Optimization of the TES-Bias Circuit for a Multiplexed Microcalorimeter Array

W.B. Doriese · B.K. Alpert · J.W. Fowler · G.C. Hilton · A.S. Hojem · K.D. Irwin · C.D. Reintsema · D.R. Schmidt · G.M. Stiehl · D.S. Swetz · J.N. Ullom · L.R. Vale

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Abstract A transition-edge-sensor (TES) microcalorimeter's shunt resistor (R_{sh}) and thermal conductance to the cryogenic bath (G) are often considered to be interchangeable knobs with which to control detector speed. Indeed, for otherwiseidentical TES-parameter models, there are many combinations of $R_{\rm sh}$ and G that give the same decay time-constant (τ_{crit}). However, our previous work showed that with time- or code-division-multiplexed readout, the distribution of signal-to-noise ratio with frequency, which depends strongly on $R_{\rm sh}$ and G, is just as important as $\tau_{\rm crit}$. Here, we present a set of calculations to select the optimal values of $R_{\rm sh}$ and G, given a linear TES model and count-rate and energy-resolution requirements. Lower G and lower $R_{\rm sh}$ make multiplexing easier. Our calculations also determine the allowed combination of SQUID-readout noise (S_{Φ}) and multiplexer row-period (t_{row}) and row-count (N_{rows}). Recent improvements to S_{Φ} and t_{row} in the NIST time-divisionmultiplexing architecture have allowed a NIST eight-pixel TES array to be read out with 2.70 eV (full-width at half-maximum) average energy resolution at 6 keV. The improvements make the X-ray Microcalorimeter Spectrometer co-proposed by NASA and NIST for ESA's Athena X-ray observatory straightforwardly achievable, including engineering margin, with $N_{\rm rows} = 16$.

Keywords SQUID multiplexer · Transition-edge sensor · X-ray microcalorimeter

1 Introduction

One instrument envisioned for ESA's Athena X-ray mission is the X-ray Microcalorimeter Spectrometer (XMS), a 32×32 array of close-packed 250 µm-square transitionedge-sensor (TES) microcalorimeters covering a total field of view of 2.4×2.4

National Institute of Standards and Technology, Boulder, CO 80305, USA e-mail: doriese@boulder.nist.gov

W.B. Doriese (\boxtimes) \cdot B.K. Alpert \cdot J.W. Fowler \cdot G.C. Hilton \cdot A.S. Hojem \cdot K.D. Irwin \cdot

C.D. Reintsema · D.R. Schmidt · G.M. Stiehl · D.S. Swetz · J.N. Ullom · L.R. Vale

arcminute. With a per-pixel input X-ray count rate of n = 50 Hz, each XMS pixel is specified to produce an output count rate of $r \ge 40$ Hz with energy resolution of $\Delta E_{\text{FWHM}} \le 3.0$ eV for $E_{\gamma} \le 6$ keV and multiplexing factor of $N_{\text{rows}} = 16$.

A version of the XMS instrument is being proposed by the U.S. consortium of NASA/GSFC (MoAu TES arrays with "mushroom"-style absorbers) and NIST-Boulder (either time-division or code-division SQUID multiplexed readout, which are being developed in parallel). In 2008 this consortium demonstrated [1] timedivision-multiplexed (TDM) readout of a close-packed array of 32 high-resolution NASA TES devices in various TDM configurations, with the key result that a 2-column × 8-row array achieved $\langle \Delta E_{\rm FWHM} \rangle = 2.93$ eV. The detectors, whose response and performance were very uniform, had critically damped time-constants of $\tau_{\rm crit} = 280$ µs, and were similar in design to those proposed here for Athena.

In this paper, we optimize Athena's detector-bias circuit. We show how $\Delta E_{\rm FWHM}$ depends on $S_{I_{\rm MUX}}$ (the detector-current-referred, multiplexed, SQUID-amplifier noise) and on $t_{\rm rec}$, the length of the digitized records. We calculate Athena's engineering margins for various combinations of SQUID noise and speed. Finally, we demonstrate recent improvements to the NIST TDM architecture.

2 Detector Model

Although Athena-XMS specifies $\Delta E_{\rm FWHM} \leq 3.0$ eV, we specify here that after degradation due only to the multiplexed readout ($S_{I_{\rm MUX}} \neq 0$ and $t_{\rm rec} < \infty$), $\Delta E_{\rm FWHM} \leq 2.7$ eV. This leaves engineering margin for other potential sources of degradation, such as imperfect gain-drift correction, electrical and thermal crosstalk among pixels, and nonuniformity in pixel bias.

