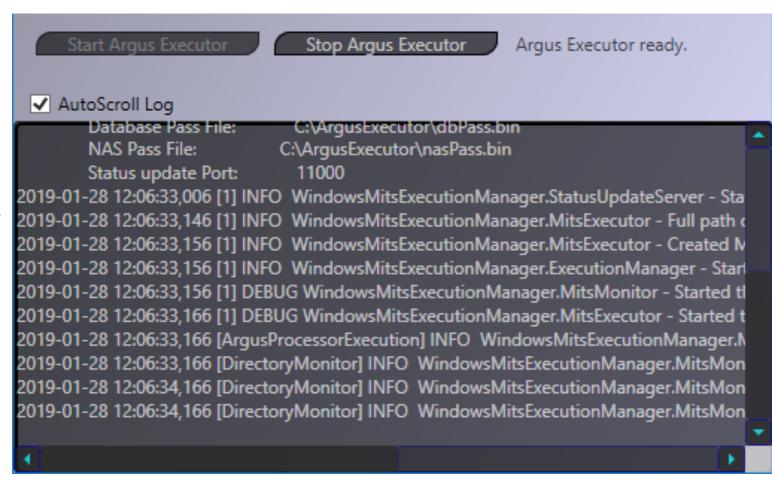
- ▶ Runs on each Microscope Machine
 - System supports N microscopes
 - Current hardware supports 4 microscopes
- Hooks to Zeiss event log
 - Watches for scan completed message
- Launches image copy to NAS
 - Able to recover if the network goes down
- Processing starts upon copy completion
- Copy & Processing decoupled from acquisition
 - Compute is overlapped with Acquisition



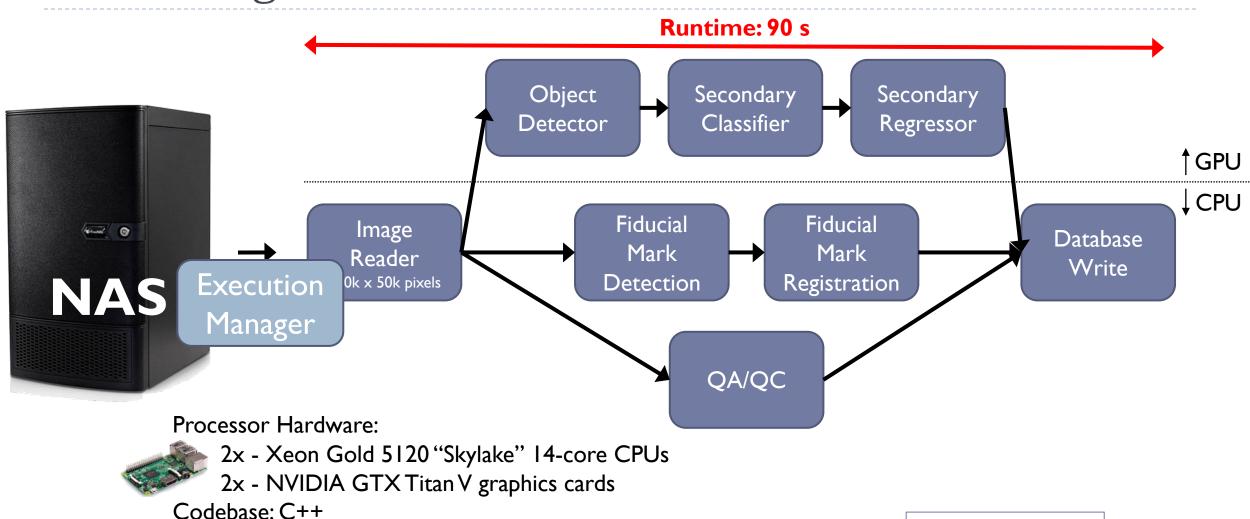
Execution Manager

Runs on Processing Machine

- Launches Processing Workflow Per Image
 - Has an input queue of images
 - Monitor adds to that queue
- Displays Processing Log



