# **The NIST Road Network Database: Version 1.0**

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#### Abstract:

For an autonomous vehicle to be able to navigate a road network, it must be aware of and must respond appropriately to any object it encounters. This includes other vehicles, pedestrians, debris, construction, accidents, emergency vehicles, ... and it also includes the roadway itself. The road network must be described in such a way that an autonomous vehicle knows, with sufficient precision and accuracy, where the road lies, rules dictating the traversal of intersections, lane markings, road barriers, road surface characteristics, and other relevant information.

The purpose of this document is to provide detailed information about the Road Network Database being developed at the National Institute of Standards and Technology (NIST) as part of the DARPA Mobile Autonomous Robotics Systems (MARS) Program. The purpose of the Road Network Database is to provide the data structures necessary to capture all of the information necessary about road networks so that a planner or control system on an autonomous vehicle can plan routes along the roadway at any level of abstraction.

1.	Introduction		3
2.	Overview of th	e Database Structure	3
3.	How a Planner	is Expected to Use The Data Structure	5
4.	Detailed Data	Structure Description	6
	4.1. Roadways	5	7
	4.1.1.	Road	7
	4.1.2.	Road Segment	9
	4.1.3.	Road Element	11
	4.1.4.	Lane Cluster	13
	4.1.5.	Lane	17
	4.1.6.	Lane Segment	20
	4.1.7.	Generic Lane Segment	22
	4.2. Lookup T	ables	26
	4.2.1.	Lane Accessibility Lookup	26
	4.2.2.	Lane Barrier Lookup	27
	4.2.3.	Lane Markings Lookup	28
	4.2.4.	Lane Type Lookup	29
	4.2.5.	Road Segment Class Lookup	30
	4.2.6.	Road Surface Lookup	31
	4.2.7.	Special Road Feature Lookup	32
	4.3. Time Var	ying Attributes	33
	4.3.1.	Generic Lane Segment Time Varying Attributes	33
	4.3.2.	Lane Time Varying Attributes	34
	4.3.3.	Lane Junction Traversibility Time Varying Attributes	35
	4.3.4.	Intersection Traversibility Time Varying Attributes	36
	4.4. Junctions		37
	4.4.1.	Junction	37
	4.4.2.	Intersections	38
	4.4.3.	Intersection Traversibility	40
	4.4.4.	Lane Junction	42
	4.4.5.	Junction Lane Segments (JLS).	43
	4.4.6.	Lane Junction Traversibility	48
	4.5. Administr	ative Tables	50
	4.5.1.	World	50
	4.5.2.	Version Control	51
5.	Conclusion		52

# 1. Introduction

For an autonomous vehicle to be able to navigate a road network, it must be aware of and must respond appropriately to any object it encounters. This includes other vehicles, pedestrians, debris, construction, accidents, emergency vehicles, ... and it also includes the roadway itself. The road network must be described in such a way that an autonomous vehicle knows, with great precision and accuracy, where the road lies, rules dictating the traversal of intersections, lane markings, road barriers, road surface characteristics, and other relevant information.

The purpose of this document is to provide detailed information about the Road Network Database being developed at the National Institute of Standards and Technology (NIST) as part of the Defense Advanced Research Projects Agency (DARPA) Mobile Autonomous Robotics Systems (MARS) Program. The purpose of the Road Network Database is to provide the data structures necessary to capture all of the information necessary about road networks so that a planner or control system on an autonomous vehicle can plan routes along the roadway at any level of abstraction. At one extreme, the database should provide structures to represent information so that a low-level planner can develop detailed trajectories to navigate a vehicle over the span of a few meters. At the other extreme, the database should provide structures to represent information so that a high-level planner can plan a course across a country. Each level of planning requires data at different levels of abstraction, and as such, the Road Network Database must accommodate these requirements.

# 2. Overview of the Database Structure

In this section, we provide a brief look at the overall structure of the Road Network Database. More details about all of the components of the structure is included throughout the remainder of the document.

The fundamental components of the Road Network Database are described below:

- Junctions A junction is a generic term referring to two or more paths of transportation that
  come together or diverge, or a controlled point in a roadway. Paths of transportation could be
  roadway or not roadway paths. Examples of roadway paths that could cause a junction are lanes
  splits, forks in the road, merges, and intersections. Example of junctions caused by roadway and
  non-roadway paths are pedestrian crossings, ferry crossings, railroad crossings. Examples of
  controlled points in the roadway are drawbridges, toll plazas, and guard gates. Junctions are an
  abstract supertype in the sense that a junction must be one of the types listed above. As of the
  time this document was published, only the intersection junction-type was included in the
  database. Other junction types will follow shortly.
- Intersections Intersections are a type of junction in which two or more separate roads come together.
- Lane Junctions A lane junction is a location in a junction in which two or more lanes of traffic overlap. A lane merge contains a lane junction starting at the point in which the two lanes begin to come together and end at the point in which the two lanes are completely together as one. A lane fork contains a lane junction at the point where the lanes begin to fork and ends at the point where the two lanes are completely separated. An intersection contains a lane junction at all points in which the lanes from the two or more intersecting roads overlap.
- **Road** A road is a stretch of travel lanes in which the name of the travel lanes does not change. An example is "Main Street" or "Route 95."
- **Road Segment** A road segment is a uni-directional stretch of roadway bounded by intersections. A road segment is roughly analogous to a "block". So the uni-directional piece of road bounded by 1<sup>st</sup> Street and 2<sup>nd</sup> Street would be a road segment.
- **Road Element** A road element is a uni-directional stretch of roadway bounded by any type of junction. Unlike road segments, road elements can be bounded by merging lanes, forks in the

road, Junctions include two or more lanes merging together, a fork in the road, a pedestrian crossing, a toll booth, a draw bridge, an intersection, etc.

- Lane Cluster A lane cluster is a set of uni-directional lanes (with respect to flow of traffic) in which no physical attribute of those lanes change over the span of the lane segment. Unlike a road element, lane clusters are not required to be bounded by junctions. Characteristics of the road that cannot change include the addition or subtraction of shoulders, the width of the lane, the separation of lanes to form a median, change in paint striping, and change in lane barriers.
- Lane A lane is a single pathway of travel that is bounded by explicit or implicit lane marking. Lanes span the length of a lane cluster in which they are a part of.
- Lane Segment A lane segment is the most elemental portion of a road network captured by the database structure. Lane segments can be either straight line or constant curvature arcs. In the case of a straight line, the location of the lane segment if fully defined by the beginning and end point of the lane segment. For a constant curvature arc, the lane segment is defined by the beginning and end of the lane segment and the curvature center point. One or more lane segments compose a lane
- Junction Lane Segments A junction lane segment is a constant curvature path through a portion of a lane junction. Apart from some subtle differences pertaining to connectivity of these junction lane segments, they are extremely similar to lane segments as described above.
- **Time Varying Attribute Tables** There are a number of tables in the database that address attributes of the above structures that may vary as a function of time. These attributes include speed limits on roadways, the average speed on a roadway, the direction of travel on lanes, the accessibility of a lane (e.g., HOV), and the legal traversibility through intersection (e.g., no right turn between 3pm and 6pm on weekdays). In these tables, the pertinent values for these attributes are associated with time intervals.
- Lookup Tables There are a number of lookup tables that include a complete list of all possible values that certain attributes in the certain data structures may have. Lookup tables are used when possible values for a given attribute are finite, and there is value in enumerating them in a table. There are currently seven lookup tables in the database: 1) accessibility restrictions on lanes (e.g., HOV-2, HOV-3, cabs only, police only), 2) possible lane barriers on the side of lanes (e.g., jersey barrier, curb, guard rail), 3) lane markings on the side of lanes (e.g., solid yellow line, double solid yellow line, dashed white line, solid white line), 4) lane types (e.g., traversable, shoulder), 5) road class (e.g., interstate highway, beltway, country road, residential, road), 6) road surface (e.g., asphalt, dirt, pebbles), and 7) special road features (e.g., bridge, tunnel).

It is assumed in this database that sub-components of a road structure are rendered in the same direction as the super-structure, namely:

- Road segments within a road are rendered in the same direction as the road.
- Road elements within a road segment are rendered in the same direction as the road segment.
- Lane clusters within a road element are rendered in the same direction as the road element.
- Lanes within a lane cluster are rendered in the same direction as the lane cluster.
- Lane segments within a lane are rendered in the same direction as the lane.

Note that the way that the road structures are rendered does not dictate the direction of travel of vehicles on that road structure. It only dictates how the structure was rendered internally.

# 3. How a Planner is Expected to Use The Data Structure

As stated earlier, this data structure is designed to accommodate a control system that may contain planners with various levels of abstraction. This section will provide insight into data structures that will be most appropriate for planners at different levels. The planners, their descriptions, and the data structures which best correspond to their level of responsibility are shown in Table 1.

Planner Name	Planner Description	Appropriate Data Structures
Destination Planner	Plans the sequence of route	Roads
	segments to get to commanded	Road Segments
	destination goal.	Intersections
	Outputs MapQuest <sup>1</sup> -like	Forks (not yet defined)
	directions	Merges (not yet defined)
	Plans on the order of 1 to 2 hrs	
	into the future	
	Plans $> 10$ km distances	
Route Segment Planner	Decides on real-time goal lanes	Road Segments
	for road segments and for	Road Elements
	negotiating intersections.	Intersections
	Deals with intersections, forks,	Forks (not yet defined)
	merges, etc.	Merges (not yet defined)
	Plans on the order of 10 mins into	
	the future	
	Plans up to 10 km distances	
Drive Behavior Planner	Develops low-level behaviors for	Lane Clusters
	negotiating intersections and	Lanes
	deciding when to change lanes.	Intersection
	Plans on the order of 100 secs	Forks (not yet defined)
	into the future.	Merges (not yet defined)
	Plans up to 500 m distances	
Elemental Maneuver Planner	Carries out real-time maneuvers	Lanes
	to slow down, stop, speed up, and	Lane Segments
	change lateral position.	
	Plans on the order of 10 secs into	
	the future	
	Plans up to 50 m distances	
Goal Path Trajectory Generator	Calculates the lane segment path	Lane Segments
	dynamic trajectory as a goal path	
	to carry out commanded move	
	while controlling for skid and	
	immediate obstacle response.	
	Plans on the order of 1 s into the	
	future	
	Plans up to 5 m distances	

Table 1: Planner to Data Structure Mapping

<sup>&</sup>lt;sup>1</sup> The name of commercial products or vendors does not imply NIST endorsement or that this product is necessarily the best for the purpose.