The following linear detector model is based on TESs presently under production by NASA [2]. We follow the parameter usage of Irwin and Hilton [3]:

- $T_b = 50 \text{ mK}$; $T_c = 90 \text{ mK}$ (cryogenic-bath and TES-critical temperatures)
- C = 0.80 pJ/K (TES heat capacity)
- -n = 3 (thermal-conductivity index; unitless)
- $\alpha_I = 75$ (TES transition steepness; unitless)
- $R_0 = 1.0 \text{ m}\Omega$ (TES quiescent resistance)
- $T_{\rm sh} = 70$ mK (temperature of TES shunt resistor)
- $-\beta_I = 1.25$ at G = 200 pW/K, and $\beta_I \propto G^{1/3}$

We allow the following TES-bias-circuit parameters to vary within practical ranges:

- G in the range 150 pW/K to 500 pW/K (thermal conductance to bath)
- $R_{\rm sh}$ in the range 50 $\mu\Omega$ to 1050 $\mu\Omega$ (TES shunt resistance)

and then derive others from them so as to have a self-consistent model:

- $-k = G/(nT_c^{n-1})$ (thermal-conductivity coefficient)
- $P_{J_0} = k(T_c^n T_b^n)$ (TES quiescent bias power, pW)
- $I_0 = \sqrt{P_{J_0}/R_0}$ (TES quiescent current, μA)
- L_{crit} (calculated inductance for critical damping [3], nH)



Fig. 1 (a) Energy resolution of the modeled detector, without readout degradation, as a function of G and $R_{\rm sh}$. Resolution degrades with higher $R_{\rm sh}$ due to the increased contribution of the shunt's Johnson noise. The dependence of β_I on G causes the dependence of resolution on G. For all choices of $R_{\rm sh}$ and G, this detector model provides significant margin in energy resolution below the limit of 2.7 eV. (b) The critically damped time-constant as a function of G and $R_{\rm sh}$. (c) The maximum allowed record length to avoid too much pileup, determined by $\tau_{\rm crit}$ and the count-rate specification, as a function of G and $R_{\rm sh}$

The TES model above predicts [3, 4] energy resolution, based on linear response and Gaussian, stationary noise sources:

$$\frac{\Delta E_{\rm FWHM}(G, R_{\rm sh})}{\sqrt{8\ln 2}} = \left(\int_{\frac{1}{2I_{\rm rec}}}^{\infty} \frac{4|s_I(f)|^2 df}{S_{I_{\rm TFN}}(f) + S_{I_{\rm TES}}(f) + S_{I_{\rm sh}}(f) + S_{I_{\rm MUX}}(f)}\right)^{-2}.$$
(1)

Here, $s_I(f)$ is the power-to-current responsivity of the TES (and is also the Fourier transform of a current pulse divided by its photon energy). The various S_I terms are, referred to the TES current: the thermal-fluctuation (phonon), TES-Johnson, shunt-resistor Johnson, and multiplexed amplifier (SQUID) noise spectra, and have units of A²/Hz. Figure 1(a) shows the nondegraded ($S_{I_{MUX}} = 0$ and $t_{rec} \rightarrow \infty$) energy resolution in our linear-detector model as a function of R_{sh} for five values of G chosen to span the selected range.

Figure 1(b) shows τ_{crit} as a function of R_{sh} and G. Changes in G mainly affect the TES's natural time-constant ($\tau_{nat} = C/G$), while changes in R_{sh} mainly affect electrothermal feedback (ETF).

3 Count Rate, Record Length, and Effective Bandwidth

In the standard Fourier-domain optimal filtering algorithm for microcalorimeter pulses [5], the time stream of data representing the detector current is digitized into records of fixed length, $t_{\rm rec}$. An output record is allowed to contain only one current pulse. Via Poisson statistics, the Athena count-rate specification is thus: $r = n \exp[-n(t_{\rm rec} + t_{\rm RTB})] \ge 40$ Hz, where n = 50 Hz. The next event cannot come within $t_{\rm rec}$ after a no-pileup trigger, and the previous event cannot have occurred within the "return-to-baseline" time, $t_{\rm RTB}$, before a no-pileup trigger. The Athena requirements yield $t_{\rm rec} + t_{\rm RTB} \le 4.46$ ms.