Processing Workflow



Libraries: OpenCV, TensorRT, LibCZI, FastImage*, HTGS*

* NIST developed

Scalable Workflows

HTGS - Hybrid Task Graph Scheduler

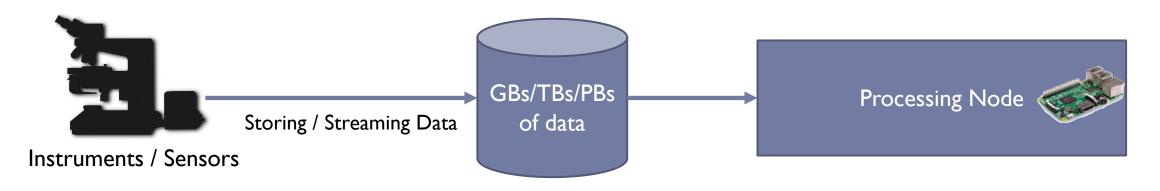
Processing Workflow

Requirements

- Meet time demands
- Fully utilize processing hardware
- Scales with increase to data rates
 - Multicore
 - Adding more GPUs to a machine
 - Additional processing nodes

Approach

- Asynchronous pipelined workflow
 - Effectively keeps processing resources busy
- Appropriately size hardware
 - ▶ To deliver throughput



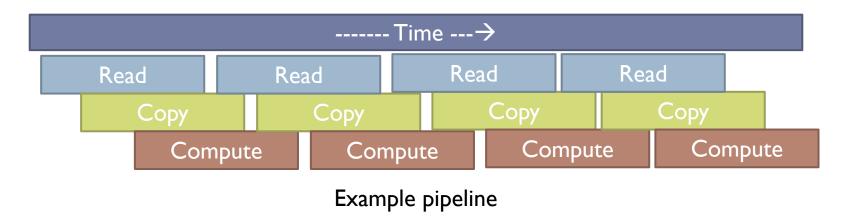
What is Pipelining

Dictionary

A form of computer organization in which successive steps of an instruction sequence are executed in turn by a sequence of modules able to operate concurrently, so that another instruction can be begun before the previous one is finished.

Applicable

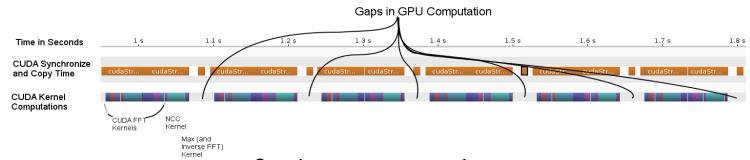
- Instruction pipelining: pre-fetching, branch prediction
- Task pipelining: reading/writing data, copying, compute



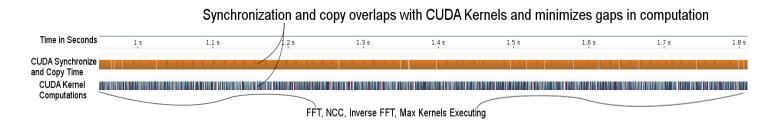
Why Asynchronous Pipelined Workflow?

Impacts on performance

- Moving data between address spaces (CPU/GPU)
- Disk I/O
- Database updates
- Overlap computation with data motion, disk I/O, and database updates
- May require decomposing problem into multiple subproblems



Synchronous approach



Asynchronous pipelined workflow approach

Challenges of Asynchronous Pipelining Workflows

- Legacy code often does not play well with pipelining
 - Restructuring and/or re-writing code may be necessary
 - Possibly algorithmic redesign
- Writing code that pipelines from scratch requires a lot of code structuring
 - Multi-threading
 - Thread safety
- Making sense of asynchronous behavior in an algorithm is not always obvious
- ▶ Solution: use existing frameworks ... helps
 - Task libraries
 - ▶ StarPU, Legion, ...
 - Hybrid Task Graph Scheduler (HTGS)

