# 11.3: Sensitivity of Display Reflection Measurements to Apparatus Geometry

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#### Abstract1

Reflection measurements made upon electronic displays can suffer from non-reproducibility owing to their possible strong dependence upon apparatus geometry. The geometrical dependence arises from non-Lambertian diffusion properties. We show the inadequacies of several conventional reflection measurement methods and offer some guidance on how these methods might be improved or replaced.

### 1. Introduction

The simple measurements employed to determine the reflection properties of electronic displays generally fall into two categories: diffuse measurements or specular measurements. In reflection, the term "diffuse" refers to light being scattered out of the specular direction; "diffuse" is *not* synonymous with "Lambertian." A surface that exhibits a Lambertian reflectance property is only one

type of diffusing surface, and all diffusing surfaces are not Lambertian. Misconceptions associated with reflection-and in particular the term "diffuse"—have generated a great deal of confusion in the display industry (author included). Space does not permit a full discussion of these details. When the front surface of a display is neither quasi-Lambertian nor specular (like a mirror), the reflection measurement result can be sensitive to the geometrical arrangement of the apparatus. The intermediate state between Lambertian and specular has been referred to as haze [1]. Having a specific name for this intermediate state has become necessary in order to communicate display reflection characteristics. What seems like such a simple measurement can be ruined by a lack of robustness of the result to small changes in the apparatus set up because of the haze component of reflection whenever it is present and non-trivial. We will investigate the geometrical sensitivity of eight different reflection measurement configurations. These kinds of methods are being considered by various display-evaluation standards-making bodies.

## 2. Apparatus Configurations

In Fig. 1 we show the eight apparatus configurations that are employed in the testing. When reflection measurements are made using such apparatus a luminance L measurement of the display is made under a source illuminant configuration. Several kinds of results might be extracted: (1) the luminance L by itself as in making a contrast measurement under illumination; (2) the specular reflectance  $\zeta = L/L_s$  (note that CIE uses  $\rho_r$  [1]), where the luminance  $L_s$  of the source is considered an important apparatus characterization quantity (as in specular types of measurements)—such a measurement is essentially the same as a luminance measurement from the standpoint of this sensitivity analysis; (3) the luminance factor  $\beta = \pi L/E$ , where the illuminance from the source is considered an important quantity; and (4) reflectance  $\rho$  measurements as made by placing the display into an integrating sphere

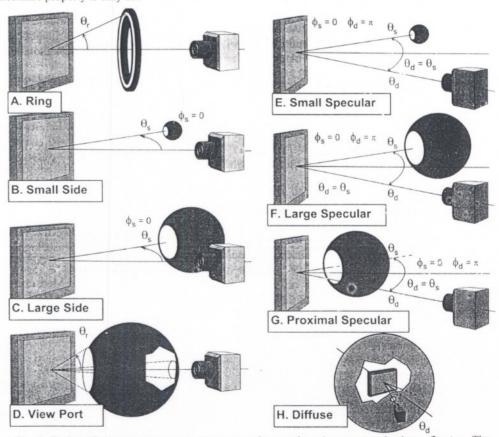


Fig. 1. Eight reflection measurement apparatus often used to characterize display reflection. The names refer to the placement and/or type of the source illumination.

source. Actually, in (4) we are making a luminance-factor  $\beta_{d/10}$  measurement using a diffuse source from some detector angle  $\theta_d = 10^\circ$  away from the normal, but this is the same as the reflectance  $\rho_{10/d}$  [1]. The Cartesian coordinate system used here is centered at the ideal position of the screen with the *y*-axis as up, the *z*-