The choice of t_{RTB} is somewhat arbitrary. We choose $t_{\text{RTB}} = 10\tau_{\text{crit}}$, so a critically damped current-pulse will have decayed to 0.1% of its peak current before another one may arrive and be considered a no-pileup event. This yields $t_{\text{rec}} \le 4.46 \text{ ms} - 10\tau_{\text{crit}}$ to achieve the Athena count-rate specification; Fig. 1(c) shows the maximum allowed t_{rec} vs. *G* and R_{sh} .

Our recent study [4] discussed how $t_{\rm rec}$ affected $\Delta E_{\rm FWHM}$ via the loss of the f = 0 bin in optimal filtering. We showed that $\tau_{\rm crit}$ was a poor predictor of the $t_{\rm rec}$ required to achieve a given $\Delta E_{\rm FWHM}$; instead, it was the effective bandwidth of the detector's signal-to-noise-ratio density that was important. The effect of finite $t_{\rm rec}$ is included via the lower limit of integration in (1), $f = 1/(2t_{\rm rec})$. If $t_{\rm rec}$ is too short, $\Delta E_{\rm FWHM}$ can be substantially degraded.

4 SQUID Noise and Slew Rate: Dynamic-Slew Density

In either TDM or code-division-multiplexed (CDM) readout, the multiplexed SQUID noise is white. We find $S_{I_{MUX}}$ such that $\Delta E_{FWHM} = 2.7$ eV, as determined by (1). This highest-allowed TES-referred SQUID noise is plotted in Fig. 2(a) vs. *G* and R_{sh} .

Figure 2(b) shows the maximum TES-current slew-rate, I_{SRmax} (which occurs just after the photon arrival), for a 6 keV X-ray. The ratio, which we term the "dynamicslew density," of this maximum slew rate to the maximum tolerable multiplexed SQUID noise is the key metric of how big a burden the Athena specifications place on a CDM or TDM system for each detector model (see Fig. 2(c)). The lowest-*G* models, G = 150 pW/K (at its optimal $R_{\text{sh}} = 175 \mu\Omega$) and G = 200 pW/K (at $R_{\text{sh}} = 400 \mu\Omega$), are easiest to multiplex.



Fig. 2 (a) The maximum TES-referred SQUID noise that will allow $\Delta E_{\rm FWHM} = 2.7$ eV, as a function of *G* and $R_{\rm sh}$. The degradation of $\Delta E_{\rm FWHM}$ due to finite $t_{\rm rec}$ is included. (b) The maximum current-slew rate due to a 6 keV X-ray, as a function of *G* and $R_{\rm sh}$. (c) The "dynamic-slew density" ((b) divided by (a)) required by the detector to achieve Athena's specifications for 6 keV X-rays, as a function of *G* and $R_{\rm sh}$. The y-units are physically not meaningful, but do allow relative comparisons among models. The '×' shows the value of $R_{\rm sh}$ that minimizes this ratio for each value of *G*, and thus that places the lowest burden on the multiplexed readout. When multiplied by the multiplexing frame time (defined by the row-dwell time and the number of multiplexed rows, or $t_{\rm fr} = t_{\rm row}N_{\rm rows}$) the dynamic-slew density is the "dynamic-range density" (units of $\sqrt{\rm Hz}$) used [6] in discussion of frequency-domain multiplexing techniques

While the five models differ in *G*, and thus in τ_{nat} , by more than a factor of three, their optimal values of τ_{crit} range only from 200 µs to 235 µs. In addition to being easiest to multiplex in general, the higher-ETF models (low-*G*, low-*R*_{sh}) have two further advantages: (1) they suffer less thermal crosstalk; and (2) more of their multiplexing degradation is due to finite t_{rec} , so when Athena's count rates were low during observations of dim sources, t_{rec} could be extended to improve ΔE_{FWHM} substantially.

5 Time-Division and Code-Division Specifications

Because SQUIDs have periodic response to input flux, SQUID multiplexers (both TDM and CDM) are run as digitally interleaved flux-locked loops, in which a feedback signal is applied once per frame to each first-stage SQUID in order to keep the SQUID output-current linear with input flux. A NIST first-stage SQUID will remain roughly linear as long as a given row's TES current causes no flux change of more than Φ_0/π between samples of that row. Each row is sampled once per frame. Thus:

$$\Delta \Phi_{\rm max} = I_{\rm SRmax} M_{\rm in} N_{\rm rows} t_{\rm row} \le \Phi_0 / \pi, \tag{2}$$

where M_{in1} is the first-stage-SQUID input mutual-inductance. This relation holds explicitly for TDM. It holds approximately for CDM, away from the limit of very high count rates, and could be modified by replacing π with a larger number to allow pileup of the leading edges of pulses among different detectors in a CDM column.