# 4. Detailed Data Structure Description

Throughout this description, we will use variations of Figure 1 to indicate the part of the road network that is being referenced by the corresponding data structure. In all cases, the shaded region in the figure indicates the extent of the data structure. When implementing the database, a value of -1 should indicate that that field contains a null value.



Figure 1: Sample Road Network

## 4.1. Roadways

## 4.1.1. Road



Figure 2: Road

A road is the most general structure in the road network database. Roads are composed of road segments and intersections. A road is primarily identified by its name. A road may also point to a parent road. For example, a given route number (say route 100) may be called Main Street in one area, First street in another area, and Broad street in another area. Each of these street names would be an instance in the road table, and would have a point to the road instance of "Route 100" as their parent road.

Attribute Data Type		Value	Points To	Is Pointed To From	Description	Required
		Restrictions				Value?
ID	Integer	Any whole		Road.Parent_Road,	A unique identifier for	Yes
		number		Road_Segment.Road_ID	this entry in this table	
		greater or				
		equal to one				
World_ID	Integer		World.ID		This value indicates which world this entry is associated with. A road may only be associated with a single world. See 4.5.1. for information about worlds	Yes
Name	Text				The name by which the road is referred to.	Yes
Description	Text				A textual description of this field for human understanding	No
Parent_Road	Integer		Road.ID		The more general road that a road is a part of.	
Start_X	Double				The X_coordinate (which is the north component of the	Yes

		(Universal Transverse Mercator (UTM) coordinate) of the geometric center of the start of the road (which	
		if it exists).	
Start_Y	Double	The Y_coordinate (which is the east component of the UTM coordinate) of the geometric center of the start of the road (which could lie in the median, if it exists).	Yes
End_X	Double	The X_coordinate (which is the north component of the UTM coordinate) of the geometric center of the end of the road (which could lie in the median, if it exists).	Yes
End_Y	Double	The Y_coordinate (which is the east component of the UTM coordinate) of the geometric center of the end of the road (which could lie in the median, if it exists).	Yes

Table 2: Road Attributes

#### 4.1.2. Road Segment



Figure 3: Road Segment

A road segment is a uni-directional stretch of roadway bounded by intersections. A road segment is composed of one or more road elements and zero or more junctions. There are one or more road segments in a road. Unlike road elements, road segments are only bounded by intersection, not any type of junction. A road segment within a road must always be rendered in the same direction as the road. Road segments are used in the planning and control system to provide MapQuest-like directions to the vehicle to allow for route planning.

Attribute	Data	Value	Points To	Is Pointed To From	Description	Required
	Туре	Restrictions				Value?
ID	Integer	Any whole number greater or equal to one		RoadElement. RoadSegment_ID, Junction.RoadSegment_ID IntersectionTraversibility.I ncomingRoadSegment_ID, IntersectionTraversibility. OutgoingRoadSegment_ID	A unique identifier for this entry in this table	Yes
World_ID	Integer		World.ID		A pointer to an element in the World table that indicates which world this entry is associated with. A road segment may only be associated with a single world. See 4.5.1. for information about worlds.	Yes
Description	Text				A textual description of this field for human understanding	No
Road_ID	Integer		Road.ID		A pointer to the element in the Road table in which the road segment is a part of.	Yes
Start_Point_A djacent_Inters ection_ID	Integer		Intersection.ID		A pointer to the element in the Intersection table which precedes the road segment.	Yes
End_Point_Ad	integer	1	intersection.ID		A pointer to the	i es

jacent_Intersec tion ID			element in the Intersection ta	ble
· · · _			which follows	the road
			segment.	
Segment_Leng	Double		Measured in 1	neters. Yes
th			The length of	the road
			segment meas	ured
			from center p	pint to
			center point.	This
			should be der	ved from
			the length of t	he road
			elements which	:h
			compose it.	
Road_Segmen	Integer	RoadSegmentC	A pointer to a	n Yes
t_Class		lass.ID	element in the	;
			RoadSegment	ClassLo
			okup table wh	lich
			contains the c	lass of
			road segment	which
			applies to this	road
			segment.	

Table 3: Road Segment Attributes

#### 4.1.3. Road Element



**Figure 4: Road Element** 

A road element is a uni-directional stretch of roadway which is bounded by any type of junction, and in which the sides of the lane clusters in that road element coincide with one another. Junctions include two or more lanes merging together, a fork in the road, a pedestrian crossing, a toll booth, an intersection, a draw bridge, etc. The stretch of uni-directional roadway between any two of these junctions constitute a road element. One or more lane clusters compose a road element. One or more road element within a road segment must always be rendered in the same direction as the road segment.

Attribute	Data	Value	Points To	Is Pointed To	Description	Required
	Туре	Restrictions		From		Value?
ID	Integer	Any whole number greater or		LaneCluster.Road _Element_ID	A unique identifier for this entry in this table	Yes
World_ID	Integer	equario one	World.ID		A pointer to an element in the World table that indicates which world this entry is associated with. A road element may only be associated with a single world. See 4.5.1. for information about worlds.	Yes
Description	Text				A textual description of this field for human understanding	No
RoadSegment_ID	Integer		RoadSegment. ID		A pointer to the element in the RoadSegment table in which the road element is a part of.	Yes
Start_Point_Adja cent_Junction	Integer		Junction.ID		A pointer to the element in the Junction table which precedes the road element.	Yes
End_Point_Adjac ent_Junction	Integer		Junction.ID		A pointer to the element in the Junction table which follows the road element.	Yes
Element_Length	Douoble				Measured in meters. The	Yes

				length of the road element measured from center point to center point. This should be derived from the length of the lane clusters which compose it.	
Lane_Direction	Integer	0 indicating forward direction, 1 indicating backward direction, with respect to how it was rendered		Shows the direction of travel of the lane segment	No

Table 4: Road Element Attributes

#### 4.1.4. Lane Cluster



Figure 5: Lane Cluster

A lane cluster is a set of uni-directional lanes (with respect to flow of traffic) in which the sides of the lanes in the lane cluster coincide with one another, and in which no physical attribute of those lanes changes over the span of the lane segment. Characteristics of the road that cannot change include the addition or subtraction of shoulders, the width of the lane, the separation of lanes to form a median, change in paint striping, and change in lane barriers. Lane cluster can only have one or zero lane clusters to the left and one or zero to the right. Lane clusters can be arbitrarily broken to ensure the zero or one restrictions on adjacency. Lane cluster adjacency is only important when one can traverse from one lane cluster to another. If barriers exist that prohibit traversal, adjacency restriction need not be applied. A lane cluster within a road element must always be rendered in the same direction as the road element.

In the case of a lane in a road that changes directions during different times of the day, it is a lane cluster in itself and does not become a part of the adjacent lane cluster that is going the same direction at that time of day. Situations such as one-lane bridges can be handled by specifying the direction of the lane cluster as a time varying attribute and having two entries in the time-varying attribute table indicating that the direction of the road is each direction all day, every day. In the case where a flag person is present, their gestures would override any information in this database.

Lane clusters can either be part of a road element or a junction. A road element is made up of one or more lane clusters. A junction can contain zero or more lane clusters. A lane cluster can have zero or one lane clusters and/or zero or more lane junctions either before it, after it, to the right of it, or to the left of it.

Attribute	Data	Value	Points To	Is Pointed To From	Description	Required
	Туре	Restrictions				value?
ID	Integer	Any whole		LaneCluster.	A unique identifier	Yes
		number		Start_Link_LaneCluster_ID,	for this entry in this	
		greater or		LaneCluster.	table	
		equal to one		End Link LaneCluster ID,		
		-		LaneCluster.		
				Right_Lane_Cluster_ID,		
				LaneCluster.		
				Left_Lane_Cluster_ID,		
				Lane.LaneCluster_ID		
World ID	Integer		World.ID		A pointer to an	Yes
_	-				element in the World	

				table that indicates	
				which world this	
				entry is associated	
				with A lane cluster	
				may only be	
				agge gisted with a	
				associated with a	
				single world. See	
				4.5.1. for information	
				about worlds.	
Description	Text			A textual description	No
···· 1 · ·				of this field for	
				human understanding	
D 1 E1 (	T. (			numan understanding	N
Road_Element	Integer	RoadElement.I		A pointer to the	NO
_ID		D		element in the	
				RoadElement table	
				which the lane cluster	
				is a part of. If this is	
				blank, the lane cluster	
				is part of a Junction	
				and the attribute	
				below should be	
				populated.	
Junction_ID	Integer	Junction.ID		A pointer to the	No
				element in the	
				Junction table which	
				the lane cluster is a	
				part of If this is	
				blank, the lane cluster	
				is part of a Road	
				Segment and the	
				attribute above	
				should be populated	
Start Link La	Integer	LanaCluster ID		A pointer to an	No
Start_Link_La	Integer	Lanceluster.ID		A pointer to an	INU
necluster_ID				element in the	
				LaneCluster table	
				which contains the	
				lane cluster which	
				directly precedes this	
				lane cluster. If this is	
				blank the lane cluster	
				is preseded by a	
				is preceded by a	
				junction.	
End_Link_Lan	Integer	LaneCluster.ID		A pointer to an	No
eCluster_ID				element in the	
_				LaneCluster table	
				which contains the	
				lane cluster which	
				directly follows this	
				land alwater 10.1	
				iane cluster. If this is	
				blank, the lane cluster	
				is followed by a	
				junction.	
Special Road	Integer	RoadFeatureLo		A pointer to an	Yes
Feature		okun ID		element in the	
		okup.its		RoadFeatureLookun	
				table solute DOKup	
				table which indicates	
				any special road	
				features that are	
				associated with this	
				lane cluster.	
Right Lane C	Integer	LaneCluster ID		A pointer to an	No
luster ID		Eurociuster.iD		element in the	
""""""""""""""""""""""""""""""""""""""				LonoChuster tal-1-	
				LaneCluster table	
				that is directly to the	
				right of this lane	
				cluster. The database	
				is defined such that	
				there can be only 0 or	
				1 lane clusters to the	
1		1 1		i fance crusters to the	