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	Table 1. Some of the Parameters S	pecify	ring Reflection Measurement Apparatus
DETI	ECTOR PARAMETERS:		
$r_{\sf d}$	Distance of the center of the detector front surface (or lens) from the center (often $z_d$ when detector is on the optical axis)	α	Measurement field angle (the angle of the measured region from the viewpoint of the detector)
$\theta_d$	Inclination angle of detector from the z-axis	$R_{d}$	Radius of the entrance pupil of the detector
$\varphi_{\rm d}$	Rotation angle of the detector about the z-axis starting from the x-axis and going counter clockwise	κ <sub>d</sub>	Subtense of the entrance pupil of the detector or angular aperture: $tan(\kappa_d/2) = R_d/r_d$
F	The luminance meter is either focused on the source ( $F =$	S) o	r the display $(F = D)$ .
SOU	RCE PARAMETERS:		
$r_{\rm s}$	Distance of center of the source exit port from the center of coordinate system (often $z_s$ when the source is on the optical axis)	$\theta_{\rm r}$	Angle of ring light outer diameter from normal or angle of outer diameter edge of the exit port of a source positioned close to the display as measured from the normal: $\tan \theta_r = R_s / r_s$
$\theta_{s}$	Rotation angle of the source from the z-axis	$R_{\rm v}$	Radius of the view port (if so equipped)
фѕ	Rotation angle of the source about the z-axis starting from the x-axis and going counter clockwise	κ <sub>s</sub>	Subtense of source from the center: $tan(\kappa_s/2) = R_s/r_s$ , $\kappa_s = 2\theta_r$
$R_{\rm s}$	Radius of the source exit port (outer diameter of ring light source)	U	The average uniformity of the source luminance over the full extent of the exit port

axis along the display surface normal, and the x-axis in the horizontal plane to the right along the display surface. The display or sample surface is positioned within 0.5 mm of the ideal position and oriented within 0.1° of the ideal z-axis. Table 1 provides the list of parameters that specify the reflection apparatus.

In general, the uniformity  $U \equiv 1$  % for the large sources and any source used in a specular configuration. In configuration D a view-port box source is used. In the standard configuration, the view port is centered along the z-axis and serves as the hole through which the luminance measurements are made.

## 3. Analysis and Results

For the diffuse source configuration H, we employ two entirely different apparatus. One is a 2 m diameter integrating sphere at the center of which is placed the sample with an illuminance meter in the same plane as the sample and placed nearby the sample. For a display that has only a non-trivial haze component (SAEH in Table 3), the reflectance measures  $\rho_{d/\theta} = 0.0557$  with a standard deviation of less than 0.3% over the detector angle range from 6° to 20°-a very robust measurement. The second reflectance measurement is performed using a sampling sphere—a closed-cell polystyrene-foam hollow sphere-with a fiber-optic source and a photopic photodiode. The sample is placed upon the exit port. With nothing on the exit port, a photocurrent of  $J_k$  is obtained. A white reflectance standard ( $\rho_{std} = 0.99$ ) placed on the exit port gives a photocurrent  $J_{std}$ . With the sample in place we get photo-The reflectance of the sample  $\rho = \rho_{std}(J-J_k)/(J_{std}-J_k) = 0.0554$  with a standard deviation of less than 3 %. The large standard deviation arises because of the relatively soft exit port (plastic foam). A more rigid sphere would provide more precise results. The polystyrene integrating sphere is used to show that even with a fairly crude apparatus the results can be surprisingly good—less than a 1 % difference between using the crude plastic foam sphere and the large integrating sphere. Thus, the reflectance measurement using diffuse illumination is very robust.

For each of the other experiments or apparatus configurations, a small subset of parameters is selected for sensitivity testing and the rest are held fixed. For each experiment there are a set of k parameters  $p_i$ , i = 1, 2, ..., k (normally k = 3, 4, or 5), for which there are standard settings  $s_i$  that are changed to varied settings  $v_i$ . The varied settings are to simulate alignment and positioning

errors from the standard settings. Methods of experimental design are employed whereby full or fractional factorial designs are used with randomized blocks to provide an approximate model of the result y—which can be  $\beta$ ,  $\zeta$ ,  $\rho$ , or L—in terms of the parameters [4]. The result y is some unknown function of the parameters  $y = g(p_1, p_2, ..., p_k)$ . The value of y at the standard settings  $s_i$  is  $y_0 = g(s_1, s_2, ..., s_k)$  for any experiment (apparatus A, B, ..., G). We form the quantity  $f = y/y_0$ , which provides us a result relative to the standard settings. The sensitivities  $S_i$ , expressed in percent, are obtained from the experimental design results in terms of partial derivatives of f:

$$S_i = 100\% \frac{\partial f}{\partial p_i} \Big|_{S_i} \tag{1}$$

The units of these sensitivities are the inverse units of the parameter  $p_i$ . These sensitivities are tabulated for reasonable errors in apparatus set-up such as in per mm of positioning or per degree of misalignment or angular size. In the process of conducting these experiments it is found that the detector distance  $r_d$  has no important effect, as should be expected. The detector distance is  $r_d = 1$  m or more, and the detector's moderately small angular aperture is  $\kappa_d \cong 1^\circ$ . This is not to say that the detector acceptance area size cannot be important. it can be [3]. However, no provision is made to deliberately change the detector acceptance area size in these experiments.