In TDM, the relation between the maximum allowed TES-current-referred multiplexed SQUID noise (see Fig. 2(a)) and the nonmultiplexed SQUID noise (S_{Φ} , referred to the first-stage SQUID) is, including the TDM aliasing factor [7]:

$$M_{\rm in}\sqrt{S_{I_{\rm MUX}}} \ge \sqrt{\pi N_{\rm rows} S_{\Phi}}.$$
(3)

We factor out M_{in} to combine (2) and (3) and find a restriction on the product of the row time and nonmultiplexed SQUID noise in a TDM system:

$$t_{\rm row} \sqrt{S_{\Phi}} \le \frac{\Phi_0}{I_{\rm SRmax}} \sqrt{\frac{S_{I_{\rm MUX}}}{\pi^3 N_{\rm rows}^3}}.$$
 (4)

Figure 3(a) illustrates this requirement for TDM with $N_{\text{rows}} = 16$ for the value of R_{sh} at each *G* that minimizes the dynamic-slew density. The region under each curve is the allowed parameter space: faster SQUID switching and lower SQUID noise make multiplexing easier.

For CDM, which has no $\sqrt{N_{\text{rows}}}$ aliasing degradation, the equivalent to (3) is [8]:

$$M_{\rm in}\sqrt{S_{I_{\rm MUX}}} \ge \sqrt{\pi \, S_{\Phi}}\,.\tag{5}$$

The CDM equivalent to (4), plotted in Fig. 3, is:

$$t_{\rm row} \sqrt{S_{\Phi}} \le \frac{\Phi_0}{I_{\rm SRmax}} \sqrt{\frac{S_{I_{\rm MUX}}}{\pi^3 N_{\rm rows}}}.$$
 (6)

Recently, NIST has improved its TDM architecture and has developed a CDM architecture that is almost as mature [9]. In each, the non-multiplexed SQUID noise,



Fig. 3 Allowed combinations of SQUID noise and row time for the five modeled G (pW/K) values and their corresponding optimal values of $R_{\rm sh}$ ($\mu\Omega$) for 16-row (a) TDM and (b) CDM. The region under each curve satisfies Athena's dual count-rate and energy-resolution requirements. '×' in each plot marks the present state of the art for NIST multiplexers: 400 ns row-settle times and $\sqrt{S_{\Phi}} = 0.42 \ \mu \Phi_0 / \sqrt{Hz}$. This condition provides engineering margin in SQUID noise of greater than 3 for TDM and more than 50 in CDM. 'O' marks our goal of 160 ns row times and $\sqrt{S_{\Phi}} = 0.35 \ \mu \Phi_0 / \sqrt{Hz}$



Fig. 4 (Color online) Energy spectra from eight NIST TESs read out through a single TDM column, with $\langle \Delta E_{\rm FWHM} \rangle = 2.70$ eV. Detector time-constants ranged from 800 µs to 1600 µs because a range of inductance values was used. The analog row-settling time was 400 ns; the data link allowed $t_{\rm row}$ no faster than 640 ns, so the detectors were sampled for 240 ns of each row period

referred to the first-stage, is $\sqrt{S_{\Phi}} = 0.42 \ \mu \Phi_0 / \sqrt{\text{Hz}}$, and the open-loop bandwidth allows a row-settling period of 400 ns. In the 2008 NIST/NASA TDM demonstration [1], these values were $\sqrt{S_{\Phi}} = 0.61 \ \mu \Phi_0 / \sqrt{\text{Hz}}$ and 600 ns. The new parameters meet the Athena-XMS multiplexing requirements with appropriate engineering margin (Fig. 3). Figure 4 shows data from the improved TDM system. NIST TESs with much slower time constants than those of the proposed NASA Athena pixels were used because the Athena pixels were not yet available.

Present NIST SQUID-multiplexers, combined with NASA TES microcalorimeters, can instrument ESA's proposed Athena XMS package with significant engineering margin, as long as the detector bias circuit is optimized with a low-G, low- $R_{\rm sh}$ design. For 16 rows, TDM has more than a factor of three in noise margin, and CDM has so much margin that, were CDM deemed mature enough to be selected, Athena's mission specifications would likely be modified to take advantage.

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