				right of any lane	
				cluster.	
Left Lane Cl	Integer	LaneCluster ID		A pointer to an	No
uster ID	integer	Dancerusterind		alement in the	110
usici_iD				LangCluster table	
				that is directly to the	
				left of this lane	
				cluster. The database	
				is defined such that	
				there can be only 0 or	
				1 lane clusters to the	
				left of any lane	
				cluster	
L . A L L	T	I an a lass ation I			N.
Left_LaneJunc	Integer	Lanejunction.1		A pointer to an	INO
tion		D		element in the	
				LaneJunction table	
				which is directly to	
				the left of this lane	
				cluster. Lane	
				junctions can only be	
				to the left of lane	
				alustor in junction	
				cluster in junction,	
				and there can be	
				either 0 or 1 lane	
				junction to the left of	
				the lane cluster.	
Right LaneIu	Integer	LaneJunction I		A pointer to an	No
nction	integer	D		element in the	110
netion		D			
				Lanejunction table	
				which is directly to	
				the right of this lane	
				cluster. Lane	
				junctions can only be	
				to the right of lane	
				cluster in junction	
				and there can be	
				and there can be	
				either 0 or 1 lane	
				junction to the right	
				of the lane cluster.	
Start LaneJun	Integer	LaneJunction.I		A pointer to an	No
ction	_	D		element in the	
				Lane Junction table	
				which directly	
				which directly	
				precedes this lane	
				cluster. This attribute	
				can only be	
				populated when the	
				lane cluster is part of	
				a junction (not a road	
				segment)	
End Lanaluna	Integer	Langlunction I		A pointer to an	No
tion	meger			alamant in the	110
uon	1	U		ciement in the	
	1			LaneJunction table	
				which directly	
				follows this lane	
				cluster. This attribute	
				can only be	
				nonulated when the	
	1			long aluster is most of	
				iane cluster is part of	
				a junction (not a road	
				segment).	
Length	Double			Measured in meters.	Yes
-				This is the length of	
				the lane cluster	
				measured from	
				centernoint to	
				conterpoint to	
				centerpoint. This	
				value should be	
				derived from the	
				length of the lanes	

					which o	compose it.	
Number_of_L anes	Integer	>=1			Indicate of lanes cluster. derived the num entries	es the number s in the lane . This is l by looking at nber of lane in the lane	Yes
					table the lane clu	nat point to this uster.	
Width	Double	>= 0			The wi entire r prepare the land	dth of the man-made ed surface of e cluster.	

Table 5: Lane Cluster Attributes

#### 4.1.5. Lane



Figure 6: Lane

A lane is a single pathway of travel that is bounded by explicit or implicit lane marking. Lanes are composed of lane segments and span the entire length of a lane cluster which it is a part of. Lanes have a direction of travel, which indicates the direction that traffic flows. A shoulder is also considered a lane, but the lane would be indicated as being a shoulder through its lanetype\_id attribute. A lane within a lane cluster must always be rendered in the same direction as the lane. Lanes are primarily used within the control system and planning algorithms to provide information about the legal paths along the road network, and allow the vehicle to position itself properly to make turns.

Attribute	Data Type	Value Restrictions	Points To	Is Pointed To From	Description	Required Value?
ID	Integer	Any whole number greater or equal to one		Lane.Start_Link_Lane_ID, Lane.End_Link_Lane_ID, Lane.Right_Link_Lane_ID Lane.Left_Link_Lane_ID, LaneSegment.Lane_ID, LaneTimeVaryingAttribute .Lane_ID	A unique identifier for this entry in this table	Yes
World_ID	Integer		World.ID		A pointer to an element in the World table that indicates which world this entry is associated with. A lane may only be associated with a single world. See 4.5.1. for information about worlds.	Yes
Description	Text				A textual description of this field for human understanding	No
LaneCluster_ ID	Integer	>0	LaneCluster.ID		A pointer to an element in the LancCluster Table which this lane is a part of.	Yes
Length	Double	>0			The length of this	Y es

					lane measured in	
					meters. This should	
					be derived from the	
					length of the lane	
					segments that	
					compose it.	
Start Link L	Integer		LaneSegment.ID		A pointer to the	Yes
ane Segment	U		U		lane segment that is	
ID					the first lane	
-					segment in the lane.	
					The start of the lane	
					is determined by the	
					way it was	
					rendered.	
End Link L	Integer		LaneSegment.ID		A pointer to the	Yes
ane Segment	-		-		lane segment that is	
ID					the last lane	
-					segment in the lane.	
					The end of the lane	
					is determined by the	
					way it is rendered.	
Width	Double	Greater than			The average width	Yes
		zero.			of the lane,	
					measured in meters.	
Road Surface	Integer		RoadSurface.ID		A pointer to an	Yes
ID					entry in the	
					RoadSurface table	
					that indicates the	
					type of surface on	
					the roadway.	
Start Link L	Integer		Lane.ID		A pointer to the	No
ane ID –	U				lane that directly	
··· · -					precedes this lane.	
					If this field is blank,	
					an intersection	
					directly precedes	
					this lane.	
End_Link_L	Integer		Lane.ID		A pointer to the	No
ane ID	_				lane that directly	
_					follows this lane. If	
					this field is blank,	
					an intersection	
					directly precedes	
					this lane.	
Right_Lane_	Integer		Lane.ID		A pointer to the	No
ID					lane that is directly	
					to the right of this	
					lane. The database	
					is defined such that	
					there can be only 0	
					or 1 lanes to the	
					right of any lane.	
Left_Lane_I	Integer		Lane.ID		A pointer to the	No
D					lane that is directly	
					to the left of this	
					lane. The database	
					is defined such that	
					there can be only 0	
					or 1 lanes to the	
					right of any lane.	
LaneType_I	Integer		LaneTypeLooku		A pointer to an	Yes
D			p.ID		entry in the	
					LaneTypeLookup	
			OR		table which	
					indicates what type	
			LaneTimeVaryin		of lane it is. If -2,	
			gAttribute.ID		you must look at the	
					LaneTimeVaryingA	
				<u> </u>	ttribute table using	

					the ID of the Lane	
					and "Lane_Type"	
					for the	
					Attribute_Type	
Accessibility	Integer		LaneAccessibilit		A pointer to an	Yes
5	U		vLookup.ID		entry in the	
			JEconup.ii		Lane AccessibilityI	
			OP		a alum tabla which	
			UK		ookup table willen	
					indicates what the	
			LaneTimeVaryin		accessibility of the	
			gAttribute.ID		lane is. If -2, you	
					must look at the	
					LaneTimeVaryingA	
					ttribute table using	
					the ID of the Lane	
					and "A appagibility"	
					and Accessionity	
					for the	
					Attribute_Type	
Lane_Numbe	Integer	>= 1			Shows the number	Yes
r	-				of the lane,	
					numbered from the	
					center lane marking	
					out I and numbers	
					out. Lane numbers	
					are unique only	
					within a lane	
					cluster.	
Left Lane	Integer		LaneMarkings.I		A pointer to an	ves
Marking ID	U		D		element in the lane	5
interning_12			2		markings table that	
					shows the type of	
					shows the type of	
					lane marking to the	
					left of lane, with	
					respect to how it	
					was rendered	
Right Lane	Integer		LaneMarkings.I		A pointer to an	ves
Marking ID			D		element in the lane	5-2
Marking_ID			D		markings table that	
					snows the type of	
					lane marking to the	
					right of lane, with	
					respect to how it	
					was rendered	
Left Lane B	Integer		LaneBarrier ID		A pointer to an	ves
arrier ID	meger		_uneburner.nb		element in the lane	,
"""					borriora table that	
					barriers table that	
					snows the type of	
					lane marking to the	
					left of lane, with	
					respect to how it	
					was rendered	
Right Lane	Integer		LaneBarrier ID		A pointer to an	ves
Barrier ID	integer		LuneDunier.iD		alamant in the long	,00
Barner_ID					benniem tel 1 die dane	
					parriers table that	
					shows the type of	
					lane barrier to the	
					right of lane, with	
					respect to how it	
					was rendered	
1		1	1	1	was rendered	

Table 6: Lane Attributes

#### 4.1.6. Lane Segment



Figure 7: Lane Segment

A lane segment is the most elemental portion of a road network captured by the database structure. Lane segments can be either straight line or constant curvature arcs. In the case of a straight line, the location of the lane segment is fully defined by the beginning and end point of the lane segment. For a constant curvature arc, the lane segment is defined by the beginning and end of the lane segment and the curvature center point. Lane segments can be arbitrarily cut off at intermediate points to ensure adjacency between other lane segments to the left or right. Lane segments can have zero or one lane segments that follow it, and zero or one lane segments that precede it. Lane segments can have zero or one junction lane segments that follow it and zero or junction lane segments that precede it. When no lane segments precede it, it means that the lane segment begins at a lane junction. When no lane segments follow it, it means that the lane segment next to the start of the following lane segment, if it exists. Due to this constraint on the database, there should never be a case where the start of one lane segment is next to the start of the next lane segment, or vice versa. A lane segment within a lane must always be rendered in the same direction as the lane. The lane segments are primarily used within a control system or planner to generate the detailed path that a vehicle is expected to follow.

This table only houses the attributes and values that are specific to a lane segment and are different that a junction lane segment. The common attributes between the two can be found in the generic lane segment table. The generic lane segment (in the generic lane segment table) which has the same ID as this lane segment will contain the corresponding attribute and values.

Attribute	Data	Value	Points To	Is Pointed To From	Description	Required
	Туре	Restrictions				Value?
ID	Integer	Any whole		Lane.Start_Link_Lane_Segment_ID,	A unique identifier	yes
		number		Lane.End_Link_Lane_Segment_ID,	for this entry in this	
		greater or			table	
		equal to one				
World_ID	Integer		World.ID		A pointer to an	yes
					element in the World	
					table that indicates	
					which world this	
					entry is associated	
					with. A lane segment	
					may only be	
					associated with a	
					single world. See	

				4.5.1. for information	
				about worlds.	
Right_Lin	Integer	Gene	ericLa	A pointer to the lane	no
k_Lane_G		neSe	egmen	segment to the right	
eneric_Se		t.ID		of this lane segment,	
gment				with respect to how it	
				was rendered.	
Left_Link	Integer	Gene	ericLa	A pointer to the lane	no
_Lane_Ge		neSe	egmen	segment to the left of	
neric_Seg		t.ID	-	this lane segment,	
ment				with respect to how it	
				was rendered.	
Lane_ID		Lane	e.ID	A pointer to an	yes
_				element in the lane	-
				table that indicates	
				the Lane which this	
				lane segment is part	
				of.	
Start Link	Integer	Gene	eric	A pointer to an	no
Lane Ge	-	Lane	eSeg	element in the	
neric Seg		ment	t.ID	generic lane segment	
ment				table which shows	
				which generic lane	
				segment comes	
				directly before this	
				lane segment. This	
				could either be a lane	
				segment or a junction	
				lane segment. This is	
				not populated only if	
				it is a dead end.	
End Link	Integer	Gene	eric	A pointer to an	no
Generic	e	Lane	eSeg	element in the	
Lane Seg		ment	t.ID	generic lane segment	
ment				table which shows	
				which generic lane	
				segment comes	
				directly after this lane	
				segment. This could	
				either be a lane	
				segment or a junction	
				lane segment. This is	
				not populated only if	
				it is a dead end.	