In Table 2 we show the standard settings  $s_i$  and the varied settings  $v_i$  for all configurations expect for configuration H (diffuse source measurements, which is dealt with separately above). Thick-lined boxes highlight the variables that are changed. Table 3 shows the samples measured with a brief description of their reflection components and properties ("L" for Lambertian, "S" for specular, and "H" for haze; boldface indicates the dominant component; smaller font size indicates a lesser contribution). Table 4 shows the sensitivity results. (Relative reproducibility of the sensitivities of repeated experiments proved to be 0.1 %. We report a relative expanded uncertainty with a coverage factor of two of 3 % for these results based upon experience, equipment calibration, and linearity)

Space does not permit a full discussion of these results. The rows labeled "Measured" indicate what is measured in determining the sensitivity: either  $\beta$  (when illuminance is considered important),  $\zeta$  (when a specular configuration is used), or the luminance  $\mathit{L}$  (as for

						Table	2a. Setti	ngs for e	each con	figuratio	n.				
		A	A B-30			B-15		C		D		E-15		E'-15	
		Ring Light Source		Small Side Source at 30°		Small Side Source at 15°		Large Side Source at 30°		View-Port Box Source		Small Specular Source at 15°		Small Specula Source at 15°	
$p_i$	Unit	$S_i$	$v_i$	$s_i$	$v_i$	$s_i$	$\nu_i$	$s_i$	$\nu_i$	$s_i$	$v_i$	$S_i$	$v_i$	$s_i$	$\nu_i$
$r_{\rm s}$	mm	76.2	83.8	515.6	464.1	515.6	464.1	474.7	427.3	76.2	83.8	515.6	464.1	515.6	464.1
$\theta_{\rm s}$	0	0	1	30	32	15	17	30	32	0	1	15	17	15	17
$\theta_{\rm d}$	10	0	1	0	2	0	2	0	2	0	1	$=\theta_s$	$=\theta_{s}$	$=\theta_s$	$=\theta_{s}$
Œ	0	1.0	0.25	1.0		1.0		1.0		1.0	0.25	0.125	0.25	0.125	0.25
$R_{v}$	mm									31.8	44.5				
F		D		D		D		D		D		S		D	
$R_{\rm s}$	mm	48.9		4.5		4.5		62.5		76.2		9	8	9	8
Ks	0	40		1		1		15		90		1		1	

				T	able 2b.	Settings	for each	configur	ation, co	ontinued.				
		E'-	15	F-	15	F-30		F'-30		G-45/45		G-45/30		
		Small Sp Source a		Large Specular Source at 15°		Large Specular Source at 30°		Large Specular Source at 30°		Proximal Specular Source		Proximal Specular Source		
$p_i$	Unit	$s_i$	$v_i$	$s_i$	$v_i$	$s_i$	$v_i$	$s_i$	$v_i$	$s_i$	$v_i$	$s_i$	$v_i$	
$r_{\rm s}$	mm	515.6	464.1	474.7	427.3	474.7	427.3	474.7	427.3	80	65	80	70	
$\theta_{\text{s}}$	0	15	17	30	32	30	32	30	32	45	47	45	47	
$\theta_{\text{d}}$	0	$=\theta_{s}$	$=\theta_{s}$	30	32	30	32	30	32	45	47	30	32	
α	0	0.125	0.25	1		1		1		1		1		
F		D		D		D		S		D		D		
$R_{\rm s}$	mm	9	8	62.5		62.5		62.5		76.2		76.2		
Ks	0	1		15		15		15		?		?		

contrast measurements—often the luminance sensitivity is identical to that for  $\zeta$ ). The sensitivity indicated for the measurement field angle  $\alpha$  arises somewhat from calibration errors of  $\pm 0.1$ % between measurement field angle settings; so we might excuse between 0.5% and up to 1% for calibration errors, but no more than that amount. In general, it should be observed that whenever haze is present ("H" in the "Components" row) the results can show a remarkable sensitivity to small changes in the parameters. In the cases of either a small-specular-source or a small-side-source apparatus a strong sensitivity is observed. It may be that the requisite alignment will not permit these configuration to be employed except in laboratory settings whenever haze is an important factor in display reflection.