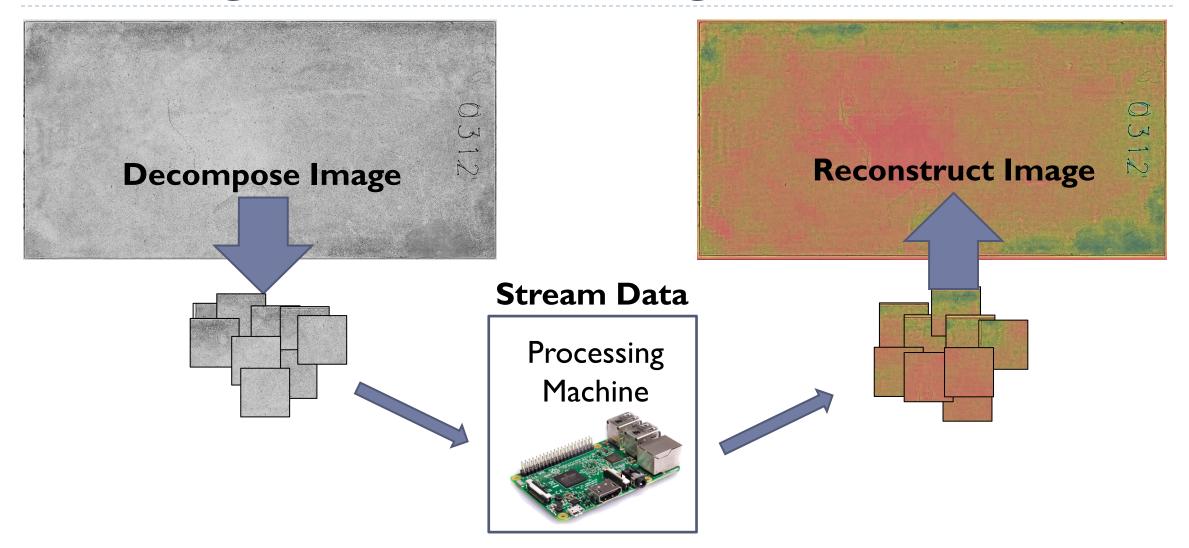
Hybrid Task Graph Scheduler

- Our approach for developing asynchronous pipeline workflows
- Application is a dataflow graph
 - Persists at runtime
 - Experimentation for performance
 - Debug, Profile, Visualize performance using the dataflow representation
- Targets powerful single nodes
 - Dual multicore CPUs & multiple GPUs

- Focus on
 - Separation of concerns
 - State maintenance versus computation
 - Coarse-grain parallelism
 - Hide latency of data motion
 - Memory management
- C++ Header API only



Streaming Tile Based Processing



HTGS API

- Task interface
 - ▶ Templates define Input and Output
 - Execute(input)
 - Called when data is available for the task
 - addResult(output)
 - Called by user when output is ready to be sent to the next task
- Data is sent to the task
 - ► Each task holds a pool of threads
 - Extra data + multiple threads = parallelism

- Specialty tasks
 - Bookkeeper task
 - Manages complex data dependencies
 - Maintains state of computation
 - CUDA Task
 - Binds task to NVIDIA CUDA GPU
 - Execution Pipeline Task
 - Creates copies of a task graph
 - ☐ Each copy bound to a specified GPU
 - Memory Manager
 - Attaches memory edge to a task
 - □ getMemory("nameOfEdge")
 - ☐ Binds memory allocation to address space
 - ☐ CPU, GPU, etc.

HTGS Profiling

- Zero overhead profiling
 - Profiling is gathered in both Release and Debug
 - Task level
- Graph visualization report generated after every run
 - Immediately identify performance impacts per task
 - Customize task profiling to obtain more details
- Optimize per task
 - Find alternative methods

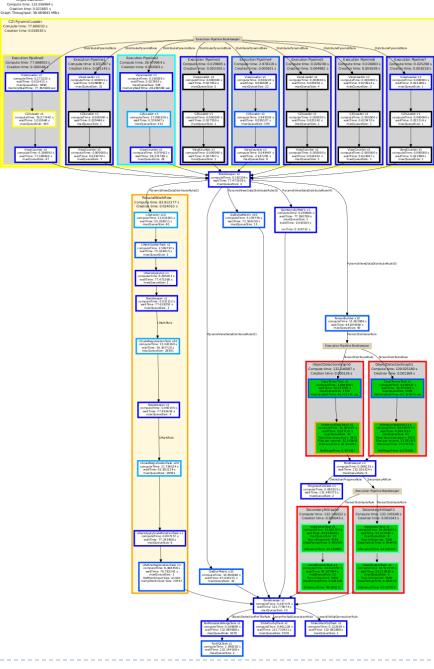
Detector x10 computeTime: 65.02001 s waitTime: 32.006141 s maxQueueSize: 10