Table 7: Lane Segment Attributes

#### 4.1.7. Generic Lane Segment

The generic lane segment is an abstract supertype of lane segment and junction lane segment. All common attributes are stored within this table. Attributes that are only specific to a lane segment are stored in the lane segment table, and attributes that are specific to a junction lane segment are stored in the junction lane segment table. Mapping between the generic lane segment and the lane segment and junction lane segment are done in two ways. First, the attribute named "lane\_segment\_type" in the generic lane segment table indicates whether this generic lane segment is of type "lane segment" or "junction lane segment". Second, the ID of the generic lane segment matches the ID of either the lane segment or the junction lane segment, whichever is appropriate.

Attribute	Data	Value	Points To	Is Pointed To From	Description	Required
	Туре	Restrictions				Value?
ID	Integer	Any whole number greater or equal to one		LaneSegment. Start_Link_Lane_Segment_ID, LaneSegment. End_Link_Lane_Segment_ID, LaneSegment. Right_Link_Lane_Segment_ID, LaneSegment. Left_Link_Lane_Segment_ID, JunctionLaneSegment. Start_Link_Generic_Lane_Segment_1, JunctionLaneSegment. Start_Link_Generic_Lane_Segment_2, JunctionLaneSegment. Start_Link_Generic_Lane_Segment_3, JunctionLaneSegment. End_Link_Generic_Lane_Segment_1, JunctionLaneSegment. End_Link_Generic_Lane_Segment_2, JunctionLaneSegment. End_Link_Generic_Lane_Segment_2, JunctionLaneSegment. End_Link_Generic_Lane_Segment_2, JunctionLaneSegment. End_Link_Generic_Lane_Segment_2, JunctionLaneSegment. End_Link_Generic_Lane_Segment_3, LaneSegment_ID, LaneJunctionTraversibility. Incoming_LaneSegment_ID, LaneJunctionTraversibility.	A unique identifier for this entry in this table	Yes
World_ID	Integer		World.ID		A pointer to an element in the World table that indicates which world this entry is associated with. A generic lane segment may only be associated with a single world. See 4.5.1. for information about worlds.	Yes
Description	Text				A textual description of this field for human understanding	No
Radius	Double				The radius of the arc that is used to	No

			4.41	
			generate the	
			lane segment.	
			If the lane	
			segment is a	
			straight line	
			the radius is 0	
			the factors is 0.	
Start_Point	Double		The X	Yes
x –			coordinate of	
-11				
			the start point	
			of the lane	
			segment	
			which is the	
			north	
			component of	
			the UTM	
			coordinate.	
Start Doint	Doublo		Tho V	Vas
Start_Foint	Double			1 05
_Y			coordinate of	
			the start point	
			of the lone	
			of the falle	
			segment,	
			which is the	
			anat	
			east	
			component of	
			the UTM	
			coordinate.	
End Point	Double		The X	Yes
v			coordinate of	
Λ			coordinate of	
			the end point	
			of the lane	
			segment,	
			which is the	
			north	
			norm	
			component of	
			the UTM	
			coordinate	
			coordinate.	
End_Point_	Double		The Y	Yes
Y			coordinate of	
-				
			the and naint	
			the end point	
			the end point of the lane	
			the end point of the lane segment.	
			the end point of the lane segment, which is the	
			the end point of the lane segment, which is the	
			the end point of the lane segment, which is the east	
			the end point of the lane segment, which is the east component of	
			the end point of the lane segment, which is the east component of	
			the end point of the lane segment, which is the east component of the UTM	
			the end point of the lane segment, which is the east component of the UTM coordinate.	
Curvature	Double		the end point of the lane segment, which is the east component of the UTM coordinate. The X	No
Curvature_	Double		the end point of the lane segment, which is the east component of the UTM coordinate. The X	No
Curvature_ Center_X	Double		the end point of the lane segment, which is the east component of the UTM coordinate. The X coordinate of	No
Curvature_ Center_X	Double		the end point of the lane segment, which is the east component of the UTM coordinate. The X coordinate of the curvature	No
Curvature_ Center_X	Double		the end point of the lane segment, which is the east component of the UTM coordinate. The X coordinate of the curvature center point	No
Curvature_ Center_X	Double		the end point of the lane segment, which is the east component of the UTM coordinate. The X coordinate of the curvature center point of the lang	No
Curvature_ Center_X	Double		the end point of the lane segment, which is the east component of the UTM coordinate. The X coordinate of the curvature center point of the lane	No
Curvature_ Center_X	Double		the end point of the lane segment, which is the east component of the UTM coordinate. The X coordinate of the curvature center point of the lane segment,	No
Curvature_ Center_X	Double		the end point of the lane segment, which is the east component of the UTM coordinate. The X coordinate of the curvature center point of the lane segment, which is the	No
Curvature_ Center_X	Double		the end point of the lane segment, which is the east component of the UTM coordinate. The X coordinate of the curvature center point of the lane segment, which is the porthe	No
Curvature_ Center_X	Double		the end point of the lane segment, which is the east component of the UTM coordinate. The X coordinate of the curvature center point of the lane segment, which is the north	No
Curvature_ Center_X	Double		the end point of the lane segment, which is the east component of the UTM coordinate. The X coordinate of the curvature center point of the lane segment, which is the north component of	No
Curvature_ Center_X	Double		the end point of the lane segment, which is the east component of the UTM coordinate. The X coordinate of the curvature center point of the lane segment, which is the north component of the UTM	No
Curvature_ Center_X	Double		the end point of the lane segment, which is the east component of the UTM coordinate of the Curvature center point of the lane segment, which is the north component of the UTM	No
Curvature_ Center_X	Double		the end point of the lane segment, which is the east component of the UTM coordinate. The X coordinate of the curvature center point of the lane segment, which is the north component of the UTM coordinate.	No
Curvature_ Center_X	Double		the end point of the lane segment, which is the east component of the UTM coordinate. The X coordinate of the curvature center point of the lane segment, which is the north component of the UTM coordinate. This will not	No
Curvature_ Center_X	Double		the end point of the lane segment, which is the east component of the UTM coordinate. The X coordinate of the curvature center point of the lane segment, which is the north component of the UTM coordinate. This will not be populated	No
Curvature_ Center_X	Double		the end point of the lane segment, which is the east component of the UTM coordinate. The X coordinate of the curvature center point of the lane segment, which is the north component of the UTM coordinate. This will not be populated if the lane	No
Curvature_ Center_X	Double		the end point of the lane segment, which is the east component of the UTM coordinate. The X coordinate of the curvature center point of the lane segment, which is the north component of the UTM coordinate. This will not be populated if the lane	No
Curvature_ Center_X	Double		the end point of the lane segment, which is the east component of the UTM coordinate of the Curvature center point of the lane segment, which is the north component of the UTM coordinate. This will not be populated if the lane segment is a	No
Curvature_ Center_X	Double		the end point of the lane segment, which is the east component of the UTM coordinate. The X coordinate of the curvature center point of the lane segment, which is the north component of the UTM coordinate. This will not be populated if the lane segment is a straight line	No
Curvature_ Center_X	Double		the end point of the lane segment, which is the east component of the UTM coordinate. The X coordinate of the curvature center point of the lane segment, which is the north component of the UTM coordinate. This will not be populated if the lane segment is a straight line.	No
Curvature_ Center_X	Double		the end point of the lane segment, which is the east component of the UTM coordinate of the Curvature center point of the lane segment, which is the north component of the UTM coordinate. This will not be populated if the lane segment is a straight line.	No
Curvature_ Center_X	Double		the end point of the lane segment, which is the east component of the UTM coordinate. The X coordinate of the curvature center point of the lane segment, which is the north component of the UTM coordinate. This will not be populated if the lane segment is a straight line.	No
Curvature_ Center_X	Double		the end point of the lane segment, which is the east component of the UTM coordinate. The X coordinate of the curvature center point of the lane segment, which is the north component of the UTM coordinate. This will not be populated if the lane segment is a straight line.	No
Curvature_ Center_X Curvature_ Center_Y	Double		the end point of the lane segment, which is the east component of the UTM coordinate. The X coordinate of the curvature center point of the lane segment, which is the north component of the UTM coordinate. This will not be populated if the lane segment is a straight line. The Y coordinate of the curvature	No
Curvature_ Center_X	Double		the end point of the lane segment, which is the east component of the UTM coordinate. The X coordinate of the curvature center point of the lane segment, which is the north component of the UTM coordinate. This will not be populated if the lane segment is a straight line. The Y coordinate of the curvature contoninate of the curvature	No
Curvature_ Center_X	Double		the end point of the lane segment, which is the east component of the UTM coordinate. The X coordinate of the curvature center point of the lane segment, which is the north component of the UTM coordinate. This will not be populated if the lane segment is a <u>straight line</u> . The Y coordinate of the curvature center point of the lane	No
Curvature_ Center_X Curvature_ Center_Y	Double		the end point of the lane segment, which is the east component of the UTM <u>coordinate</u> . The X coordinate of the curvature center point of the lane segment, which is the north component of the UTM coordinate. This will not be populated if the lane segment is a straight line. The Y coordinate of the curvature center point of the curvature center point of the curvature center point of the curvature	No
Curvature_ Center_X	Double		the end point of the lane segment, which is the east component of the UTM coordinate. The X coordinate of the curvature center point of the lane segment, which is the north coordinate. This will not be populated if the lane segment is a straight line. The Y coordinate of the curvature center point of the lane	No
Curvature_ Center_X Curvature_ Center_Y	Double		the end point of the lane segment, which is the east component of the UTM coordinate. The X coordinate of the curvature center point of the lane segment, which is the north component of the UTM coordinate. This will not be populated if the lane segment is a <u>straight line</u> . The Y coordinate of the curvature center point of the lane segment is a <u>straight line</u> .	No