Of all the apparatus configurations, the ring light (A), the large specular source (F), and—as mentioned earlier—the diffuse apparatus (H) prove to be the least sensitive to geometrical variations and are therefore the most robust methods. Even in these more robust cases, except for the diffuse illumination (H), a reasonable effort still must be made to carefully set the apparatus geometry—often to within a fraction of a millimeter and a fraction of a degree—in order to achieve a 1 % reproducibility.

Assume that a sample exhibits all three components of reflection: Lambertian, haze, and specular. Reflection from the diffuse illumination apparatus (H) arises from all three reflection components in the most robust manner. Reflection from the ring light (A) arises from the far wings of the haze profile and any quasi-

		Table 3. Reflection Samples
Name	Compo- nents	Description
SAEH	Hц	Display used in automotive research having only a nontrivial haze component, Lambertian component is small. The display is off.
OCRT	SL	Sample, looks like an old CRT B&W monitor, no haze component, only Lambertian and specular.
FPD	sHı	Sample, from FPD manufacturer, used as front glass, strong haze, weak specular, small Lambertian.
CRT	SHL	Sample, resembles a modern color CRT with front-surface diffusion treatment (haze), weak specular, moderate Lambertian.
FPD2	HL	Tighter haze than FPD (gloss 70), no specular, strong haze, small Lambertian.

Lambertian behavior. Reflection from the large specular source (F) includes the specular reflection, the haze peak, and an integration over much of the significant part of the haze profile around the peak; reflection from the Lambertian component is reduced from that obtained from either the ring light or the diffuse illumination. Additionally, these three methods (ring, large specular, diffuse) integrate the reflection contributions from all rotation angles around the normal or specular direction—a single direction is not preferred.

Config	ration.	A: Ring	g Light	Source,	Focus	B: Small Side Source, Focus on Display									
Configuration:		on Disp	olay			B-30: Sou	rce at 30°	B-15: So	ource at	15°					
Sample:		SAEH	SAEH	OCRT	FPD	SAEH	SAEH	SAEH	SAEH	OCRT	OCRT	FPD	FPD	CRT	
Components:		HL	HL	SL	sHL	HL	HL	HL	HL	SL	SL	s <b>H</b> L	s <b>H</b> L	SHL	
Measured:		β	L	β	β	β	L	β	L	β	L	β	L	β	
Result for settings $s_i$ , $y_0$ :		0.0416		0.0381	1.62 ×10 <sup>-3</sup>	0.0177		0.101		0.0407		2.72 ×10 <sup>-3</sup>		0.0283	
$p_i$	Unit	$S_{i}$	$S_{i}$	$S_{i}$	$S_{i}$	$S_{i}$	$S_{i}$	$S_{i}$	$S_{i}$	$S_{i}$	$S_{\rm i}$	$S_{i}$	$S_{i}$	Si	
$r_{\rm s}$	mm	1.8%	-0.4%	0.1%	0.5%	0.0%	-0.4%	0.0%	-0.5%	0.0%	-0.4%	0.0%	-0.5%	0.0%	
$\theta_{\rm s}$	0	-0.7%	-0.8%	-0.3%	0.1%	-8.0%	-8.8%	-19.7%	-21.5%	-1.2%	-1.3%	-20.1%	-22.0%	-19.8%	
$\theta_d$	0	0.6%	0.7%	0.1%	-0.3%	6.9%	7.5%	20.1%	21.9%	-0.6%	-0.6%	20.2%	22.0%	19.7%	
α	0	-1.0%	-1.8%	-2.9%	-1.4%										