QaIntensityMetric x1 computeTime: 0.243897 s waitTime: 39.637898 s maxQueueSize: 1 buildTime: 0.053468 s runTime: 0.190006 s

Detector x10 computeTime: 0.518991 s waitTime: 39.166141 s maxQueueSize: 3

HTGS Software Engineering

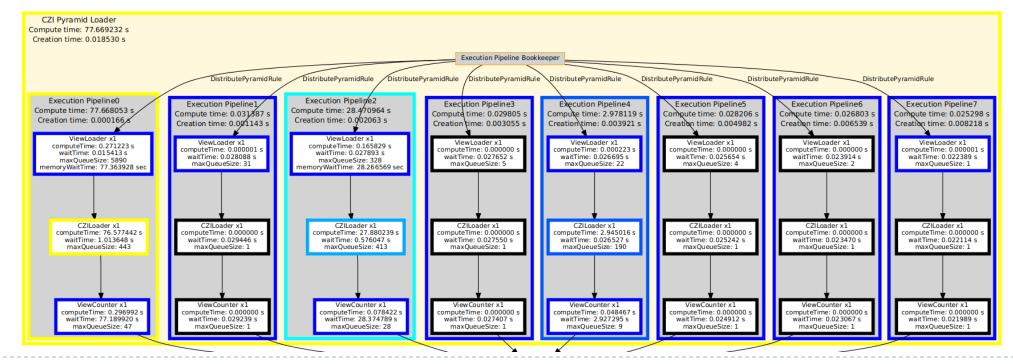
- Distribute tasks to developers
 - Narrow view of the world
 - Operate only on data sent as input and produce output
 - Difficult for developers to have code conflicts
 - Not impossible
- Maintains parallelism of the workflow
- Visual representation of critical path
 - Self-motivating to improve performance



Microscopy Analysis

Image Reading

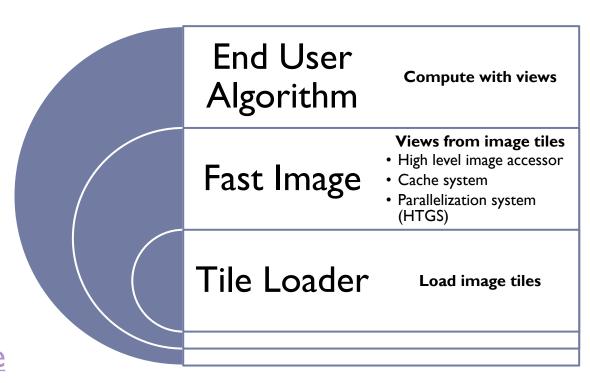
- Zeiss generates CZI images (pyramidal)
 - Tasks can operate at whatever pyramid they need to
 - Fiducial Detection happens at level 2 (25% resolution)
- Read all pyramid levels in parallel using Fastlmage



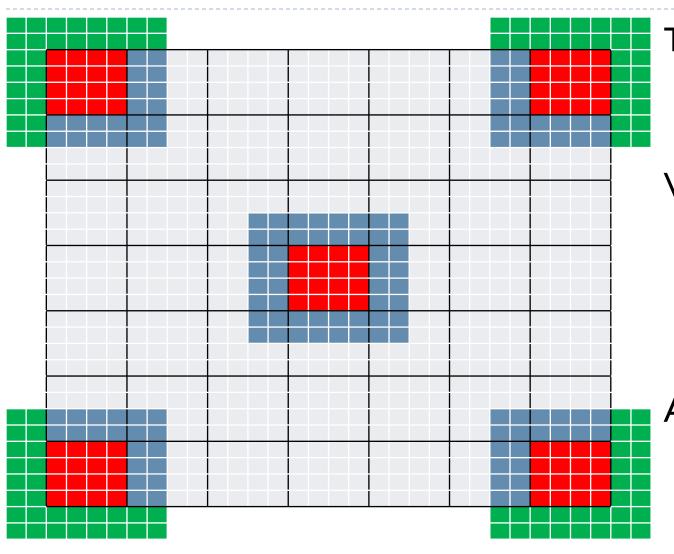
Fast Image

- ▶ C++ Library based on HTGS
- High level API to access an image
 - Or part of it
- Only access interesting views in an image