				component of	
				the UTM	
				coordinate.Thi	
				s will not be	
				nopulated if	
				the lane	
				segment is a	
				straight line.	
Line Type	Integer	0 – straight		Indicates	Yes
	C	line 1 – arc		whether the	
		inite, i uite		lane segment	
				iane segment	
				is a straight	
				line or an arc.	
Direction R	Integer	0 for		For arc lane	no
endered	_	clockwise, 1		segments.	
		for counter-		indicates	
		CIOCKWISE		which way to	
				render the lane	
				segment.	
Lane Segm	Integer	0 indicates		Shows the	
ent Type	meger	lane segmen		type of lane	
cm_rypc		lanc_segmen		type of falle	
1		i, i indictaes		segment that	
1		lane_junctio		this generic	
1		n lane segm		lane segment	1
1		ent		is (either a	
1				lane segment	
1				lane_segment	1
1				ora	
				lane_junction_	
				lane segment)	
Direction o	Integer	0 indicates		Show the	
f Traval	integer	the direction		direction of	
1_Traver		the direction			
		of travel of		travel of the	
		the lane is		lane with	
		the way it is		respect to the	
		rendered 1		way it is	
		indiantas tha		way it is	
		indicates the		rendered. II -	
		direction of		2, you must	
		travel of the		look at the	
		lane is		GenericLaneS	
		opposite the		egmentTimeV	
		opposite the		orgina Attribut	
		way it is		aryingAttribut	
		rendered		e table using	
				the ID of the	
				GenericLaneS	
1				egment and	
1				"Direction of	1
1				Direction_of	
1				_Travel" for	1
1				the	
1				Attribute Tvn	
1				e	1
Const T.	Testa			The next 1	
Speea_Limi	integer			i ne posted	yes
t				speed limit for	
1				the lane	
1				segment in	1
1				m/s If the	
1				volue is 2	
1				value is -2,	
1				you must look	1
1				in the	
1				GenericLaneS	
1				egmentTimeV	1
1				oming Attailant	
1				aryingAttribut	
1				e table to	1
1				determine the	
1				speed limit	
Average Co	Integer			The average	no
Average_sp	meger			ine average	110
eed				speed for	
1				vehicles	
1				traveling on	1
1				the lane	
1				sogmont in	1
1	1			segment, in	1

				1 10-1	
				m/s. If the	
				value is $-2$ ,	
				you must look	
				in the	
				GenericLaneS	
				egmentTimeV	
				aryingAttribut	
				e table to	
				determine the	
				average speed.	
Length	Double			The length of	yes
•				the lane,	-
				measured	
				from center	
				point to center	
				point. This	
				should be	
				derived from	
				the other	
				information in	
				this table.	
Orientation	Double	Any number		Radians in	no
		between 0		absolute	
		and 2 PI		coordinates, 0	
				is north	
				facing,	
				increasing	
				clockwise	

Table 8: Generic Lane Segment Attributes

# 4.2. Lookup Tables

#### 4.2.1. Lane Accessibility Lookup

The LaneAccessibilityLookup table contains all possible accessibility restrictions on lanes of a road. Some entries in this table include high occupancy vehicle (HOV) restrictions, taxi-only lanes, and bus-only lanes. Many of these accessibility restrictions will be time-dependent (e.g., a HOV may only be in effect certains hours of certain days). This will be handled by the LaneTimeVaryingAttributes table. In future versions of the database, an exhaustive list of lane accessibility types will be included in the databases itself.

Attribute	Data Type	Value	Points	Is Pointed To	Description	Required
		Restrictions	То	From		Value?
ID	Integer	Any whole		Lane.Accessibility	A unique identifier for this	yes
	_	number greater		-	entry in this table	
		or equal to one				
Accessibility_	Text				The accessibility restriction on	yes
Туре					the lane. (e.g., none, HOV-2,	
					HOV-3, cabs-only, etc.)	
Description	Text				A textual description of this	no
-					field for human understanding	

Table 9: Lane Accessibility Lookup Attributes

### 4.2.2. Lane Barrier Lookup

The LaneBarrierLookup table contains all possible barriers that could exist on the side of a lane. Lane barriers could include jersey barrier, curb, guard rail, etc. There could be a barrier to the left and/or to the right of a lane, hence there are two pointers from the lane segment table to this barrier table. In future versions of the database, an exhaustive list of lane barriers will be included in the databases itself.

Attribute	Data Type	Value Restrictions	Points To	Is Pointed To From	Description	Required Value?
ID	Integer	Any whole number greater or equal to one		LaneSegment.Left_Lane_Barrier_ID, LaneSegment.Right_Lane_Barrier_ID, GenericLaneSegment. Left_Lane_Barrier_ID, GenericLaneSegment. Right_Lane_Barrier_ID, JunctionLaneSegment. Left_Lane_Barrier_ID, JunctionLaneSegment. Right_Lane_barrier_ID,	A unique identifier for this entry in this table	yes
Barrier_Type	Text				The barrier type on a side of a lane. (e.g., none, jersey barrier, curb, guard rail. etc.)	yes
Description	Text				A textual description of this field for human understanding	no

Table 10: Lane Barrier Lookup Attributes

#### 4.2.3. Lane Markings Lookup

The LaneMarkingsLookup table contains all possible lane markings that could exist on the left or right of a lane segment, as defined by the Department of Transportation. This could include no markings, white or yellow dashed lines, white or yellow solid lines, etc. In the case of a double yellow line in between two lanes, this table would only include the part of that marking which pertains to your lane, namely, the single solid yellow line directly to the left of the lane. Similarly, the lane going the opposite direction would also have a single yellow line to its left, indicating the other half of the double yellow line. In future versions of the database, an exhaustive list of lane markings will be included in the databases itself.

Attribute	Data Type	Value Restrictions	Points To	Is Pointed To From	Description	Required Value?
ID	Integer	Any whole number greater or equal to one	10	LaneSegment. Left_Lane_Marking_ID, LaneSegment. Right_Lane_Marking_ID, GenericLaneSegment. Left_Lane_Marking_ID, GenericLaneSegment. Right_Lane_Marking_ID, JunctionLaneSegment. Left_Lane_Marking_ID, JunctionLaneSegment. Right_Lane_Marking_ID	A unique identifier for this entry in this table	yes
Marking _Type	Text				The lane marking type on a side of a lane. (e.g., none, solid yellow, dashed yellow, solid white, dashed white, etc.)	yes
Description	Text				A textual description of this field for human understanding	no

Table 11: Lane Markings Lookup Attributes

## 4.2.4. Lane Type Lookup

The LaneTypeLookup table contains additional information about a lane that is not evident from the other attributes of a lane. In the database, lanes could be either traversable lanes or shoulders. The lane table thus points to the LaneTypeLookup table to indicate which it is. There are cases when shoulder on roads open up to become traversable lanes. This is handled by the LaneTimeVaryingAttributes table. In future versions of the database, an exhaustive list of lane types will be included in the databases itself.

Attribute	Data Type	Value	Points	Is Pointed To	Description	Required
		Restrictions	То	From		Value?
ID	Integer	Any whole number greater or equal to one		Lane.LaneType_ID	A unique identifier for this entry in this table	yes
Lane_Type	Text				The lane type (e.g., traversable, shoulder, etc.)	yes
Description	Text				A textual description of this field for human understanding	no

Table 12: Lane Type Lookup Attributes

### 4.2.5. Road Segment Class Lookup

The RoadSegmentClassLookup table contains information about the class of road that is prevalent along the span of the road segment. Classes of road segments include interstate highway, beltway, country road, residential street, etc. This type of information allows for better path planning by allowing one to prefer passage via a certain type of road. In future versions of the database, an exhaustive list of road segment classes will be included in the databases itself.

Attribute	Data Type	Value	Points	Is Pointed To	Description	Required
		Restrictions	То	From		Value?
ID	Integer	Any whole		RoadSegment.	A unique identifier for this	yes
		number greater		RoadSegmentClass	entry in this table	
		or equal to one				
Lane_Type	Text				The road segment type (e.g.,	yes
					interstate highway, beltway,	
					country road, residential	
					street, etc.)	
Description	Text				A textual description of this	no
					field for human understanding	

Table 13: Road Segment Class Lookup Attributes

## 4.2.6. Road Surface Lookup

The RoadSurfaceLookup table contains information about the road surface types for a lane. The road surface types include asphalt, pebbles, dirt, etc. The coefficient of friction values indicate the approximate coefficient of friction for the different types of road surfaces during generally wet and generally dry conditions. In future versions of the database, an exhaustive list of road surface types will be included in the databases itself.

Attribute	Data Type	Value Restrictions	Points To	Is Pointed To From	Description	Required Value?
ID	Integer	Any whole number greater or equal to one		Lane.RoadSurface_ID	A unique identifier for this entry in this table	yes
Surface_Type	Text				The surface type for a lane(e.g., asphalt, pebbles, dirt, etc.).	yes
Description	Text				A textual description of this field for human understanding	no
Coefficient_of _Friction_Wet	Number				Indicates the approximate coefficient of friction of a road surface when the road conditions are wet (when known).	no
Coefficient_of _Friction_Dry	Number				Indicates the approximate coefficient of friction of a road surface when the road conditions are dry (if known).	no

Table 14: Road Surface Lookup Attributes

## 4.2.7. Special Road Feature Lookup

The SpecialRoadFeatureLookup table contains information about any special features that exist on the road. Special features could indicate that the stretch of road is part of a tunnel, bridge, etc. In future versions of the database, an exhaustive list of road feature types will be included in the databases itself.

Attribute	Data Type	Value	Points	Is Pointed To From	Description	Required
		Restrictions	10			value:
ID	Integer	Any whole		LaneCluster.	A unique identifier for this	yes
	•	number greater		Special_Road_Feature	entry in this table	-
		or equal to one				
Road_Featu	Text				The special road feature	yes
re_Type					(e.g., bridge, tunnel, etc.)	
Description	Text				A textual description of	no
					this field for human	
					understanding	

Table 15: Special Road Feature Lookup Attributes

# 4.3. Time Varying Attributes

In many cases, road attributes can vary over time. Lane directions can change as a function of the time of day, shoulders can open up for travel, high occupancy vehicle (HOV) restrictions may or may not be in effect, speed limits can change depending if schools are letting out, etc. A series of time varying attributes tables address this by associating dates and times with different attributes of the data structures.

### 4.3.1. Generic Lane Segment Time Varying Attributes

Within the lane segment table, three attributes may be time varying: speed limit, average speed, and lane direction. In the case when these attributes are not time varying, the value for these attributes are entered directly in the appropriate attribute value spot in the lane segment table. In the case when these attributes are time varying, a -2 will be entered as the value to indicate that one must look in this table to get the value. A unique row in this table is identified by passing the ID of the lane segment, the attribute that is being queried (one of speed\_limit, average\_speed, or lane direction), and the time that one wants to check. In the case of speed limit and average speed, the value returned will be in meters/second. In the case of lane\_direction, a 0 indicates positive direction and a 1 indicates negative direction, with respect to how the lane segment was rendered.