			Table 4b.	Sensitiv	ities to p	aramete	er variati	on (S <sub>i</sub> in	per uni	t), conti	nued.			
Configu	ration:		side Source,	1			E: Small Specular Source at 15°							
Comigai	· · · · · · · · · · · · · · · · · · ·	30°, Focus	: Display	Focus on Display			Focus o	n Source	e		Focus on Display			
Sample:		SAEH	OCRT	SAEH	FPD	OCRT	SAEH	OCRT	CRT	FPD	FPD2	SAEH	FPD	FPD2
Components:		HL	SL	HL	sHi.	SL	HL	SL	SHL	sHL	HL	HL	SHL	HL
Measured:		β	β	β	β	β	$\zeta, L$	$\zeta, L$	ζ, L	ζ, L	ζ, L	ζ, L	$\zeta, L$	ζ, L
Result for settings $s_i$ , $y_0$ :		0.0177	0.0404	0.0835	0.0184	0.0435	5.15 ×10 <sup>-4</sup>	0.0390	0.0148	2.72 ×10 <sup>-3</sup>	1.01 ×10 <sup>-3</sup>	4.70 ×10 <sup>-4</sup>	2.73 ×10 <sup>-3</sup>	1.04 ×10 <sup>-3</sup>
$p_i$	Unit	$S_{\rm i}$	$S_{i}$	$S_{i}$	$S_{i}$	$S_{i}$	$S_{i}$	$S_{i}$	$S_{i}$	$S_{i}$	$S_{i}$	$S_{i}$	$S_{i}$	$S_{i}$
rs	mm	0.0%	0.0%	1.3%	1.1%	0.0%	-0.3%	0.0%	-0.1%	-0.3%	-0.4%	-0.5%	-0.3%	-0.4%
$\theta_{s}$	0	-7.8%	-0.2%	-0.4%	0.5%	0.2%	-2.2%	0.1%	-0.1%	0.4%	1.0%	-2.8%	1.3%	0.9%
$\theta_d$	0	7.9%	-0.2%	0.4%	-4.4%	-0.1%	-	-	-	-	-	-	-	-
α	0			-1.6%	-1.0%	-0.2%	-39.1%	5.1%	-7.6%	-1.2%	-23.4%	-18.3%	-23.3%	-36.6%
$R_{\rm v}$ or $R_{\rm s}$	mm			1.3%	10.4%	-0.1%	22.8%	-0.3%	6.9%	16.6%	20.6%	22.3%	15.8%	20.9%

			Table	4c. Sen.	sitivities	to para	ameter va	riation (Si	in per ui	nit), con	tinued.				
	F: L	arge	Specular	Source	at, F	ocus on		G: Proximal Specular Source, Focus on Display							
Configuration	, ,	, , ,					Source	Source a	t 45°, De	Source at 45°, Detector at 30°					
Sample:	SA	AEH	H SAEH	OCRT	FPD	FPD2	SAEH	SAEH	SAEH	OCRT	OCRT	SAEH	SAEH		
Componen	ts: I	HL	HL	SL	SHL	HL	HL	HL	HL	SL	SL	HL	H1.		
Measured	: ζ	, L	$\zeta, L$	ζ, L	ζ, L	ζ, L	ζ, L	β	ζ, L	β	ζ, L	β	ζ, L		
Result for s tings $s_i$ , $y_0$	() (	0317	0.0344	0.0478	0.0434	0.0426	0.0345	0.2075	0.0627	0.247	0.0747	0.178	0.0551		
$p_i$ Un	it	$S_{i}$	$S_{i}$	$S_{i}$	$S_{i}$	$S_{i}$	$S_{i}$	$S_{i}$	$S_{i}$	$S_{i}$	$S_{i}$	$S_{i}$	$S_{i}$		
r <sub>s</sub> mr	n -0	.2%	-0.2%	0.0%	0.0%	0.0%	-0.2%	1.2%	0.0%	1.6%	-0.3%	1.8%	-0.1%		
$\theta_{s}$ °	-1	.0%	-1.0%	0.1%	-0.2%	-0.5%	-0.7%	1.7%	0.0%	1.4%	-0.4%	1.5%	-0.2%		
$\theta_d$ °	1.	.0%	1.0%	0.5%	0.8%	1.1%	1.6%	1.6%	1.8%	1.8%	1.9%	0.7%	0.8%		

## 4. References

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