https://github.com/usnistgov/FastImage



Views and Tiles



Tile

Part of the image (here 28x28 pixels) given by the image loader

View

- Center tile (here 4x4 pixels)
- Neighboring pixels within a radius (here 2 pixels)
- ▶ Ghost (halo) values

Advantages

- Reduce memory footprint
- Enable tile caching & parallelism

Problem Decomposition into Tasks

Task Graph

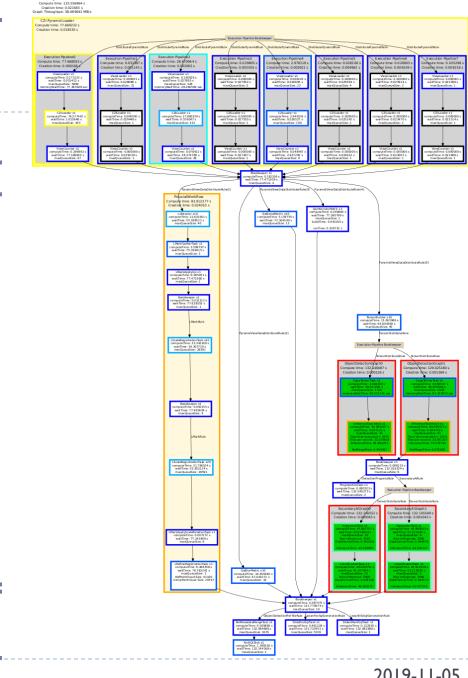
- ▶ Traditional CV Tasks
 - Quality Analysis/Quality Control
 - Fiducial Mark Detection and Registration
 - Pipeline of subtasks
- ▶ Al Tasks
 - **Object Detection**
 - Secondary Classification/Regression

Relative Compute Time More Less

Processing Workflow **Database Transactions** GTC-DC

Image

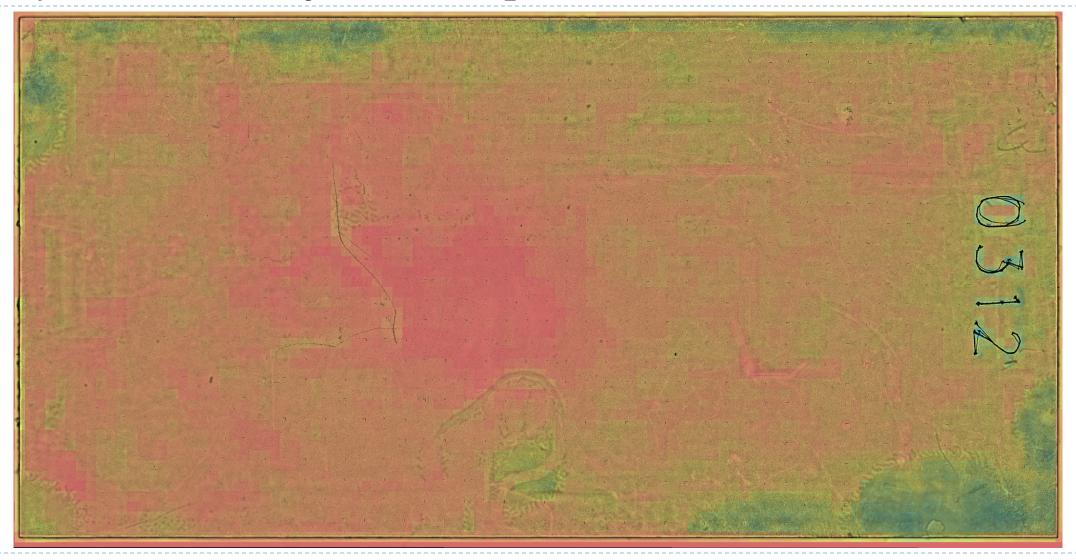
Readers



QA/QC

- Input: whole slide image coming directly from microscope
- No guarantees the image was
 - acquired correctly
 - contains the expected content
- ▶ Need to verify that the input image is within quality specifications for
 - Focus (image blur)
 - Background noise
 - Image brightness
- ▶ Each QA/QC item is a task in the HTGS system
 - Leverages OpenCV