Attribute	Data	Value	Points To	Is Pointed	Description	Required
ID	Integer	Any whole		TOFIOM	A unique identifier for this	value:
	integer	number greater			entry in this table	yes
		or equal to one			chu y in this tuble	
World_ID	Integer	or equal to one	World.ID		A pointer to an element in the World table that indicates	yes
					associated with. A time	
					varying attribute may only be associated with a single world.	
					See 4.5.1. for information about worlds.	
Lane_Segment _ID	Integer		GenericLaneSeg ment.ID		A pointer to the element in the LaneSegment table which this time varying attribute is	yes
Attribute	Text	Speed Limit			associated with.	VAS
Type	Телі	Average Speed			GenericI aneSegment table	yes
_ <sup>rypc</sup>		Average_speed			which the time varying	
		, Direction of T			attributes refers to	
		ravel				
Begin Date	Date/Ti	14101			The date and time that the	ves
and Time	me				value for the attribute takes	5
					effect. Note that this mention	
					and all future mentions of	
					date/time is a placeholder. A	
					more detailed representation,	
					which will most likely involve	
					a dedicated table, will be	
					included in future versions.	
End_Date_and	Date/Ti				The date and time that the	yes
_Time	me				value for the attribute ends.	
Value	Integer				The value associated with the	yes
					attribute. In the case of	
					average_speed and	
					speed_limit, the units are	
					neters/second. In the case of	
					lane_direction, 0 indicates	
					positive direction and 1	
					indicates negative direction.	
Description	Text				A textual description of this	no
	1				field for human understanding	

Table 16: Generic Lane Segment Time Varying Attributes

#### 4.3.2. Lane Time Varying Attributes

Within the lane table, two attributes may be time varying: lane type and lane accessibility. In the case when these attributes are not time varying, the value for these attributes are entered directly in the appropriate attribute value spot in the lane table. In the case when these attributes are time varying, a -2 will be entered as the value to indicate that one must look in this table to get the actual value. A unique row in this table is identified by passing the ID of the lane, the attribute that is being queried (one of lane\_type or lane\_accessibility), and the time that one wants to check. In the case of lane\_accessibility, a pointer to an element in the LaneAccessibilityLookup table is returned. In the case of lane\_type, a pointer to an element in the LaneTypeLookup table is returned.

Attribute	Data	Value	Points To	Is Pointed To	Description	Required
	Туре	Restrictions		From		Value?
ID	Integer	Any whole		Lane.	A unique identifier for	yes
		number greater		LaneType_ID,	this entry in this table	
		or equal to one		Lane.		
				Accessibility		
World_ID	Integer		World.ID		A pointer to an element	yes
					in the World table that	
					indicates which world	
					this entry is associated	
					with. A time varying	
					attribute may only be	
					associated with a single	
					world. See 4.5.1. for	
					worlds	
Lana ID	Integer		Lana ID		A pointer to the element	1/05
Lane_ID	Integer		Lane.iD		in the Lane table which	yes
					this time varying	
					attribute is associated	
					with	
Attribute Type	Text	Lane Type			The attribute in the Lane	ves
indicate_1)pe	10.00	Lane Accessibili			table that the time	<i>y</i> <b>e</b> <i>c c</i>
		tv			varving attributes refers	
		.5			to.	
Begin Date an	Date/Ti				The date and time that	yes
d_Time	me				the value for the	5
					attribute takes effect.	
End_Date_and_	Date/Ti				The date and time that	yes
Time	me				the value for the	
					attribute ends.	
Value	Integer		LaneAccessibility		The value associated	yes
			Lookup.ID		with the attribute. In the	
					case of lane	
			OR		accessibility, this is a	
			LaneTypeLookup.		pointer to an element in	
			ID		the LaneAccessibility	
					lookup table. In the case	
					of lane_type, this is a	
					the LengTure Legiture	
					table	
Description	Text				A textual description of	no
Description	ICAL				this field for human	110
					understanding	

Table 17: Lane Time Varying Attributes

### 4.3.3. Lane Junction Traversibility Time Varying Attributes

Within the lane junction traversibility table, the permissibility attributes may be time varying. For example, the legality for traversing from one lane segment that is entering an intersection to another lane segment that is exiting the intersection may change at different times of the day. This may be captured by a sign which states "No right turn between 3:00pm and 6:00pm Monday through Friday". In the case when this attribute is not time varying, the value for this attribute is entered directly in the permissibility attribute value spot in the lane junction traversibility table. In the case when this attribute is time varying, a -2 will be entered as the value in the lane junction traversibility table to indicate that one must look in this time varying attribute table to get the actual value. A unique row in this table is identified by passing the ID of the lane\_junction\_traversibility and the time that one wants to check.

Attribute	Data Type	Value	Points To	Is Pointed	Description	Required
The second se		Restrictions		To From		Value?
ID	Integer	Any whole			A unique identifier for this	yes
		number			entry in this table	
		greater or				
		equal to one				
World_ID	Integer		World.ID		A pointer to an element in the	yes
					World table that indicates	
					which world this entry is	
					associated with. A time	
					varying attribute may only be	
					associated with a single world.	
					See 4.5.1. for information	
					about worlds.	
LaneJunctionTr	Integer		LaneJunction		A pointer to the element in the	yes
aversibility ID	_		Traversibility.		LaneJunctionTraversibility	
			ID		table which this time varying	
					attribute is associated with.	
Begin Date	Date/Time				The date and time that the	yes
_and_Time					value for the attribute takes	
					effect.	
End_Date	Date/Time				The date and time that the	yes
_and_Time					value for the attribute ends.	
Value	Integer				The value associated with the	yes
					attribute. '0' indicates legal,	
					'1' indicates illegal, '2'	
					indicates impossible.	
Description	Text				A textual description of this	no
					field for human understanding	

Table 18: Lane Junction Traversibility Time Varying Attributes

### 4.3.4. Intersection Traversibility Time Varying Attributes

Within the intersection traversibility table, the permissibility attributes may be time varying. For example, the legality for traversing from one road segment that is entering an intersection to another road segment that is exiting the intersection may change at different times of the day. This may be captured by a sign which states "No right turn between 3:00pm and 6:00pm Monday through Friday". In the case when this attribute is not time varying, the value for this attribute is entered directly in the permissibility attribute value spot in the intersection traversibility table. In the case when this attribute is time varying, a -2 will be entered as the value in the intersection traversibility table to indicate that one must look in this time varying attribute table to get the actual value. A unique row in this table is identified by passing the ID of the intersection\_traversibility and the time that one wants to check.

The information is this table is very similar to, and can be derived from, the information in the lane junction traversibility time varying attribute table. This table is included in the database to facilitate route planning and higher levels in a control hierarchy by allow the control system to be able to understand traversibility at intersection between road segments without having to dive down into the lane segments level.

Attribute	Data Type	Value	Points To	Is Pointed	Description	Required
ID	Integer	Any whole		TOFIOM	A unique identifier for this	yes
	•	number			entry in this table	-
		greater or				
		equal to one				
World_ID	Integer		World.ID		A pointer to an element in the	yes
					World table that indicates	
					which world this entry is	
					associated with. A time	
					varying attribute may only be	
					associated with a single world.	
					See 4.5.1. for more	
					information about worlds.	
LaneJunctionTr	Integer		LaneJunction		A pointer to the element in the	yes
aversibility_ID			Traversibility.		LaneJunctionTraversibility	
			ID		table which this time varying	
					attribute is associated with.	
Begin_Date_an	Date/Time				The date and time that the	yes
d_Time					value for the attribute takes	
					effect.	
End_Date_and_	Date/Time				The date and time that the	yes
Time					value for the attribute ends.	
Value	Integer				The value associated with the	yes
					attribute. '0' indicates legal,	
					'1' indicates illegal, '2'	
					indicates impossible.	
Description	Text				A textual description of this	no
					field for human understanding	

Table 19: Intersection Traversibility Time Varying Attributes

## 4.4. Junctions

#### 4.4.1. Junction

Junctions are a general term to refer to two or more paths of transportation that come together or diverge, or a controlled point in a roadway. Paths of transportation could be roadway or not roadway paths. Example of roadway paths that could cause a junction are lanes splits, forks in the road, merges, and intersections. Example of junctions caused by roadway and non-roadway paths are pedestrian crossings, ferry crossings, railroad crossings. Examples of controlled points in the roadway are draw bridges, toll plazas, and guard gates. Junctions are an abstract supertype in the sense that a junction must be one of the types listed above. As of the time this document was published, only the intersection junction-type was included in the database. Other junction types will follow shortly.

Junctions are made up of one or more lane junction and zero or more lane junctions. Roads are made up of one or more road segment and zero or more junctions.

Attribute	Data	Value	Points To	Is Pointed To From	Description	Required
	Туре	Restrictions				Value?
ID	Integer	Any whole number greater or equal to one		Road_Element. Start_Point_Adjacent_Junction, Road_Element. End_Point_Adjacent_Junction, LaneCluster.Junction_ID, LaneCluster.Left_LandJunction, LaneCluster.Right_LaneJunction, LaneCluster.Start_LaneJunction, LaneCluster.End_LaneJunction, LaneCluster.End_LaneJunction,	A unique identifier for this entry in this table	yes
World_ID	Integer		World.ID		A pointer to an element in the World table that indicates which world this entry is associated with. A junction may only be associated with a single world. See 4.5.1. for more information about worlds.	yes
Description	Text				A textual description of this field for human understanding	no
RoadSegment _ID	Integer		Road_Seg ment.ID		A pointer to the element in the road segment table that this junction is a part of	yes

Table 20: Junction Attributes

#### 4.4.2. Intersections



**Figure 8: Intersection** 

Intersections are a type of junction in which two or more separate roads come together. The bounds of an intersection coming from any roadway that enters the intersection are decided in the following order:

- 1. If a stop line exists (a line in the road that indicates where a vehicle is suppose to stop), the side of the line that is furthest from the intersection.
- 2. If a crosswalk exists, the side of the crosswalk that is furthest from the intersection.
- 3. If a traffic sign exist to control the intersection, one would use the location of that sign to draw a line perpendicular to the direction of traffic.
- 4. If lane markings in the road exist that separate different lanes of travel, the last point in which the lane marking is visible. One would then use that point to draw a line across the roadway perpendicular to the direction of traffic.
- 5. If none of the above exists, a line should be draw connecting the corners of the road where it touches the intersection.

Attribute	Data	Value	Points To	Is Pointed To From	Description	Required
	Туре	Restrictions				Value?
ID	Integer	Any whole number greater or equal to one		RoadSegment. Start_Point_Adjacent_Intersection_ID, RoadSegment. End_Point_Adjacent_Intersection_ID, IntersectionTraversibility. Intersection_ID	A unique identifier for this entry in this table	yes
World_ID	Integer		World.ID		A pointer to an element in the World table that indicates which world this entry is associated with. An intersection may only be associated with a single world. See 4.5.1. for information about worlds.	yes
Description	Text				A textual description of	no

				this field for human understanding	
Junction_ID	Integer	Any whole number greater or equal to one	Junction.ID	A pointer to the junction that this intersection is a type of.	yes

Table 21: Intersection Attributes

### 4.4.3. Intersection Traversibility

The intersection traversibility table captures, at a road segment level, the permissible traversibility through an intersection. In other words, for every pair of road segments that is connected to an intersection (e.g., RoadSegment1 and RoadSegment2), there are two entries in this table, one that describes the permissibility of going from RoadSegment1 to RoadSegment2 and one that describes the permissibility of going from RoadSegment1. Therefore, for an intersection that is bounded by 8 road segments, there would be 8 entering road segments \* 7 possible exiting road segments (since you can't exit on the path that you entered) = 56 entries in the table for that intersection. Permissibility can take one of three values: 1) *legal* meaning that it is possible and legal to traverse that path; 2) *illegal* meaning that it is possible but illegal to traverse that path; and 3) *impossible* meaning that it is not physically possible to traverse that path. An impossible path may occur when a barrier exists between the entering road segment and the existing road segment.

In some cases, the permissibility of the intersection traversibility may be time varying. In this case, the value in this table for the permissibility attribute will be -2, which indicates that one must look in the intersection traversibility time varying attribute table to determine the permissibility at a given point in time.

Attribute	Data Type	Value Restrictions	Points To	Is Pointed To From	Description	Required Value?
ID	Integer	Any whole number greater or equal to one			A unique identifier for this entry in this table	yes
World_ID	Integer		World.ID		A pointer to an element in the World table that indicates which world this entry is associated with. An intersection traversibility may only be associated with a single world. See 4.5.1. for information about worlds.	yes
Description	Text				A textual description of this field for human understanding	no
Intersection_ID	Integer		Intersection.ID		A pointer to the element in the intersection table that an element in this table applies to.	yes
Incoming_Road Segment_ID	Integer		RoadSegment.ID		A pointer to an element in the RoadSegment table that indicates the road segment that is to be evaluated as entering the intersection.	yes
Incoming_Road Segment_Side	Integer	0 or 1			This is the side of the incoming road segment which is adjacent to the intersection. '0' indicates that the beginning of the road segment is adjacent to the intersection, '1' indicates that the end of the road segment is adjacent to the intersection (based upon how the road segment is rendered).	yes
Outgoing_Road Segment_ID	Integer		RoadSegment.ID		A pointer to an element in the RoadSegment table that indicates the road segment that is be evaluated as exiting the intersection.	yes
Outgoing_Road Segment_Side	Integer	0 or 1			This is the side of the outgoing road segment which is adjacent to the intersection. '0' indicates that the beginning of the road segment is adjacent to the intersection, '1' indicates	yes

				that the end of the road segment is adjacent to the intersection (based upon how the road segment is rendered).	
Permissibility	Integer			Indicates the permissibility through the intersection. '1' indicates legal, '2' indicates illegal, '3' indicated impossible. '-2' indicates that it is timevarying, and one must look at the IntersectionTraversibilityTime VaryingAttribute table using the ID of the IntersectionTraversibility to determine the permissibility	yes
Relative_Directi on	Integer	1, 2, or 3		Indicated the direction in which the outgoing road segment as compared to the incoming lane segment. This is only applicable when that lane segment has traffic that is entering the intersection. All other times, this field is left empty. 0 – opposite (straight ahead) 1 – left (from the left of straight ahead) 2 – right (from the right of straight ahead)	

Table 22: Intersection Traversibility Attributes

### 4.4.4. Lane Junction

A lane junction is a location in a road network in which two or more lanes of traffic overlap. A lane merge contains a lane junction starting at the point in which the two lanes begin to come together and end at the point in which the two lane are completely together as one. A lane fork contains a lane junction at the point where the lanes begin to fork and ends at the point where the two lanes are completely separated. An intersection contains a lane junction at all points in which the lanes from the two or more intersecting roads overlap.

Paths through lane junctions are defined using junction lane segments. Lane junctions are primarily used by the lower levels of a control system to define the path a vehicle should take to traverse the lane junction and to understand the permissibility of traversing through different paths of the lane junction.

Attribute	Data Type	Value Restrictions	Points To	Is Pointed To From	Description	Required Value?
ID	Integer	Any whole number greater or equal to one		LaneJunctionTraversibility .LaneJunction_ID	A unique identifier for this entry in this table	yes
World_ID	Integer		World.ID		A pointer to an element in the World table that indicates which world this entry is associated with. A lane junction may only be associated with a single world. See 4.5.1. for more information about worlds.	yes
Description	Text				A textual description of this field for human understanding	no
Junction_ID	Integer		Junction.ID		A pointer to the element in the junction table that an element in this table applies to.	yes
Lane_Junctio n_Center_X	Double				The X_coordinate center location of the lane junction, which is the north component of the UTM coordinate.	no
Lane_Junctio n_Center_Y	Double				The Y_coordinate center location of the lane junction, which is the east component of the UTM coordinate.	no

Table 23: Lane Junctions Attributes

#### 4.4.5. Junction Lane Segments (JLS)

Paths through lane junctions are defined using junction lane segments. A junction lane segment is a constant curvature path through a portion of a lane junction. JLSs are very similar to lane segments in that they:

- can be either straight line or constant curvature arcs. In the case of a straight line, the location of the lane segment if fully defined by the beginning and end point of the lane segment. For a constant curvature arc, the lane segment is defined by the beginning and end of the lane segment and the curvature center point.
- can be arbitrarily cut off at intermediate points
- are primarily used within a control system or planner to generate the detailed path that a vehicle is expected to follow.

JLSs are different than lane segments in that there can be up to three JLSs that come directly after a given JLS and there can be up to three JLSs that come directly before a given JLS. Also, multiple junction lane segment do not compose a lane, they simply show a path through a lane junction.

Any given JLS can have either a single lane segment or one to three JLS before it. Any given JLS can have either a single lane segment or one to three JLS after it.

This table only houses the attributes and values that are specific to a junction lane segment and are different that a lane segment. The common attributes between the two can be found in the generic lane segment table. The generic lane segment (in the generic lane segment table), which has the same ID as this junction lane segment will contain the corresponding attribute and values.

A small junction lane segment should be placed just priori to every entrance to a lane junction, just after the last lane segment that approaches the lane junction.

Lane junctions are primarily used by the lower levels of a control system to define the path a vehicle should take to traverse the lane junction and to understand the permissibility of traversing through different paths of the lane junction.

Attribute	Data Type	Value Restrictions	Points To	Is Pointed To From	Description	Required Value?
ID	Integer	Any whole number greater or equal to one		JunctionLaneSegment. Right_JunctionLaneSegment_ID, JunctionLaneSegment. Left_JunctionLaneSegment_ID, JunctionLaneSegment_Connectivity. Incoming_JunctionLaneSegment_ID, JunctionLaneSegment_Connectivity. Outgoing_JunctionLaneSegment_ID	A unique identifier for this entry in this table	yes
World_ID	Integer		World.ID		A pointer to an element in the World table that indicates which world this entry is associated with. A junction lane segment may only be associated with a single world. See 4.5.1. for more information about worlds.	yes
Lane_Juncti on_ID	Integer		LaneJuncti on.ID		A pointer to the lane junction which the junction lane segment is in.	no
Junction ID	Integer		Junction.ID		A pointer to the	yes

	1		junction which the	
			junction lane	
			juiction faile	
TOT	T /	T M 1	segment is in.	
Left_Lane_	Integer	LaneMarki	A pointer to and	no
Marking_I		ngs.ID	element in the lane	
D			marking table that	
			shows the type of	
			lane marking to	
			the left of a	
			junction lane	
			segment with	
			respect to how it	
			was rendered.	
			Markings are	
			sometimes present	
			in intersections to	
			separate two lanes	
			that are turning the	
			same direction	
Dight Lana	Integer	LanaMarki	A pointer to ap	<b>n</b> 0
Kight_Lane	Integer		A pointer to an	по
_Marking_I		ngs.ID	element in the lane	
D			markings table	
			that shows the	
			type of lane	
			marking to the	
			right of a junction	
			lane segment with	
			respect to how it	
			respect to now it	
			was rendered.	
			Markings are	
			sometimes present	
			in intersections to	
			separate two lanes	
			that are turning the	
			same direction.	
Left Lane	Integer	LaneBarrier	A pointer to an	no
Barriar ID	integer	ID	alement in the lane	110
Dainer_ID		.ID	termientelle the	
			barrier table that	
			shows the type of	
			lane barrier to the	
			left of a junction	
			lane segment, with	
			respect to how it	
			was rendered	
Right Lane	Integer	LaneBarrier	A pointer to an	no
Dorright_Lanc	integer	D	A pointer to an	110
_bainer_iD		.ID		
			barriers table that	
			shows the type of	
			lane barrier to the	
			right of a junction	
			lane segment. with	
			respect to how it	
			was rendered	
Dight Junet	Integer	Innation La	A pointer to an	
Kigni_Junct	integer	JunctionLa	A pointer to an	no
ionLaneSeg		neSegment.	element in the	
ment_ID		ID	junction lane	
			segment to the	
			right of this	
			junction lane	
			segment with	
			respect to how it	
			was rendered	
T O T	<b>T</b> .		was rendered.	
Left_Juncti	Integer	JunctionLa	A pointer to an	no
onLaneSeg		neSegment.	element in the	
ment_ID		ID	junction lane	
_			segment to the left	
			of this junction	
	1		lane segment with	
Î.				
			ragnant to how it	
			respect to how it	