QA/QC – Quality Heatmap



AI Tasks .MarkRule waitTime: 64.804569 s maxQueueSize: 40 yramidViewDataDistributeRule(0) LScaleRegistrationTask x 20 Execution Pipeline Bookkeeper waitTime: 54.307720 s maxQueueSize: 28591 Traditional Computer Vision Tasks Object Detection Graph1 Compute time: 132 46087 s Compute time: 129.025180 s Creation time: 0.000126 s Creation time: 0.001369 s Quality Analysis/Quality Control Fiducial Mark Detection/Registration waitTime: 77.495639 s maxQueueSize: 4 Pipeline of subtasks Al Tasks LScaleRegistrationTask x20 waitTime: 55.852124 s waitTime: 132.016324 s maxQueueSize: 28591 maxQueueSize: 6 **Object Detection** Execution Pipeline Bookkeeper waitTime: 132.045273: maxQueueSize: 2 Secondary Classification/Regression — Compute time: 132.146552 s Compute time: 132.145548 s Creation time: 0.000043 s Creation time: 0.001043 s LMarkApplyScaleRotationTask x1 computeTime: 0.007272 s waitTime: 77.243809 s Relative Compute Time mmnuteTime: 6.466358 s QaBlurMetric x 10 maxQueueSize: 1 RefPointCloud Size: 41100 waitTime: 67.016271 s ompPointCloud Size: 2979 More Less waitTime: 131.779074

AI Tasks

- Object Detection
 - Yolo v3 model
- Secondary Feature Categorization/Regression
 - Pair of ResNet50 models
- Object detector extracts Regions of Interest (ROIs)
- ▶ ROIs are streamed to secondary AI models
 - As soon as the detector task generates an ROI output
 - Classification and regression tasks are run sequentially per ROI
 - Each task adds a new metadata value to an ROI as it flows through the compute graph

Task Scalability

- Specify thread count per task to control task's processing
 - Fiducial mark detection is expensive
 - ▶ 40 threads
 - QA is cheap
 - ► I-I0 threads
- Al tasks utilize all available GPUs

QaNoiseMetric x10 computeTime: 5.159755 s waitTime: 72.504190 s maxQueueSize: 13

QaIntensityMetric x1 computeTime: 0.299864 s waitTime: 77.590799 s maxQueueSize: 1 buildTime: 0.043255 s

runTime: 0.226732 s

GPU0 **GPUI** ObjectDetectionGfaph0 ObjectDetectionGraph1 Compute time: 132./146087 s Compute time: 129.025180 s Creation time: 0.00126 s Creation time: 0.001369 s CopyTensorTask x1 CopyTensorTask x1 computeTime: 4.804308 s computeTime: 4.658547 s waitTime: 38.567265 s waitTime: 38.876036 s maxQueueSize: 1736 maxQueueSize: 1692 memoryWaitTime: 86.312240 sec memoryWaitTime: 83.353970 sec InferenceTaskYolo3 x1 InferenceTaskYolo3 x1 computeTime: 92.065567 s computeTime: 88.945573 s waitTime: 0.007121 s waitTime: 4.844719 s maxOueueSize: 41 maxOueueSize: 41 Total tiles executed = 2970Total tiles executed = 2970Tiles per second: 32.259618 Tiles per second: 33.391207 InferenceTime: 79.579791 InferenceTime: 82.694251 RoiMergeTime: 5.943457 RoiMergeTime: 6.072680 Bookkeeper x1 computeTime: 0.098135 s waitTime: 132.016324 s maxQueueSize: 6