Beginning	Integer		An indication of a	
Control	C		traffic control	
			mechanism that	
			governs how a	
			vehicle should	
			behave at the	
			beginning of that	
			junction lane	
			segment.	
			1 – stop sign	
			2 – yield sign	
			3 – traffic light	
			4 – gate	
			5 – no control	
			6 – lane segment	
			exiting the	
			intersection	
Start Link	Integer	Generic La	A pointer to an	no
Canania La	Integer	Generic_La	A pointer to an	110
Generic_La		nesegment.	element in the	
ne_Segment		ID	generic lane	
_1			segment table that	
			show the generic	
			lane segment	
			which comes	
			directly before this	
			iunction lane	
			segment if it	
			segment, II It	
			exists. An entry of	
			-1 indicates that a	
			start_link_generic	
			_lane_segment	
			does not exist, and	
			thus a dead-end is	
			present. This field	
			is nonulated unless	
			is populated unless	
			it is a dead end.	
			This field could	
			either hold a lane	
			segment, or the	
			left most junction	
			lane segment with	
			respect to how the	
			iunction lane	
			segment is	
			segment is	
Q 1	<b>*</b> .	a : .	rendered.	
Start_Link_	Integer	Generic_La	A pointer to an	no
Generic_La		neSegment.	element in the	
ne_Segment		ID	generic lane	
2			segment table that	
_			shows the generic	
			lane segment	
			which comes	
			directly before this	
			iumation 1	
			junction lane	
			segment, if it	
			exists. This field	
			only holds the	
			second left most	
			junction lane	
			segment with	
			respect to how the	
			iunction long	
			junction falle	
			segment is	
			rendered, if it	
			exists.	
Start_Link_	Integer	Generic_La	A pointer to an	no
Generic La	-	neSegment.	element in the	
ne Segment		ID	generic lane	
3			segment table that	
			shows the generic	
1	l		snows the generic	

			-	
			lane segment which comes directly before this junction lane segment, if it exists. This field only holds the third left most junction lane segment with respect to how the junction lane segment is rendered, if it exists.	
End_Link_ Generic_La ne_Segment _1	Integer	Generic_La neSegment. ID	A pointer to an element in the generic lane segment table that shows the generic lane segment which comes directly after this junction lane segment, if it exists. An entry of -1 indicates that an end_link_generic_ lane_segment does not exist, and thus a dead-end is present. This field could either hold a lane segment, or the left most junction lane segment with respect to how the junction lane segment is rendered.	no
Generic_La ne_Segment _2	integer	neSegment. ID	A pointer to an element in the generic lane segment table that shows the generic lane segment which comes directly after this junction lane segment, if it exists. This field only holds the second left most junction lane segment with respect to how the junction lane segment is rendered, if it exists	
End_Link Generic_La ne_Segment _3	Integer	Generic_La neSegment. ID	A pointer to an element in the generic lane segment table that shows the generic lane segment which comes directly after this	no

		junction lane	
		segment if it	
		segment, ii n	
		exists. This field	
		only holds the	
		third left most	
		junction lane	
		segment with	
		respect to how the	
		junction lane	
		segment is	
		rendered, if it	
		exists.	

Table 24: Lane Junctions Lane Segments Attributes

#### 4.4.6. Lane Junction Traversibility

The lane junction traversibility table captures, at a lane segment level, the permissible traversibility through a lane junction. In other words, for every pair of lane segments that is connected to a lane junction (i.e., LaneSegment1 and LaneSegment2), there are two entries in this table, one that describes the permissibility of going from LaneSegment1 to LaneSegment2 and one that describes the permissibility of going from LaneSegment1. Therefore, for a lane junction that is bounded by 8 lane segments, there would be 8 entering lane segments \* 7 possible exiting lane segments (since you can't exit on the path that you entered) = 56 entries in the table for that lane junction. Permissibility can take one of three values: 1) *legal* meaning that it is possible and legal to traverse that path; 2) *illegal* meaning that it is possible but illegal to traverse that path; and 3) *impossible* meaning that it is not physically possible to traverse that path. An impossible path may occur when a barrier exists between the entering road segment and the existing road segment. Note that this table does not address the issue of "right of way", since that is a real-time determination based upon the location of vehicles and objects on the roadway as opposed to characteristics of the roadway itself.

In some cases, the permissibility of the lane junction traversibility may be time varying. In this case, the value in this table for the permissibility attribute will be -2, which indicates that one must look in the lane junction traversibility time varying attribute table to determine the permissibility at a given point in time.

Attribute	Data	Value	Points To	Is Pointed To	Description	Required
	Туре	Restrictions		From		Value?
ID	Integer	Any whole		IntersectionTrave	A unique identifier for this	yes
		number		rsibilityTimeVar	entry in this table	
		greater or		yingAttribute.La		
		equal to one		neJunctionTraver		
				sibility_ID		
World_ID	Integer		World.ID		A pointer to an element in the	yes
					World table that indicates	
					which world this entry is	
					associated with. A lane	
					junction traversibility may	
					only be associated with a	
					single world. See 4.5.1. for	
					information about worlds.	
Description	Text				A textual description of this	no
					field for human understanding	
LaneJunction_I	Integer		LaneJunction.ID		A pointer to the element in	yes
D					the lane junction table that an	
					element in this table applies	
					to.	
Incoming_Lane	Integer		GenericLaneSeg		A pointer to an element in the	yes
Segment_ID			ment.ID		GenericLaneSegment table	
					that indicates the lane	
					segment that is be evaluated	
					as entering the lane junction.	
Incoming_Lane	Integer	0 or 1			This is the side of the	yes
Segment_Side					incoming lane segment that is	
					adjacent to the lane junction.	
					0 <sup>°</sup> indicates that the	
					beginning of the lane segment	
					is adjacent to the lane	
					junction, 1 indicates that the	
					end of the lane segment is	
					adjacent to the lane junction	
					(based upon how the lane	
	<b>T</b> .		0 0		segment is rendered).	
Outgoing_Lane	Integer		GenericLaneSeg		A pointer to an element in the	yes
Segment_ID			ment.ID		GenericLaneSegment table	
					that indicates the lane	
					segment that is be evaluated	
	T. (	0 1			as exiting the lane junction.	
Outgoing_Lane	Integer	U or I			I his is the side of the	yes
Segment Side	1	1		1	outgoing lane segment that is	

1				
			adjacent to the lane junction.	
			'0' indicates that the	
			beginning of the lane segment	
			is adjacent to the lane	
			junction, '1' indicates that the	
			end of the lane segment is	
			adjacent to the lane junction	
			(based upon how the lane	
			segment is rendered).	
Permissibility	Integer		Indicates the permissibility	yes
			through the lane junction. '0'	
			indicates legal, '1' indicates	
			illegal, '2' indicated	
			impossible. '-2' indicates that	
			it is timevarying, and one	
			must look at the	
			LaneJunctionTraversibilityTi	
			meVaryingAttribute table	
			using the ID of the	
			LaneJunctionTraversibility to	
			determine the permissibility	

Table 25: Lane Junctions Traversibility Attributes

# 4.5. Administrative Tables

### 4.5.1. World

Every road network resides in a world. The world provides a reference point in which all coordinates are measured. Currently there is no interaction between worlds – only road "elements" that are in the same world may be related to one another. Future versions of the database will allow for interactions between worlds.

Attribute	Data	Value	Points	Is Pointed To From	Description	Required
	Туре	Restrictions	То			Value?
ID	Integer	Any whole		Road.World_ID,	A unique identifier	yes
		number		RoadSegment.World_ID,	for this entry in	
		greater or		RoadElement.World_ID,	this table	
		equal to one		LaneCluster.World_ID,		
				Lane.World_ID,		
				LaneSegment.World_ID,		
				GenericLaneSegment,World_ID,		
				LaneSegmentTimeVaryingAttribute.		
				World_ID,		
				Lane I ime Varying Attribute. World_ID,		
				LaneJunction I imeVaryingAttribute.		
				wond_nD, IntersectionTroversibilityTimeVersing		
				Attribute World ID Junction World ID		
				Intersection World ID		
				IntersectionTraversibility World ID		
				Lanelunction World ID		
				Junction I aneSegment World ID		
				JunctionLaneSegment Connectivity		
				World ID.		
				LaneJunctionTraversibility.World ID		
Name	Text				This is a name to	no
					refer to the World,	
					for human	
					understanding.	
Descriptio	Text				A textual	no
n					description of the	
					world for human	
					understanding	
X_Offset	Double				An offset in the X	yes
					direction,	
					measured in	
M. O.S.	D 11				meters.	
Y_Offset	Double				An offset in the Y	yes
					direction,	
					measured in	
7	Interne				The LITM in	
Zone	integer				which the world is	yes
					logated	
Export T:	Toyt				The date and time	NOS
mestamn	Text				in which this	yes
mestamp					world was	
					exported	
Name Descriptio n X_Offset Y_Offset Zone Export_Ti mestamp	Text Text Double Double Integer Text			.World_ID, LaneJunctionTraversibility.World_ID	This is a name to refer to the World, for human understanding. A textual description of the world for human understanding An offset in the X direction, measured in meters. An offset in the Y direction, measured in meters. The UTM in which the world is located. The date and time in which this world was exported.	no no yes yes yes

Table 26: World Attributes

#### 4.5.2. Version Control

The version control table provides a mechanism to track changes as they are made to the database. There are nine legal change actions currently permissible:

- added attr added a new attribute to a table
- added table added a new table to the database
- changed attr. name change the name of an attribure
- changed table name changed the name of a table in the database
- removed attr removed an attribute from a table
- removed table removed a table from the database
- redefinition redefined the meaning of an attribute
- moved attr moved an attribute from one table to another
- changed value for attr changed the possible value for an attribute (e.g., from text to integer)

Attribute	Data Type	Value Restrictions	Points To	Is Pointed To From	Description	Required Value?
Version	Double	Any positive number			The version number which the change applies.	yes
Date	Date/Ti me				The date in which the change was made.	yes
Table1	Text				The table that was affected by the change.	yes
Table2	Text				When moving attributes from one table to another, Table1 is the source table and Table2 is the destination table.	yes
Action	Text	Added attr., added table, changed attr. name, changed table name, removed attribute, removed table, moved attr, changed value for attr., redefinition,			The action that was performed on the table.	yes
Description	Text				Further description about the action that was performed.	yes

Table 27: Version Control Attributes

# 5. Conclusion

This document describes the Road Network Database being developed as part of the NIST efforts in enabling autonomous on-road driving. The database is currently at Version 1.0, and has been implemented as part of two planners being developed within NIST (a cost-based and a finite state machine-based planner) within a simulated environment.

Though a considerable amount of time and effort has been put into the database, there is still quite a bit of work that has yet to be accomplished. Additional types of junctions must be included, including merges, forks, pedestrian crossings, and railroad crossings. More information about roads also needs to be included, such as the overall width of the road, so that obstacles can be placed on the roads cleanlier. The database also needs to continue to be "stress tested" in simulated and real environments to ensure its consistency and completeness.