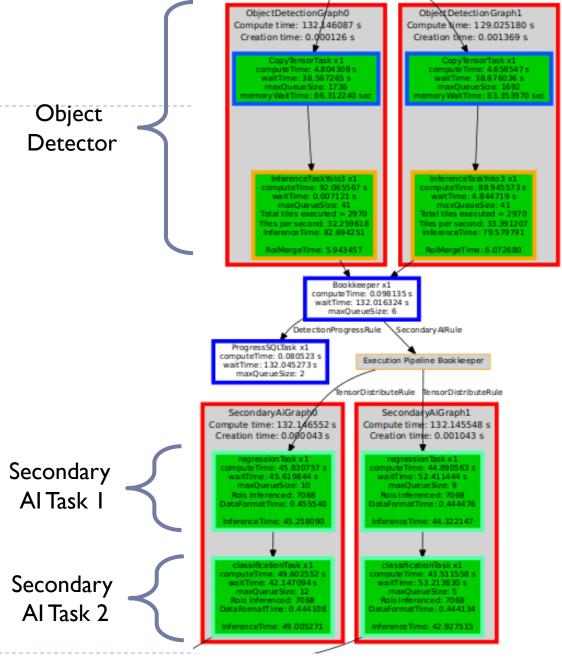
TensorRT

TensorRT

- Al models trained in Tensorflow on Power9 with VI00s
 - Trained models saved in UFF format
- Deploy Al in TensorRT
 - ▶ Enables FP16 inference using Titan V tensor cores
 - Translate from UFF to TRT
- Processor detects what UFF/TRT models exist
 - Auto-generates new optimized TRT when UFF is newer than existing TRT
 - TRT creation time is amortized over many runs
 - Generate TRT on deployment hardware to have models optimized for platform of interest

TensorRT Engine

- ▶ TensorRT engine initialization
 - Loads serialized TRT model
- One TRT Engine per AI task
 - Al tasks duplicate: one per GPU using HTGS execution pipeline
- Example with 2 Titan V GPUs used for inferencing on 3 separate TRT models
 - ▶ Each red box is a sub-workflow per GPU
- Progress updates sent to database
 - Real-time visualization of progress



Workflow Scalability

- Codebase is designed for scalability
 - Auto detects the number of GPUs
 - Initializes one AI workflow, per model, per GPU
- Add another GPU if AI tasks are the bottleneck
 - Al tasks will duplicate
- CPU tasks specify the number of threads to use
 - Allocation of threads distinct from what to compute
 - Specifying thread count controls speed of task completion
 - Allows for load balancing between different tasks
 - Fiducial mark registration is CPU-bound and uses 40 threads
 - QA is fairly cheap and gets I thread only.

Programming Scalability

- Software developers write HTGS tasks
 - Tasks are constrained so that they can scale arbitrarily if needed
- Once dev decomposes the problem into a data streaming task based processing, tasks become the logical unit of thinking
- For example, whole image is never passed through the GPU for inference.
 - ▶ Too large to fit in GPU memory
 - Inference happens per 1024 x 1024 tile managed by Fast Image
- Developers incur upfront cost of learning curve
 - Enables parallel development & testing at task level
 - Simplifies obtaining performance-oriented software

Summary

Requirements for Realtime Microscope Processing

Hardware:

- Microscope with event hooks to enable automation
- Storage for images
- Processing machine
 - Same as acquisition machine or on LAN

Software

- Fixed analysis pipeline which needs to be applied to every image coming off the microscope
- Task based, data streaming processing model
- Workflow system to orchestrate compute in a scalable manner

Future Work

- Hedgehog: next generation of HTGS
 - Hedgehog simplifies graph design
 - Each task can have multiple input types and broadcast outputs
 - Hedgehog implementation of FastImage
 - ▶ Generalization beyond image data → serialized matrices data
 - Available now

Shift from UFF AI model format to ONNX

Thank You

Questions?

- Code
 - ► HTGS: github.com/usnistgov/HTGS
 - Hedgehog: github.com/usnistgov/hedgehog
 - ► FastImage: github.com/usnistgov/FastImage
 - HedgehogFastImage: soon
- **▶** Email
 - <u>timothy.blattner@nist.gov</u>
 - michael.majurski@nist.gov